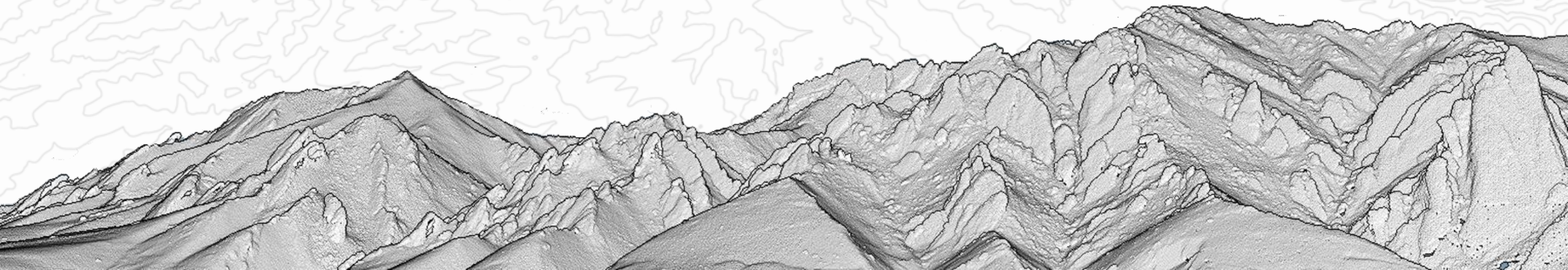


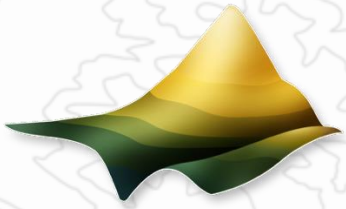
# Introduction to OpenTopography Tools for Calculating Change at the Earth's Surface

Cassandra Brigham (ASU)

Christopher J. Crosby (EarthScope)

*2025 NSF GAGE/SAGE Community Science Workshop | May 18<sup>th</sup>, 2025*





*Short course web page:*

*<https://opentopography.org/workshops/gage-sage-2025-OT-diff>*

## **Tentative Agenda:**

1:00 pm Welcome and course introduction. Around the room intros. (Brigham & Crosby)

1:30 pm Lecture & activity: Introduction to OpenTopography and short tour of the OT website. Get differencing jobs running via the OT-browser. (Crosby)

*2:15 pm Break*

2:30 pm Lecture: Differencing and error analysis in OpenTopography (Brigham)

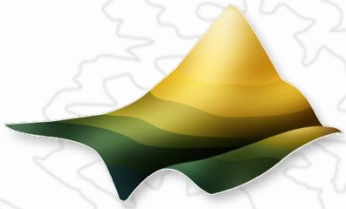
3:30 pm Discussion: Review participants' differencing results (Brigham & Crosby)

3:45 pm Activity: Colab differencing and error exercise. (Brigham)

*4:45 pm Discussion*

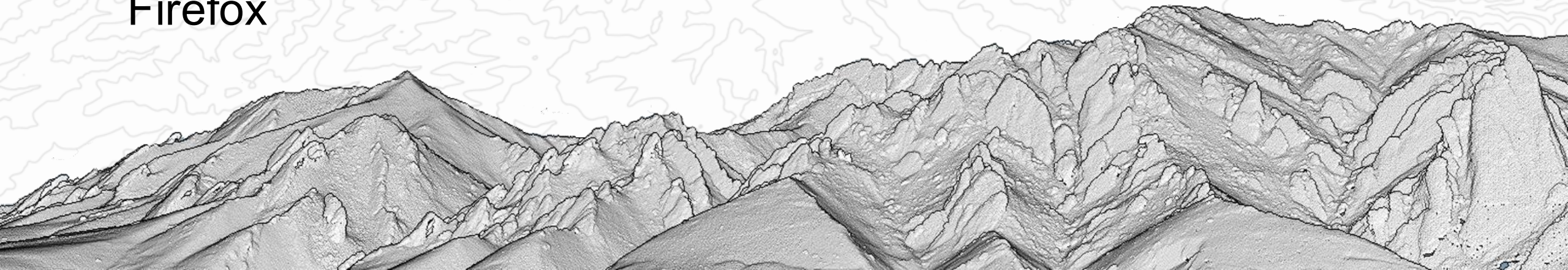
*5:00 pm Short Course End*



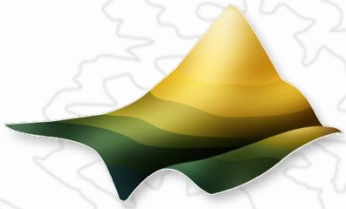


## LOGISTICS:

1. Ensure you have a Gmail account and at least 500 MB of Google Drive space
2. Create an OpenTopography account (if you do not already have one) at <https://portal.opentopography.org/newUser>
3. Bring a laptop capable of connecting to the conference WiFi network, ideally with a WebGL enabled browser like Chrome or Firefox

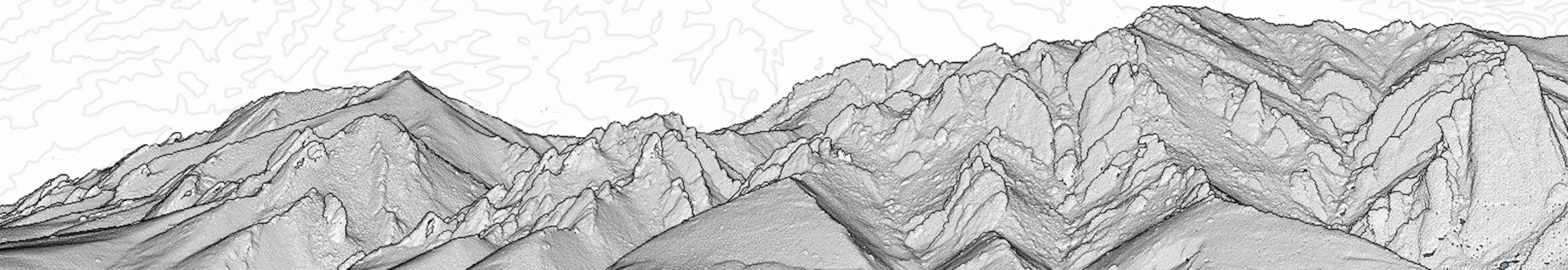




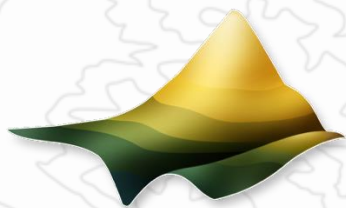


## INTRODUCTIONS:

1. Name & affiliation?
2. Your research area / application of high-resolution topography and topographic differencing?
3. Experience with lidar / topographic data and geospatial data analysis?



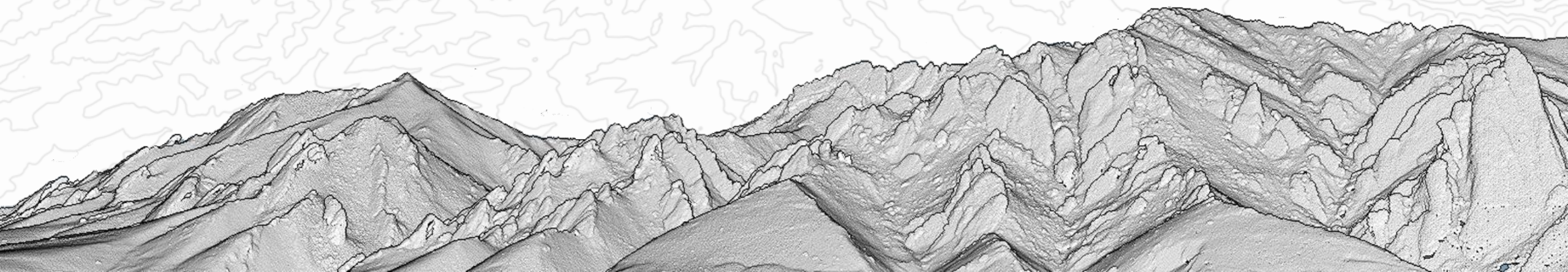




# Introduction to OpenTopography

**Christopher J. Crosby (EarthScope)**

*2025 NSF GAGE/SAGE Community Science Workshop | May 18<sup>th</sup>, 2025*



# What is OpenTopography?



*Democratize online access to high resolution topography*

Data access (lidar, photogrammetry, satellite) and derived data products

The screenshot shows the OpenTopography website homepage. At the top is a blue navigation bar with links for 'Getting Started', 'MyOpenTopo', and 'Premium Subscriptions', followed by a search bar labeled 'Search OpenTopography...'. Below this is the OpenTopography logo and a navigation menu with links for 'HOME', 'DATA', 'RESOURCES', 'LEARN', and 'ABOUT'. The main content area features a large, colorful 3D point cloud visualization of the Auckland skyline, with the Sky Tower highlighted in red. The URL 'https://opentopography.org/' is displayed in large white text on the right. At the bottom left, a caption reads: 'Profile through Auckland, NZ lidar point cloud data. Sky Tower at center left.'

Getting Started MyOpenTopo Premium Subscriptions Search OpenTopography...

**OpenTopography**  
High-Resolution Topography Data and Tools

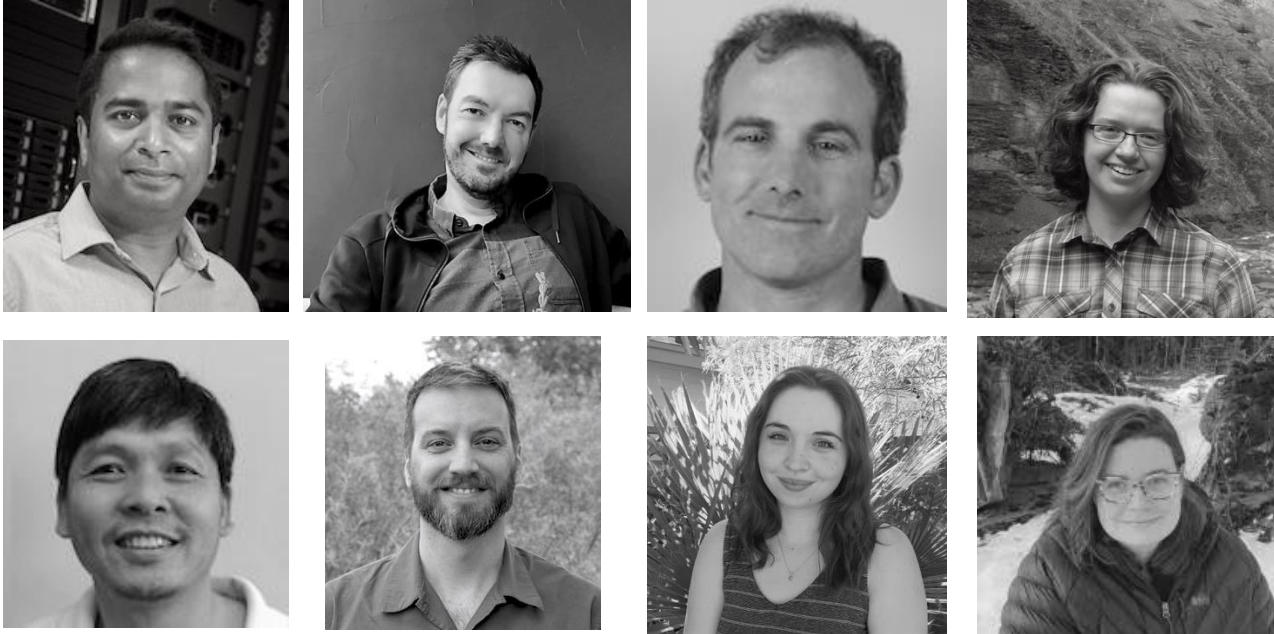
HOME DATA RESOURCES LEARN ABOUT

<https://opentopography.org/>

Profile through Auckland, NZ lidar point cloud data. Sky Tower at center left.



# Who We Are



Founded in 2009

Supported by US National Science Foundation (*EAR Award No. 2410799, 2410800 & 2410801*)



# What Do We Do?

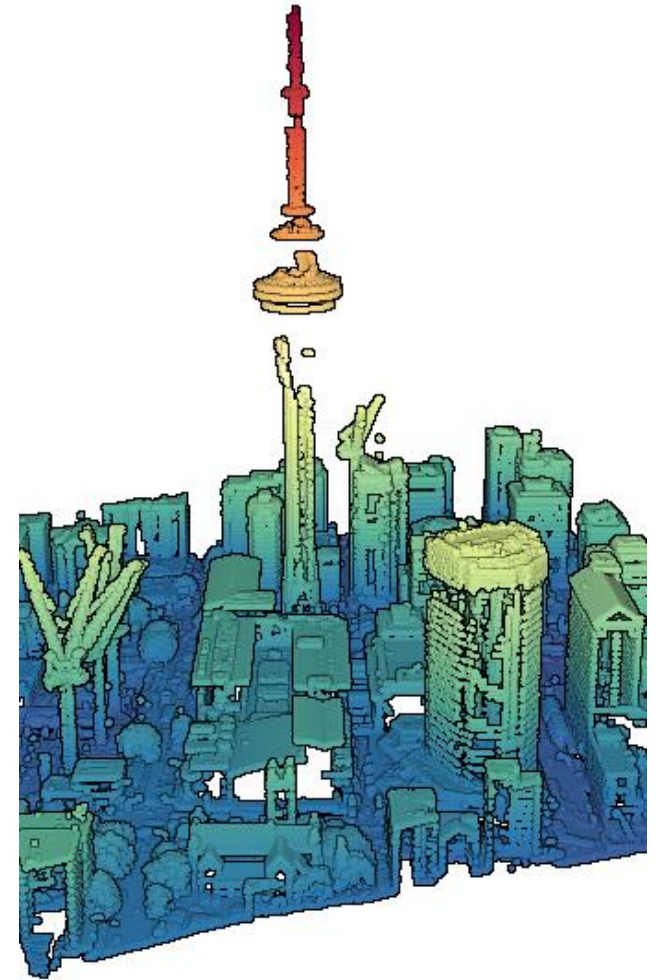


Topographic data hosting and distribution

On-demand derived data products and visualizations (DEMs, hillshade, slope, contours, etc.)

Portal, APIs, cloud native data, notebooks, open source code

Education and training in use of high-resolution topography

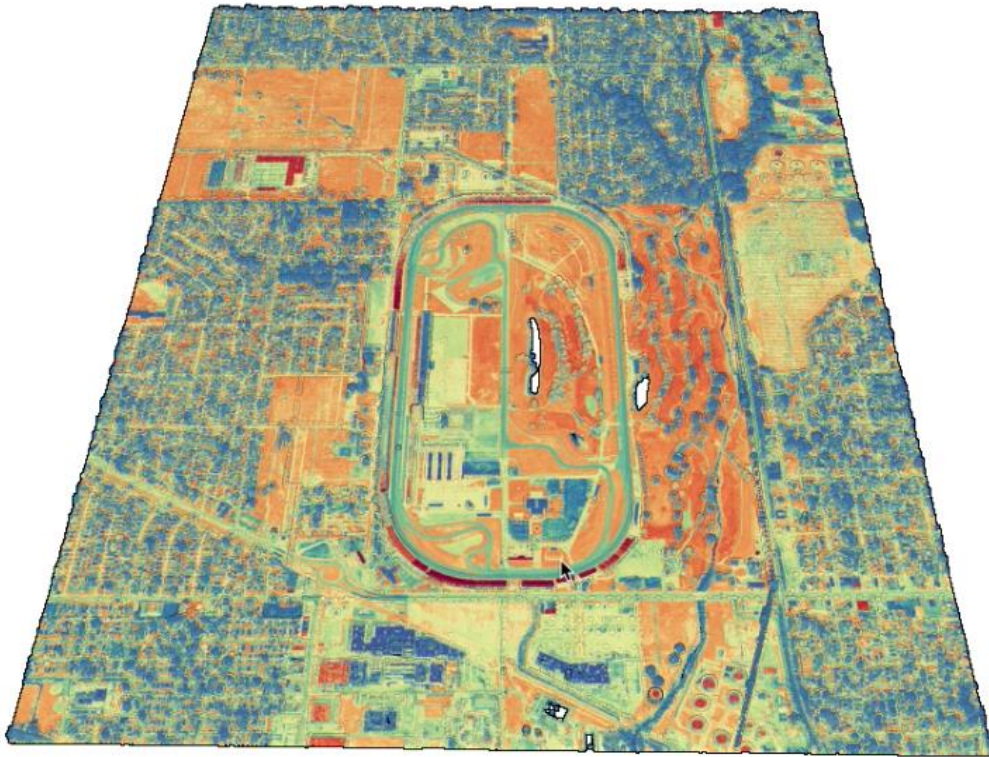




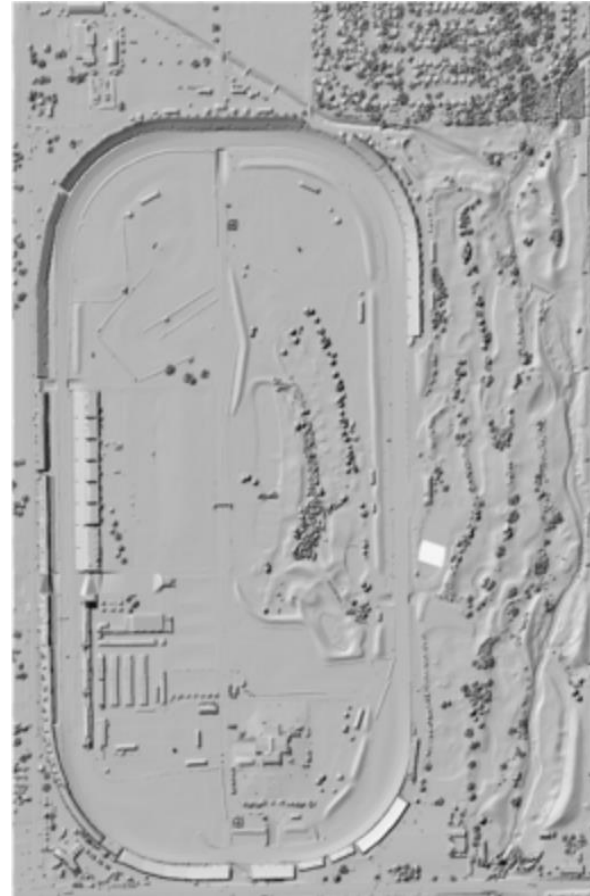
# Topographic Data & Derivatives



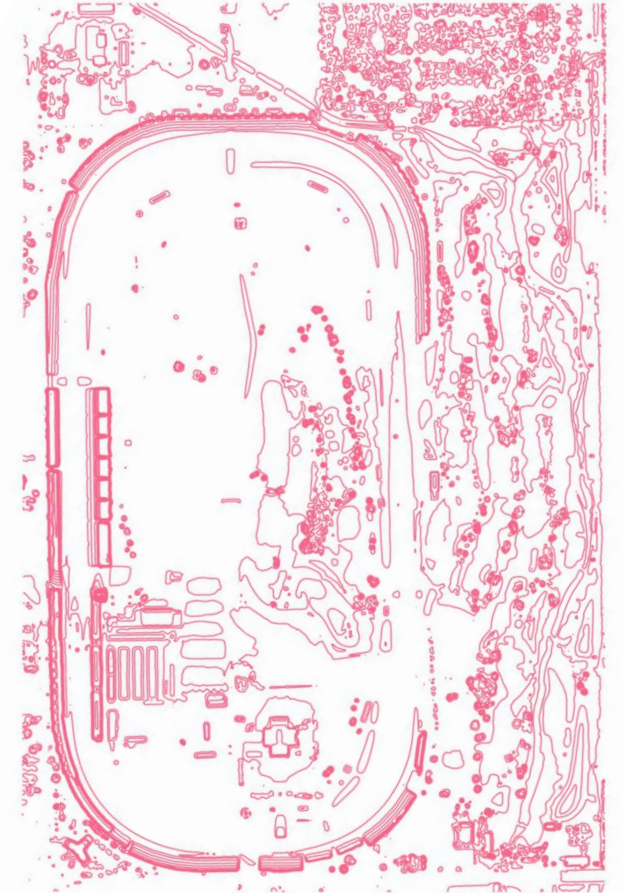
*Indianapolis Motor Speedway*



Point cloud



Raster: DEMs,  
hillshade, slope



Vector: Contours

# Data Services



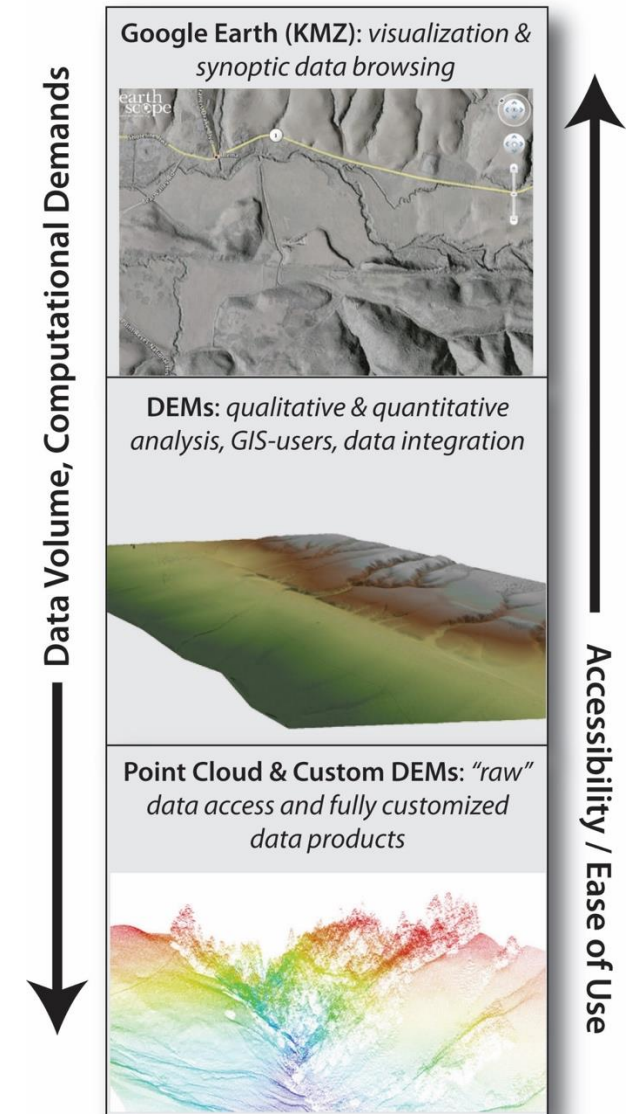
Topography data products and access mechanisms for a diverse user community

Range of available data products:

- Easy to access products for browsing and education
  - Browse images, Google Earth, 3D visualization
- Majority of users want a standard gridded product
  - GIS products (e.g. DTM, DSM)
- “Raw” point cloud data for modeling or analysis

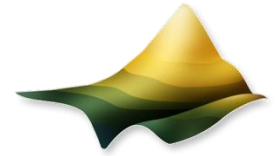
Multiple Access Pathways

- Web Portal interfaces, APIs and web services, Bulk Downloads (Cloud Optimized GeoTIFFs - COGs)





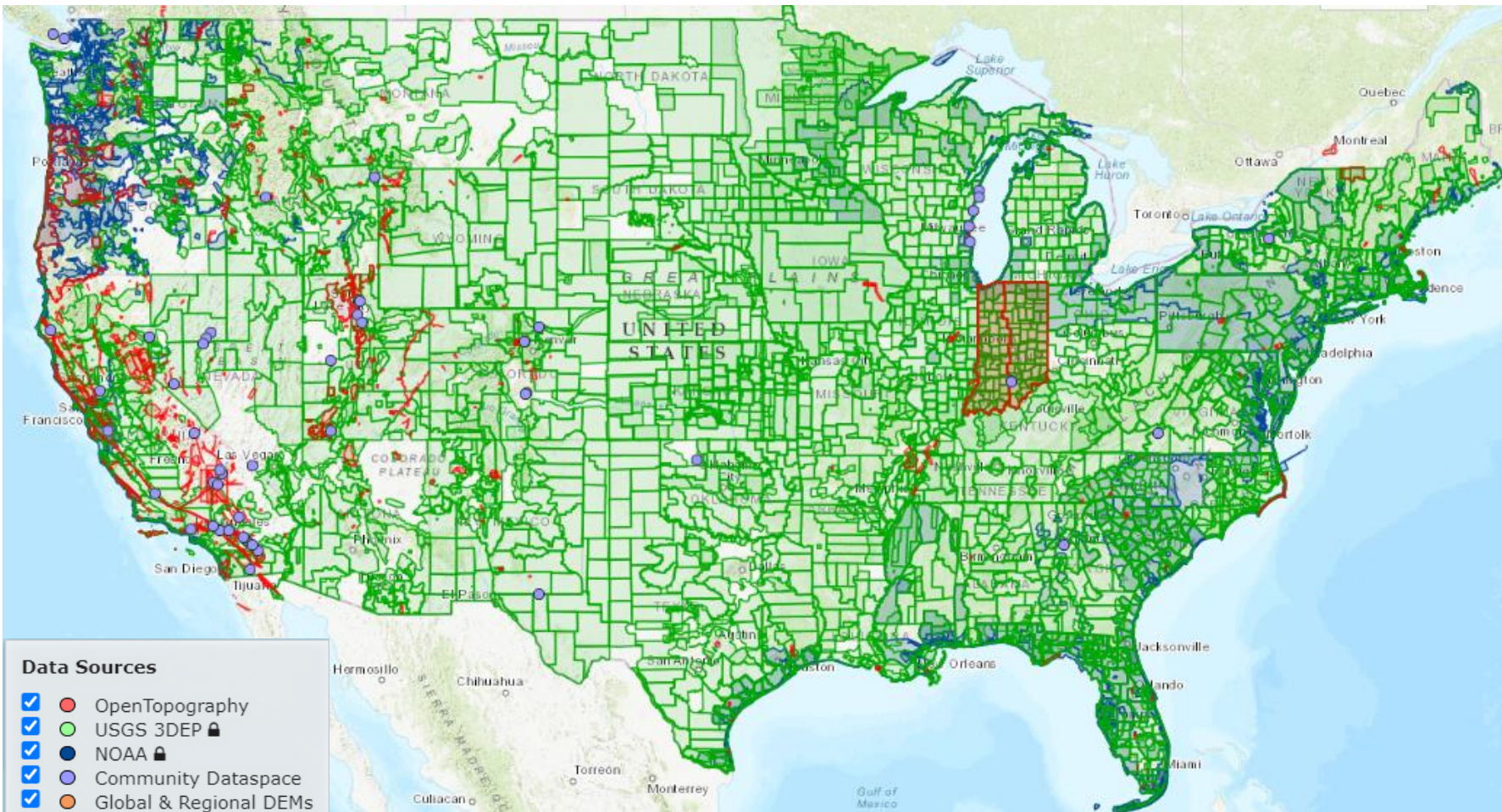
# The Data



85 trillion points from  
lidar & photogrammetry

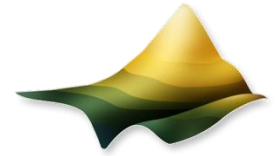
17 global & regional  
topographic datasets  
(e.g., SRTM, COP30,  
USGS 3DEP 10m)

Goal: Streamlined  
access without the  
need for specialized  
software or local  
compute resources





# New Zealand National Lidar Program



62 lidar point cloud datasets in OpenTopography covering 261,600 sq km (3.1 trillion points)

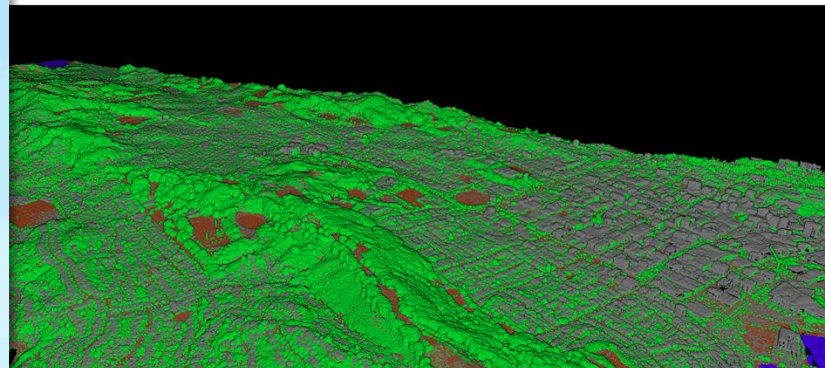


LINZ Data Service  
@LINZLDS



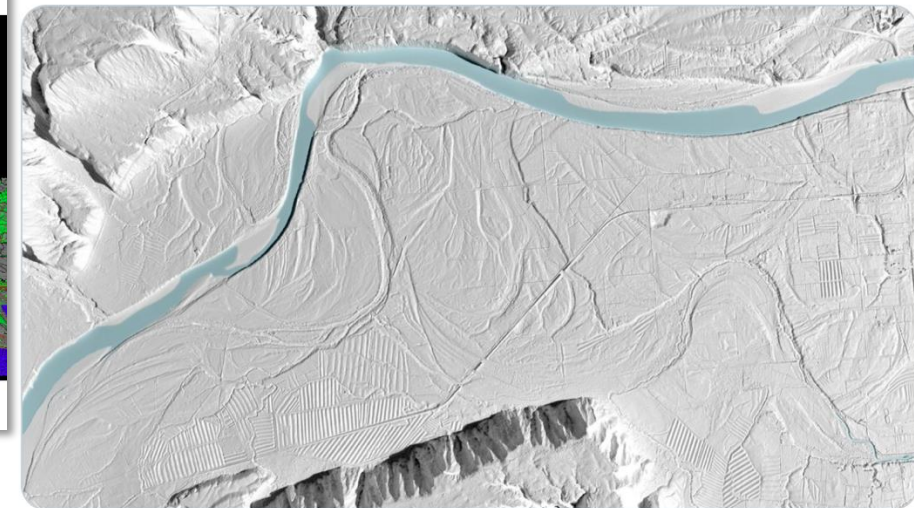
LINZ [Follow](#)  
We make sure NZ has accurate information about where people and places are, people have confidence in property rights and Crown property is well managed.  
Oct 16 · 5 min read

**Creating point cloud visualisations with OpenTopography**



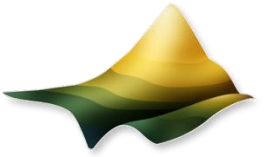
Stripping down point clouds to bare earth — Wellington, New Zealand

New **#LiDAR** available! DEM/DSM of Westport [data.linz.govt.nz/layer/105446](https://data.linz.govt.nz/layer/105446). Point clouds [@OpenTopography doi.org/10.5069/G9Z31W](https://doi.org/10.5069/G9Z31W).... Check out this image of the Buller River showing land features not easily seen in aerial imagery alone **#opendata**



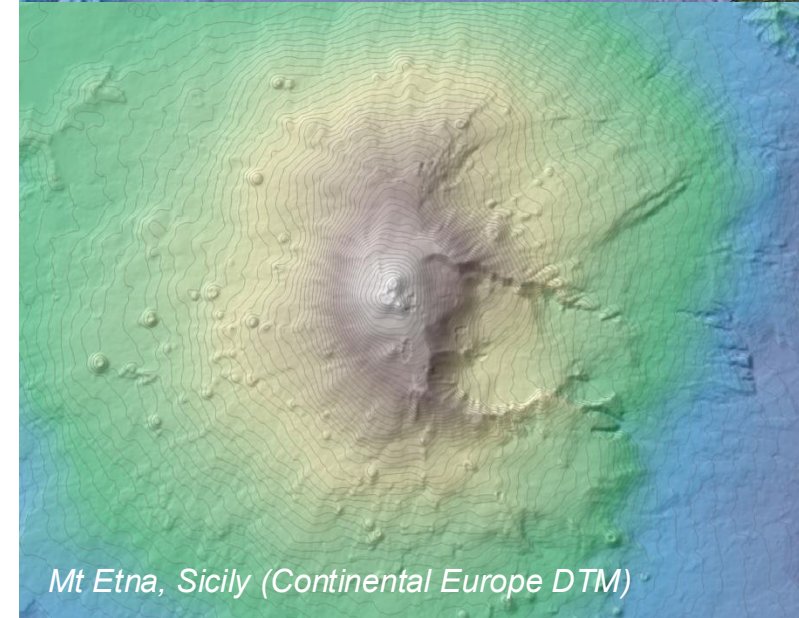
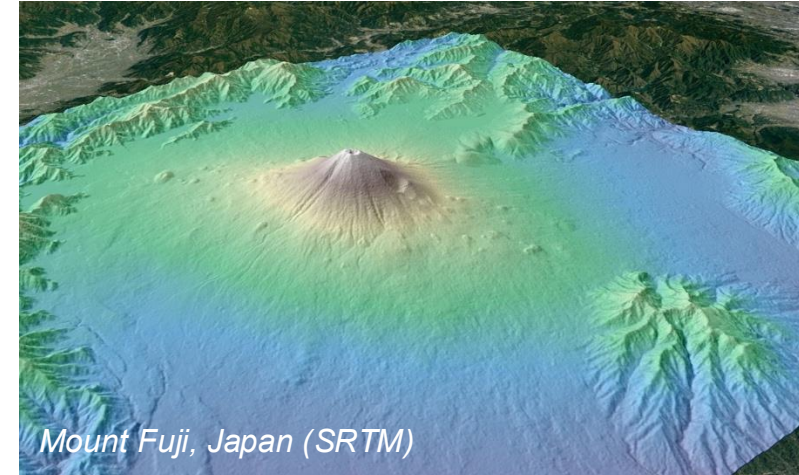
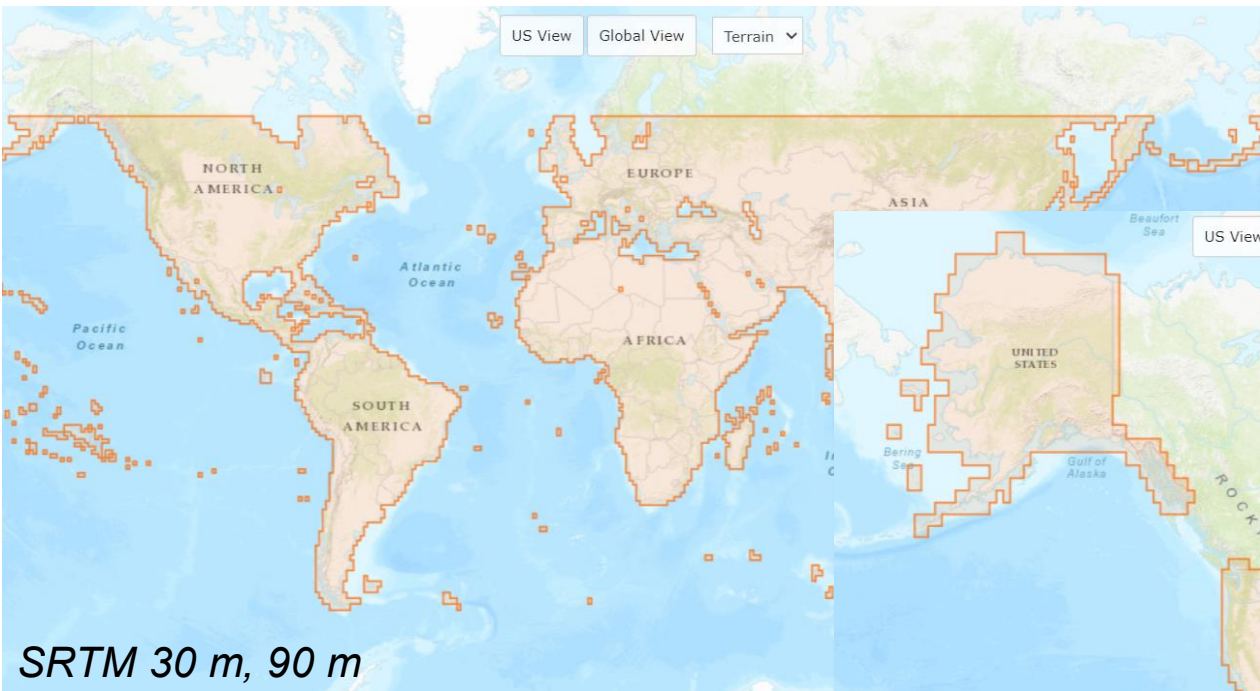


# Global & Regional Topography Data



SRTM, NASADEM, ALOS World 3D, Copernicus, GEDI L3, GEBCO, ArcticDEM, REMA, etc.

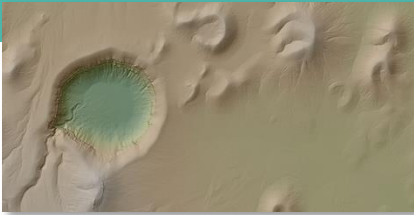
USGS 1m, 10m, 30m



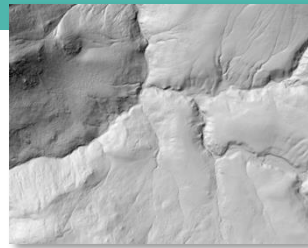
# Data Services



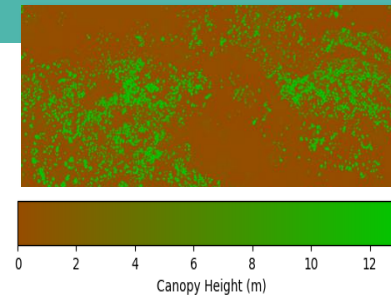
Digital Elevation Models  
TIN / Local Gridding



Topographic  
Hillshades



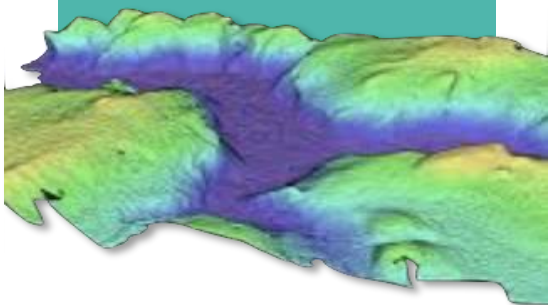
Canopy Height Model



Contour Lines



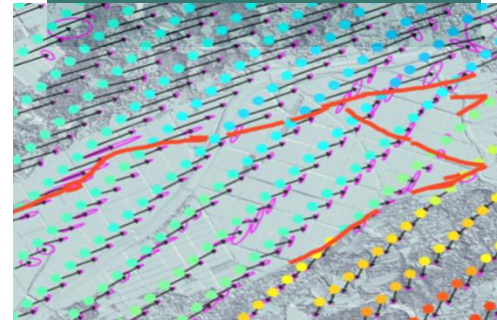
3D Visualization



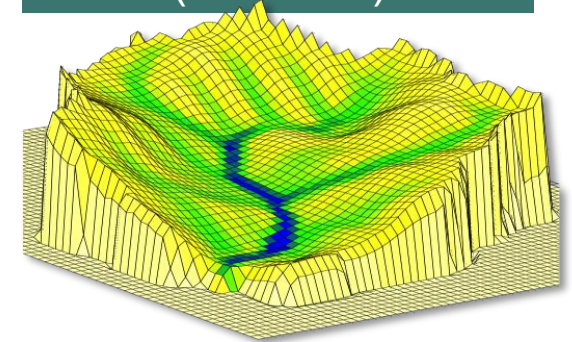
Vertical Differencing



3D Differencing

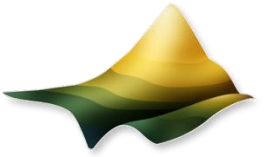


Hydrology Tools  
(TauDEM)

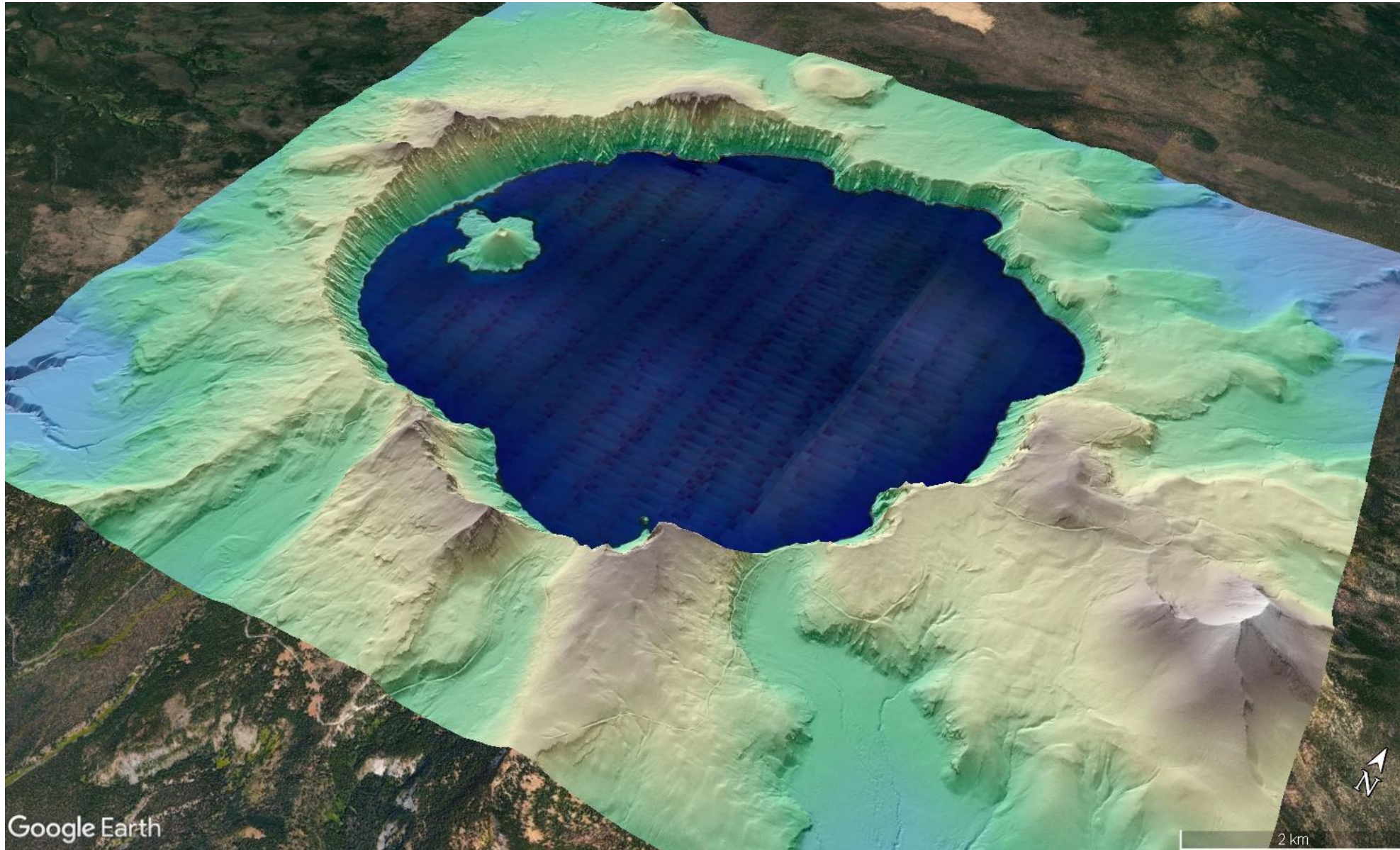




# Point Cloud Viewer



# Visualization Products





*Crater Lake  
colored DTM  
hillshade overlain  
on Google Earth  
imagery*











# Hydrologic Routing




## 7. Hydrologic Terrain Analysis Products (tauDEM)

  Hydrologically correct DEM with pits filled

  D-Infinity Flow Direction  
  D8 Flow Direction:

  D-Infinity Specific Catchment Area  
  D8 Contributing Area

  Topographic Wetness Index

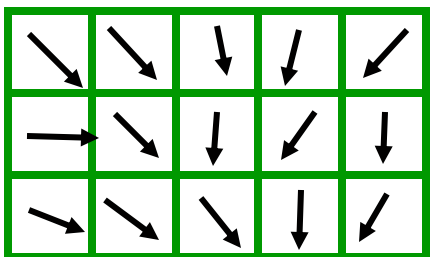
Raw DEM



Pit Removal (Filling)

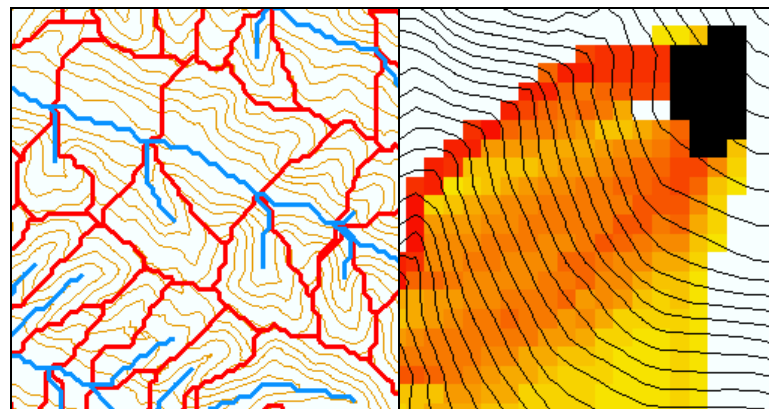


Flow Field



D8  
D-Infinity

Channels, Watersheds, Flow  
Related Terrain Information

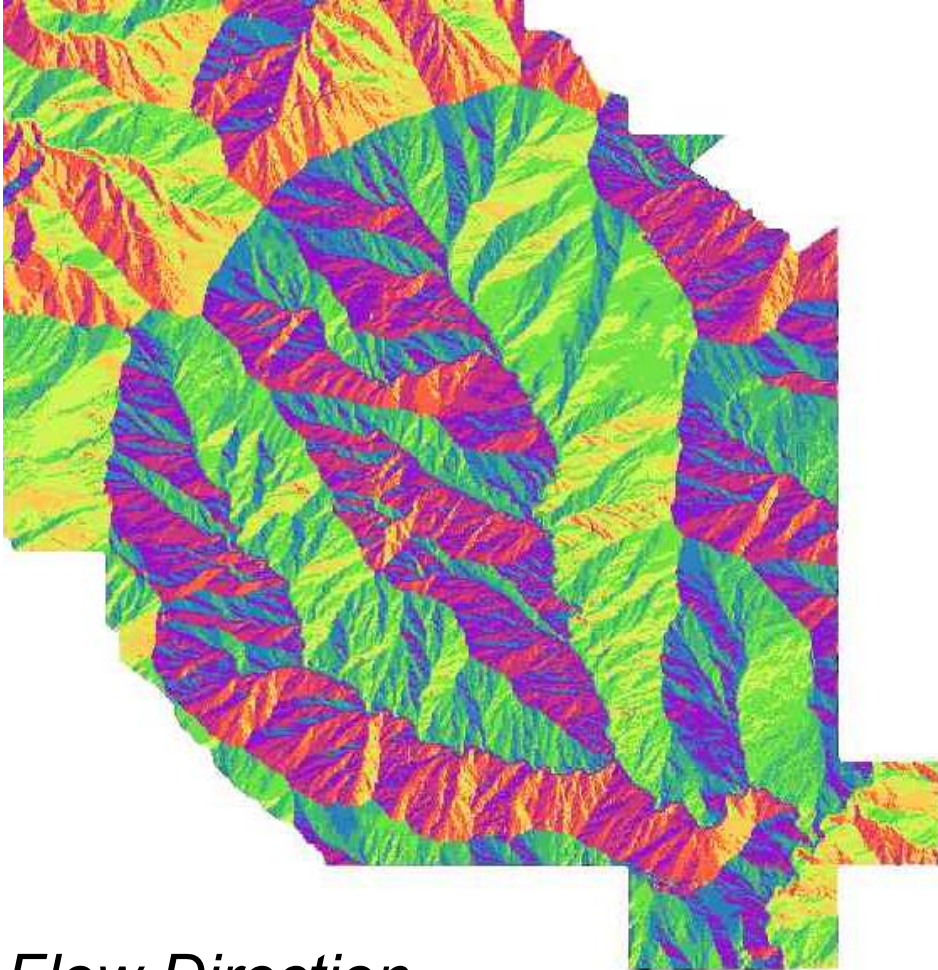


From David Tarboton, USU

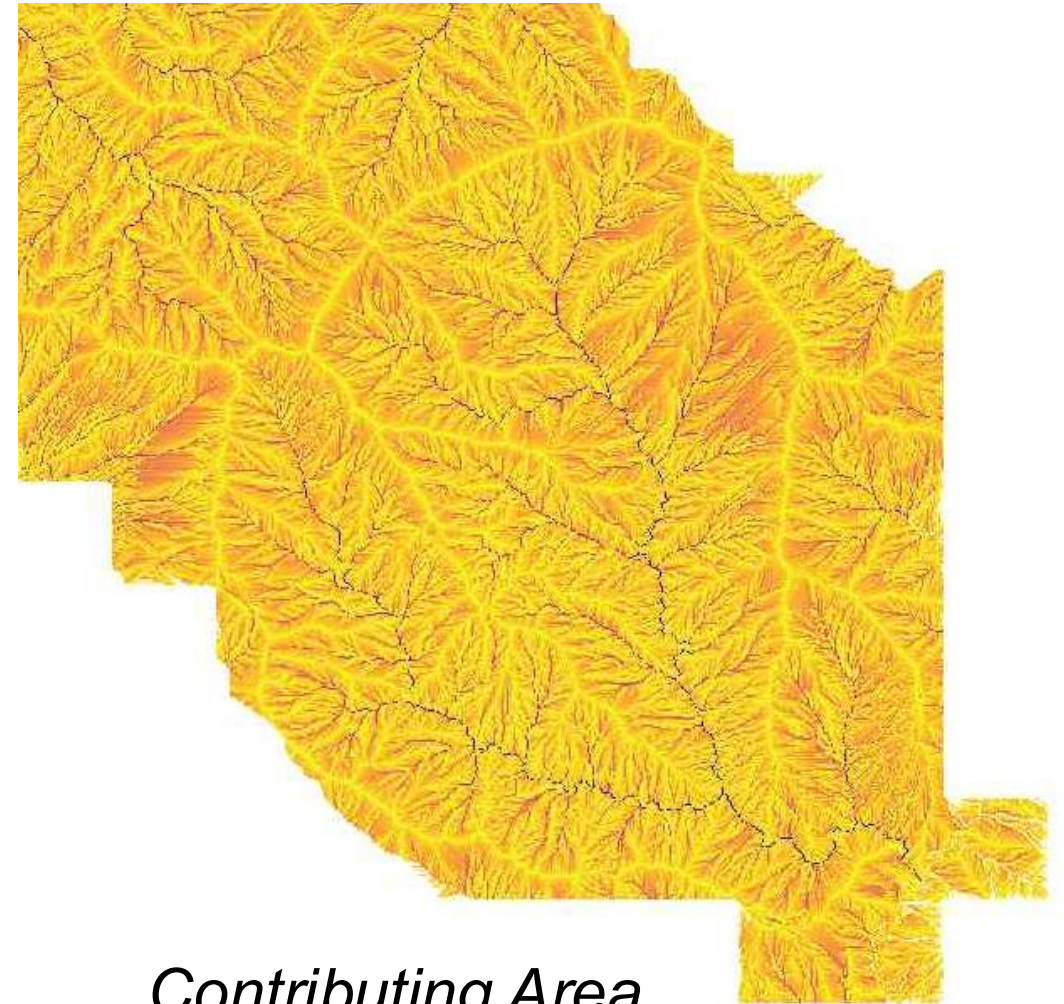
# Hydrologic Routing



## GIS Visualizations



*Flow Direction*



*Contributing Area*



# Topographic Differencing



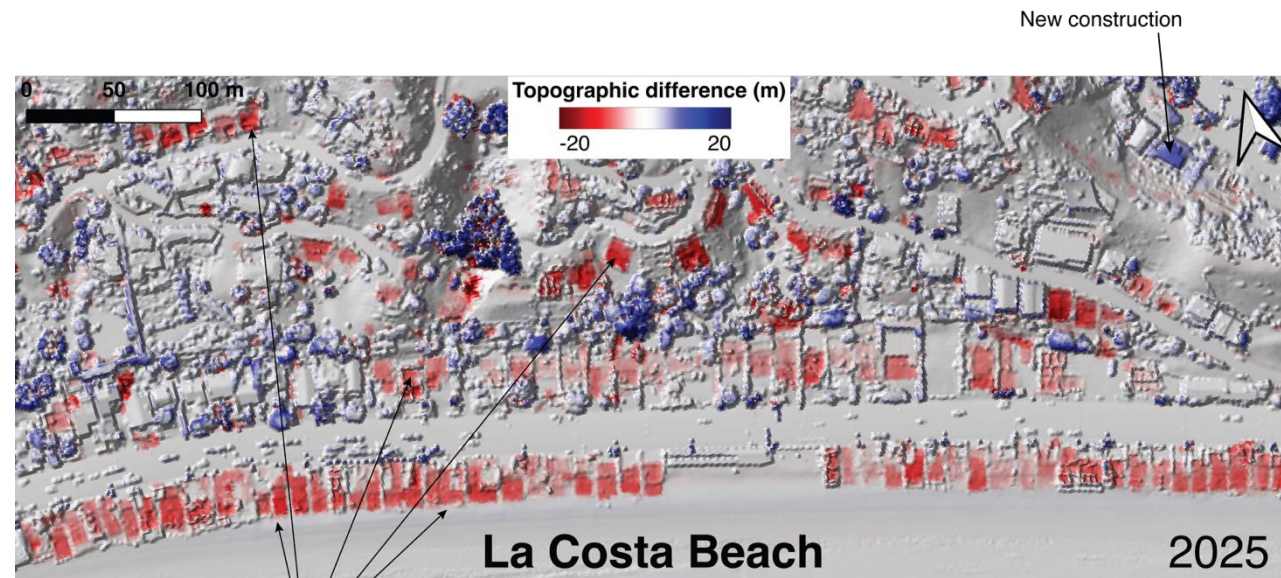
Multi-temporal data  
comparison / change detection

How do we best utilize the  
growing availability of multi-  
temporal topography?

Challenges:

- Methods
- Error assessment
- Data management

*LA County Wildfires, January 2025  
Palisades Fire*



*Post-fire lidar: NV5 & ALERT California*

# Topographic Differencing



OT High Resolution Topography [3]

USGS 3DEP [6]

NOAA [0]

Community Contributed [1]

Global & Regional DEM [10]

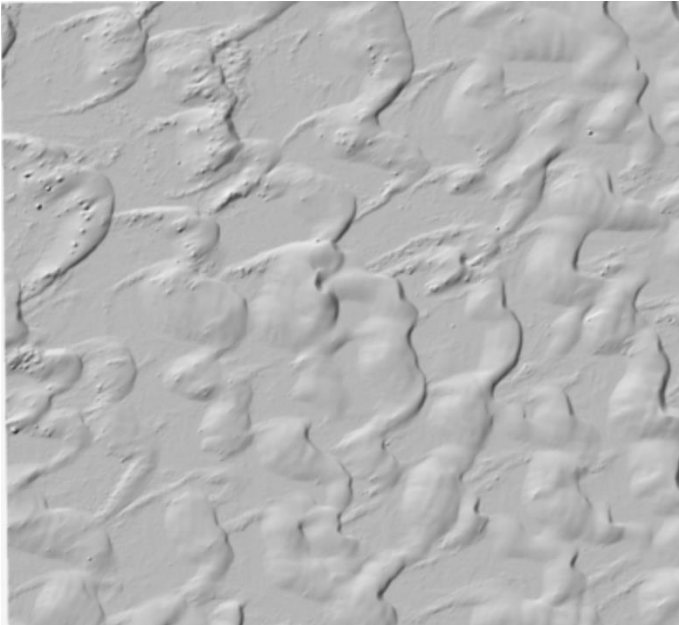


Datasets listed below are hosted by OpenTopography and are available in point cloud format for download and processing (e.g., creating custom DEMs). In some cases derived data products such as raster and Google Earth Image overlays are also available. Click the button to the right of the dataset name to access the available data products.

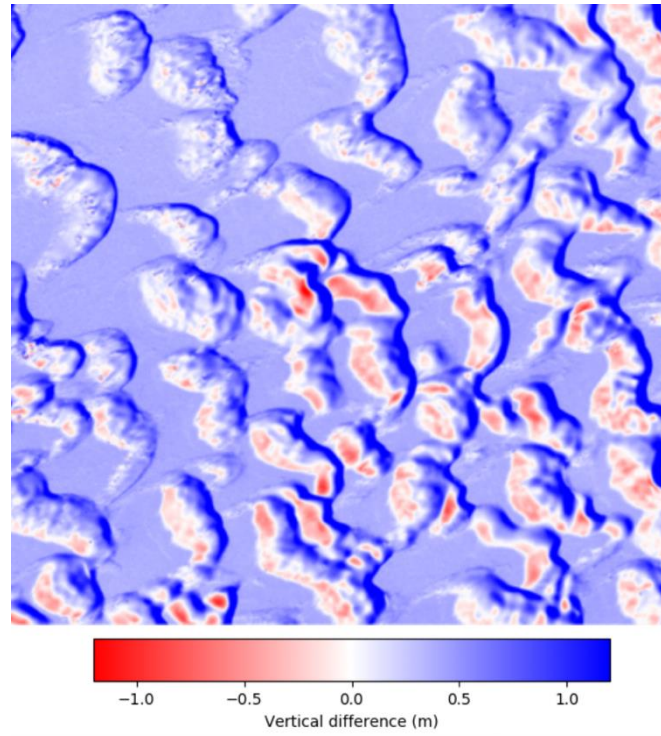
- 1 [White Sands National Monument, NM: LiDAR Survey of Dune Fields \(Sept 2009\)](#) [Open Data](#)
- 2 [White Sands National Monument, NM: LiDAR Survey of Dune Fields \(Jan 2009\)](#) [Open Data](#)
- 3 [White Sands National Monument, NM: LiDAR Survey of Dune Fields](#) [Open Data](#)

Differencing ⚙️  
Differencing ⚙️  
Differencing ⚙️

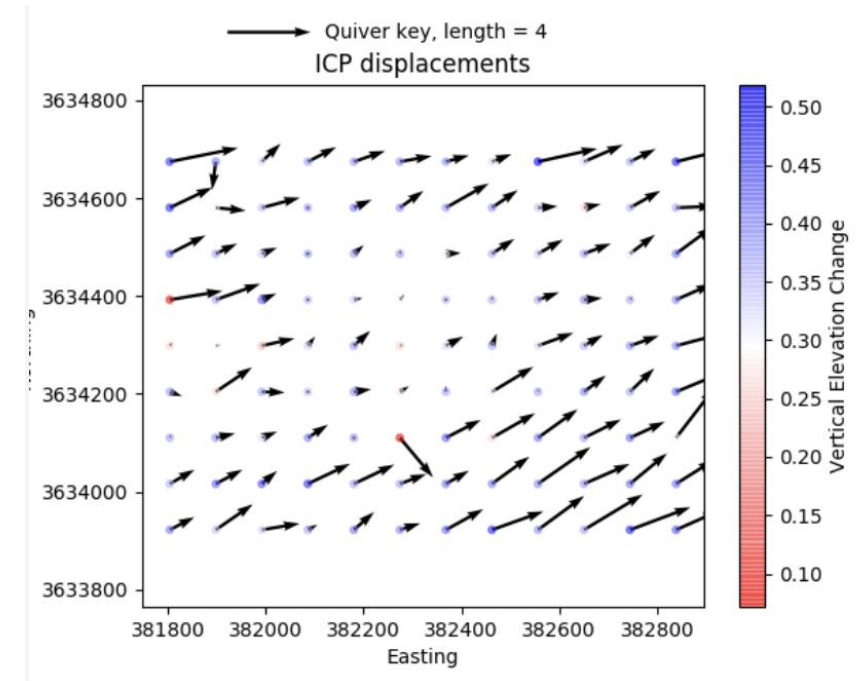
Point Cloud  
Point Cloud  
Point Cloud



Hillshade



Vertical differencing

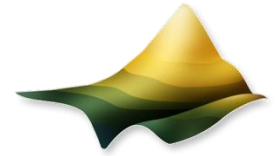


3D differencing

*Tools for on-demand comparison of datasets.  
Change in the vertical or in 3D.*



# OT Community & Impact



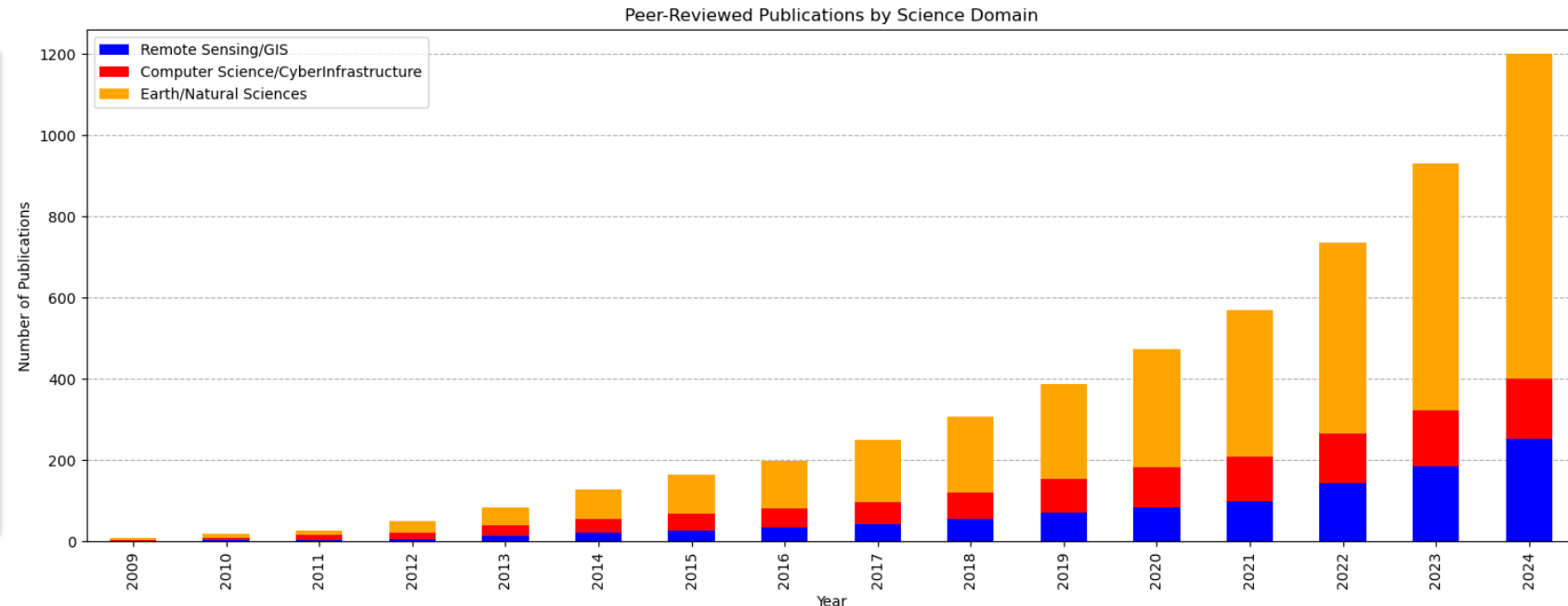
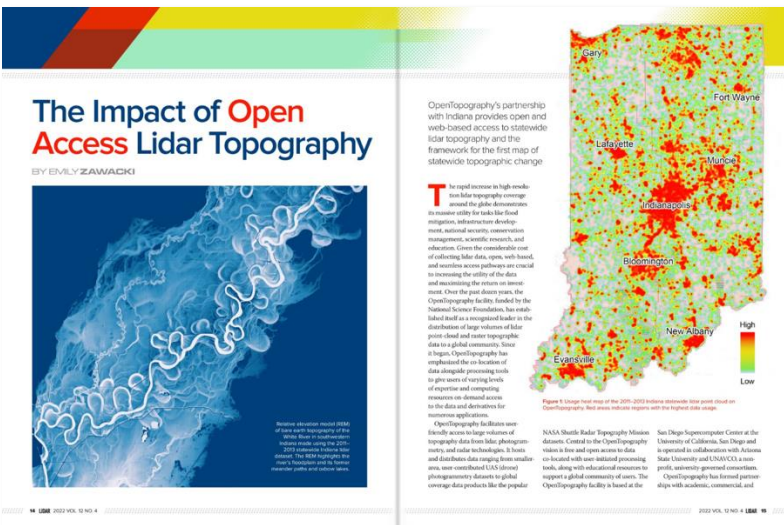
260k registered portal users (2.46M jobs)

141k API users (5.3M API calls)

67k OT mailing list subscribers

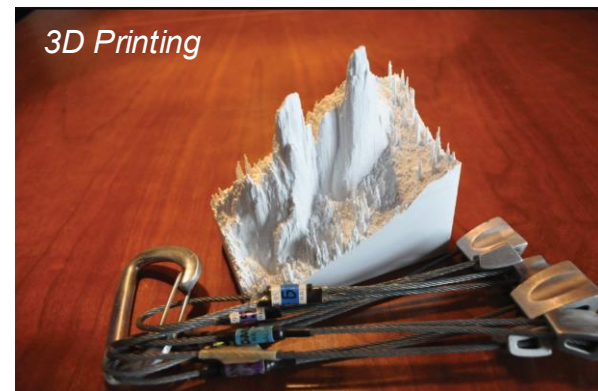
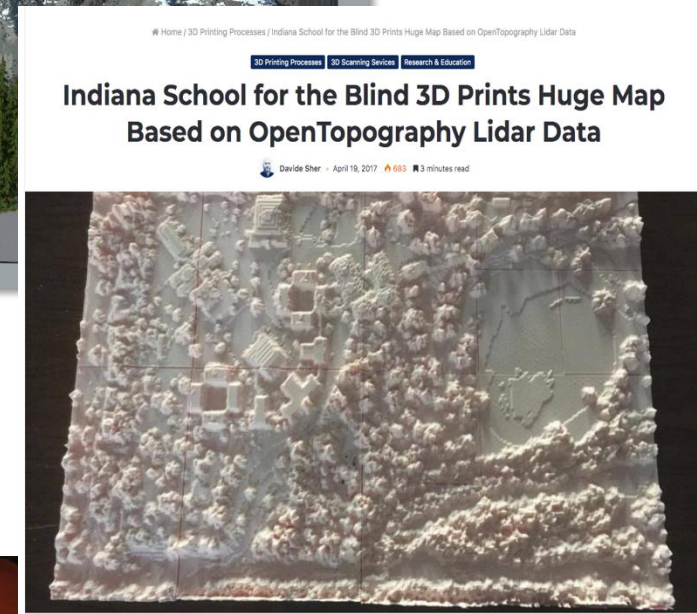
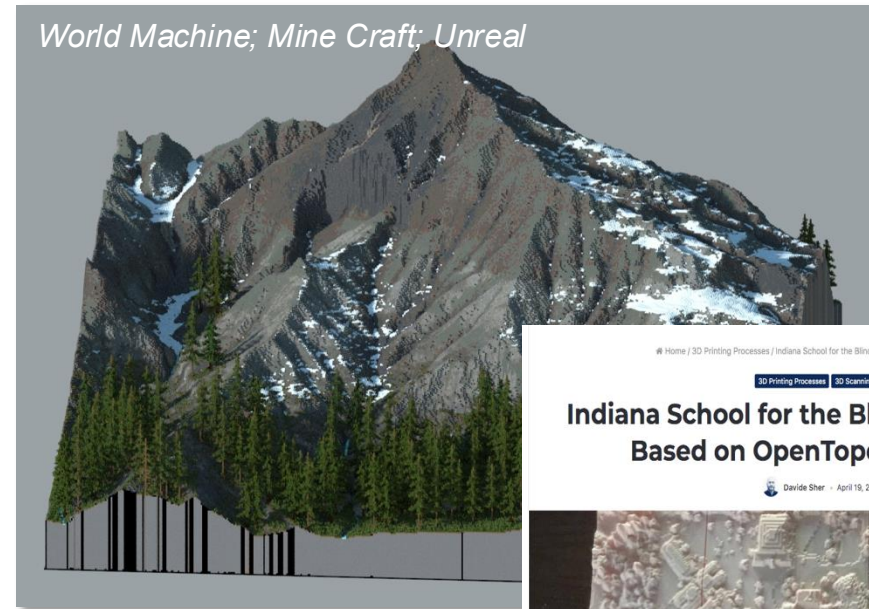
Since 2009, OT has enabled 1204 peer-reviewed publications

<https://opentopography.org/blog/ot-bibliography-2024-review-publications-using-opentopography>



# Diverse Use Cases

- “...developing a video game and want to experiment with landscapes”
- “...make maps for the family ranch”
- “...providing training and instruction to land surveyors and engineers”
- “...development of Emergency Action Plans”
- “...better understand avalanche conditions”
- “...generate fault hazard maps for the state of CA”
- “...I use these data sets both for teaching and for research”
- “...to create orienteering map contours”
- “...estimating forest canopy height and density”





# Education and Training



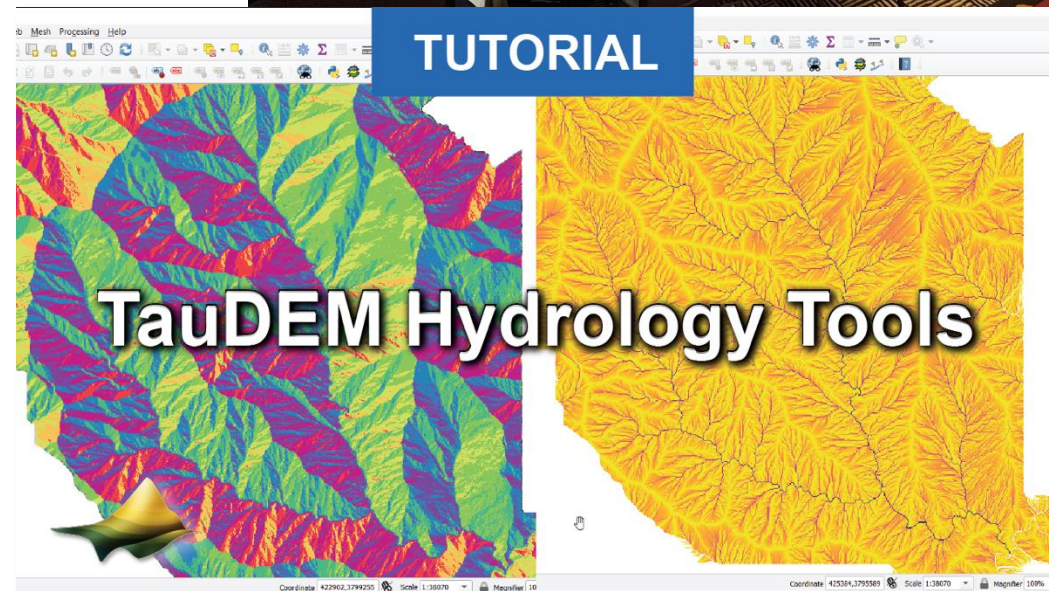
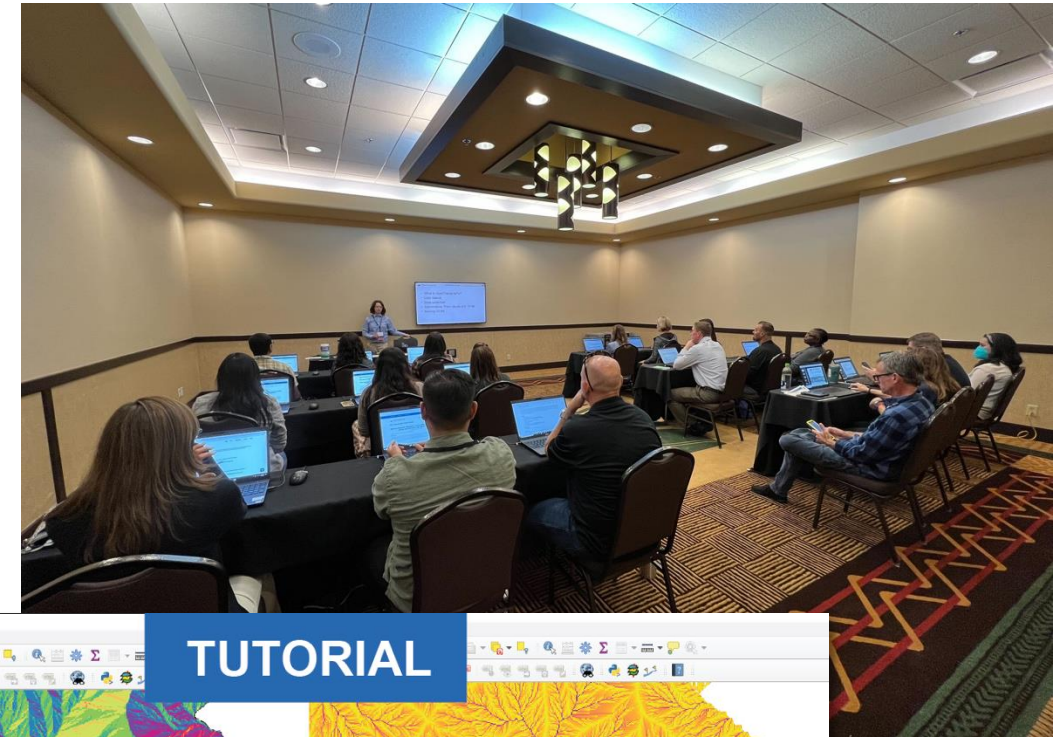
Short courses on lidar technology, data processing and analysis, applications

Video tutorials on OT YouTube channel

<https://www.youtube.com/user/OpenTopography>

Ready to use classroom activities

The screenshot shows the Teach the Earth website interface. At the top is a navigation bar with 'Themes', 'Key Resources', 'News & Events', and 'Community'. Below this is a search bar and a 'Go' button. The main content area features a sidebar on the left with links to 'Search the Portal', 'Review Processes', 'Exemplary Teaching Activities', 'Teaching Activities', 'Earth Education Project Sites', 'Community', 'News', 'Workshops, Webinars and Events', and 'About this Portal'. The main content area displays the 'Indiana River Meanders Mapping Exercise' by Emily Zawacki, Arizona State University at the Tempe Campus. A summary section describes the exercise, which involves using hillshade images from airborne lidar to map river meanders and oxbow lakes. A 'Keywords' section lists: river meander, oxbow lake, discharge, geomorphology, lidar. At the bottom, it indicates the activity is for 'Fluvial | College Lower (13-14)' and provides a link to 'Expand for more detail and links to related resources'.



# Jupyter Notebooks & Code



## OpenTopography Facility

Open access to high-resolution, Earth science-oriented topography data, and related tools & resources. US NSF supported.

Follow

125 followers

San Diego Supercomputer Center, ...

<http://www.opentopography.org>

[@opentopography.org](#)

[info@opentopography.org](mailto:info@opentopography.org)

### Popular repositories

#### RiverREM

Public

Forked from [klarrieu/RiverREM](#)

Make river relative elevation models (REM) and REM visualizations from an input digital elevation model (DEM).

Python 150 25

#### points2grid

Public

Points2Grid is a robust and scalable tool for gridding LIDAR point cloud data to generate Digital Elevation Models (DEM). Points2Grid uses a local gridding method to compute grid cell elevation usi...

C++ 88 36

#### OT\_3DEP\_Workflows

Public

Forked from [cmspeed/OT\\_3DEP\\_Workflows](#)

Jupyter Notebook-based workflows for programmatically accessing, processing, and visualizing 3D Elevation Program (3DEP) lidar data

Jupyter Notebook 77 17

#### OT\_BulkAccess\_COGs

Public

OpenTopography has recently converted its entire global dataset collection to COGs. This notebook example highlights the power of Cloud Optimized GeoTIFFs (COGs) and how they can be used to reduce ...

Jupyter Notebook 41 5

#### 3D\_Differencing

Public

3D differencing in OpenTopography - Author: Chelsea Scott [cpsscott1@asu.edu](mailto:cpsscott1@asu.edu)

Python 21 10

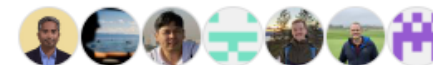
#### PointCloud\_to\_STL

Public

This notebook uses a Voxel subsampling method for point cloud data thinning. After the point cloud has been thinned, triangulation is computed to create a mesh which can be exported as a STL file a...

Jupyter Notebook 19 5

### People



Invite someone

### Top languages



# RiverREM



OpenTopography / RiverREMPublicforked from klarrieu/RiverREM

<> CodeIssuesPull requestsActionsProjectsSecurityInsights

main1 branch3 tagsGo to fileCode

This branch is up to date with klarrieu/RiverREM:main.

klarrieu Update README.mdc7427a0 on Aug 16, 2022105 commits

docs	accept url inputs, added test files, improve error/warning messages, ...	7 months ago
riverrem	accept url inputs, added test files, improve error/warning messages, ...	7 months ago
tests	fix test path	7 months ago
.gitignore	added pics, update gitignore	9 months ago
CITATION.cff	accept url inputs, added test files, improve error/warning messages, ...	7 months ago
LICENSE	GPLv3 license	8 months ago
README.md	Update README.md	7 months ago
bld.bat	fixed conda bld.bat typo	7 months ago
build.sh	cleaned up file structure, changed blend percent to 25	9 months ago
environment.yml	accept url inputs, added test files, improve error/warning messages, ...	7 months ago
meta.yaml	accept url inputs, added test files, improve error/warning messages, ...	7 months ago
setup.py	conda build config	7 months ago

README.md

NSF 1948997NSF 1948994NSF 1948857

conda | conda-forge v1.0.4downloads 1.7k

## RiverREM

RiverREM is a Python package for automatically generating river relative elevation model (REM) visualizations from nothing but an input digital elevation model (DEM). The package uses the OpenStreetMap API to retrieve river centerline geometries over the DEM extent. Interpolation of river elevations is automatically handled using a sampling scheme based on raster resolution and river sinuosity to create striking high-resolution visualizations without interpolation artefacts straight out of the box and without additional manual steps. The package also contains a helper class for creating DEM raster visualizations. See the [documentation](#) pages for more details.

For more information on REMs and this project see [this OpenTopography blog post](#).

About

Make river relative elevation models (REM) and REM visualizations from an input digital elevation model (DEM).

[opentopography.org/blog/new-packag...](#)

visualizationdigital-elevation-modellidar

ReadmeGPL-3.0 licenseCite this repository87 stars7 watching12 forks

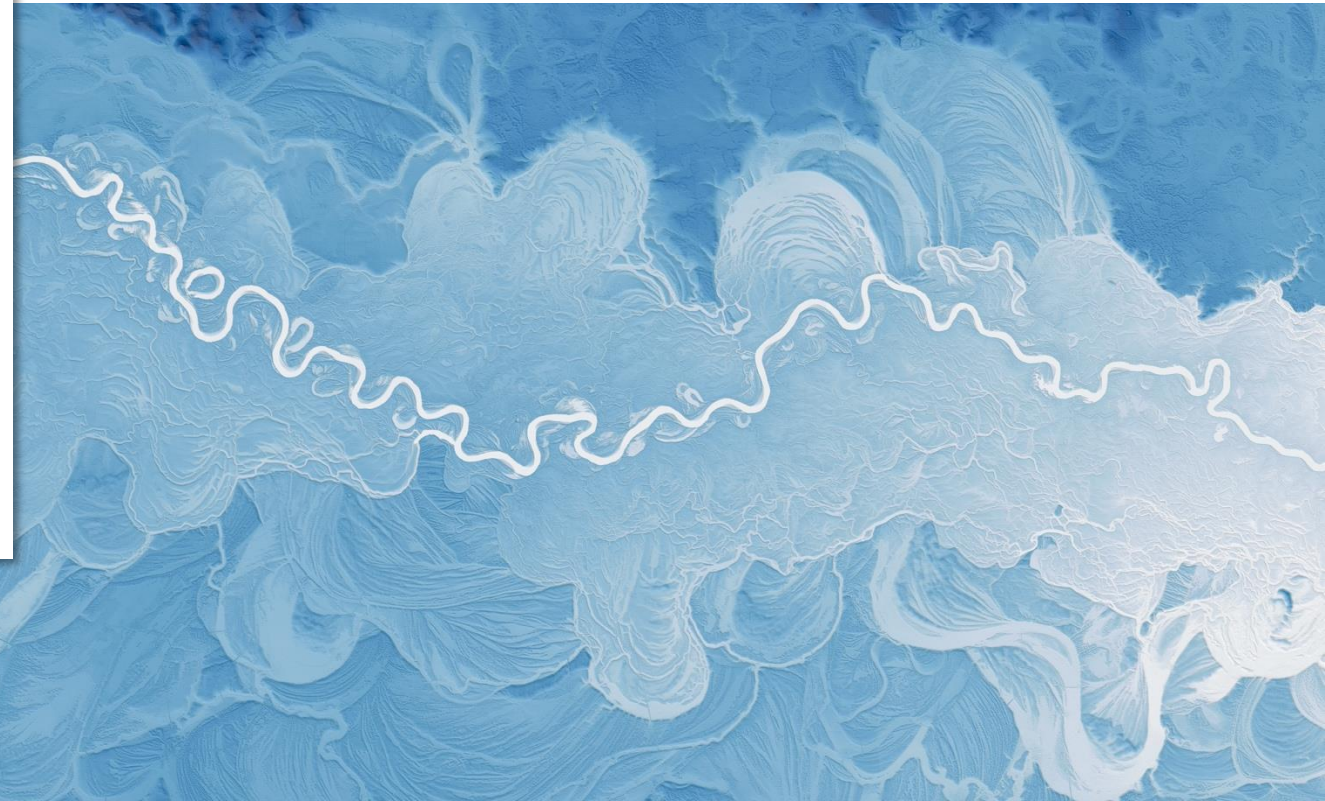
Releases3v1.0.4Lateston Aug 13, 2022+ 2 releases

PackagesNo packages published

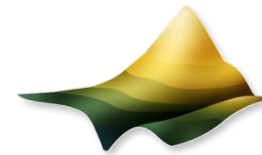
LanguagesPython 99.9%Other 0.1%

Python package for the automated generation of relative elevation models (REMs) in fluvial environments.

Open source package built by OT intern Kenny Larrieu summer 2022.



# Topography for 3D Printable Models

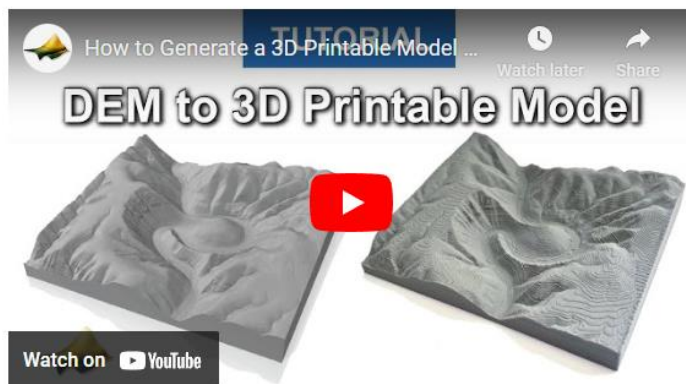


HOME DATA ▾ RESOURCES ▾ LEARN ▾ ABOUT ▾

## 3D Printing Digital Elevation Models

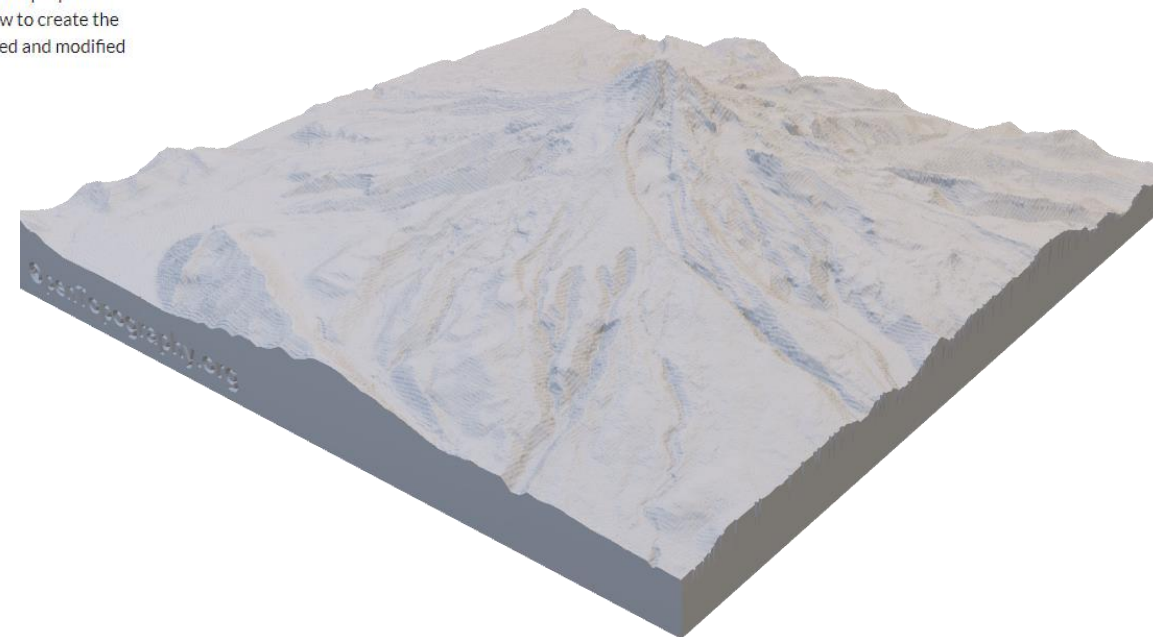
Have you ever wanted to make a 3D print of your favorite mountain peak, city-scape, or tourist destination? OpenTopography's video tutorial demonstrates how to prepare a digital elevation model (DEM) for 3D printing. Each software package in the tutorial is freely available for download. In the tutorial, we describe step-by-step how to create the standard triangle language (STL) file that is commonly used in 3D printing. We use the DEMto3D plugin in QGIS to generate the STL file, which can then be viewed and modified using the 3D Builder software. You can find a number of pre-made STL files for 3D printing on our [OpenLandform Catalog](#).

This YouTube video tutorial explains how to create a 3D printable model from a DEM downloaded from OpenTopography:



### 3D Printing Terrain Workflow

You can find [topography data](#) via OpenTopography's portal to download high resolution digital elevation models (DEMs). 3D prints can be made using a digital terrain model (DTM), which depicts just the bare Earth surface, or a digital surface model (DSM), which depicts vegetation, buildings, and other structures at Earth's surface. DTMs are preferable when printing topographic landforms, and DSMs are preferable when printing urban environments.

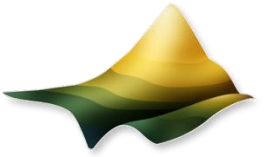


*Mount Hood 3D Model*

[https://opentopography.org/learn/3D\\_printing](https://opentopography.org/learn/3D_printing)



# Conclusions

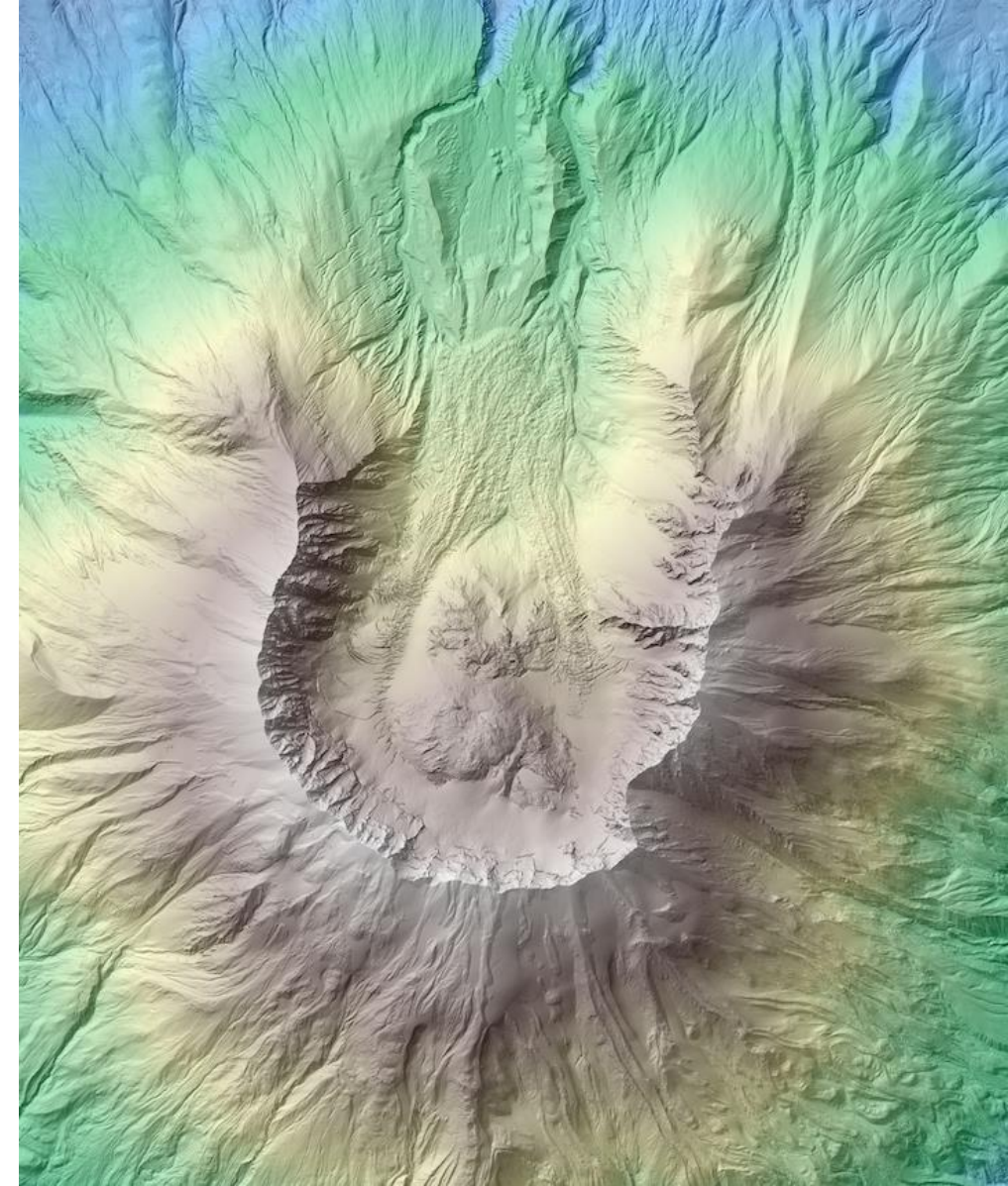


OT provides easy access to high resolution and global/regional topographic data and derived products

Most comprehensive source of topographic data on the internet

Education and training resources for self-paced learning

State and national-scale datasets present massive opportunities for advanced processing and analysis







White River, IN



# OpenTopography



## Thank you!

[www.opentopography.org](http://www.opentopography.org)

**Contact:** [info@opentopography.org](mailto:info@opentopography.org)

**Socials:** [@OpenTopography](https://twitter.com/OpenTopography)

**SDSC**



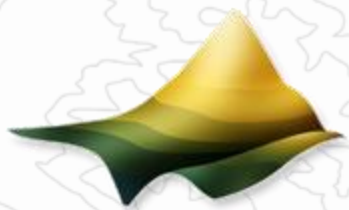
**EarthScope**  
Consortium







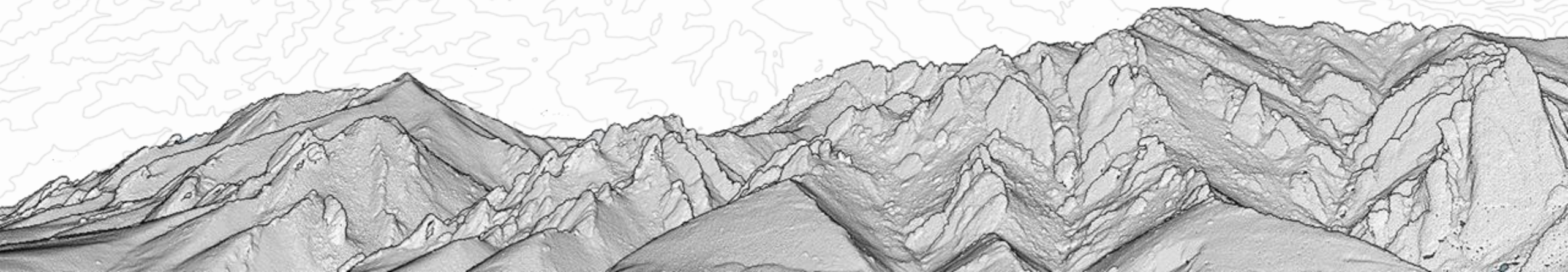
# Demo: OpenTopography data discovery and access



# Introduction to OpenTopography Tools for Calculating Change at the Earth's Surface

**Cassandra Brigham & Christopher Crosby**

*2025 NSF GAGE/SAGE Community Science Workshop*

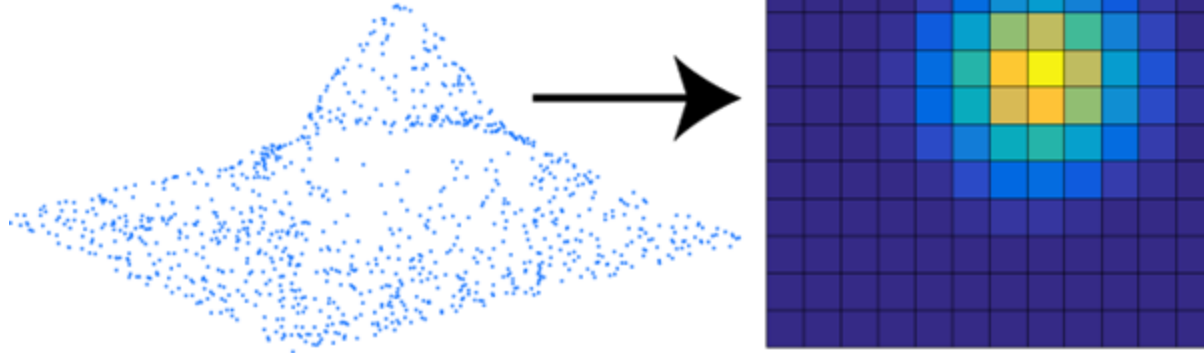




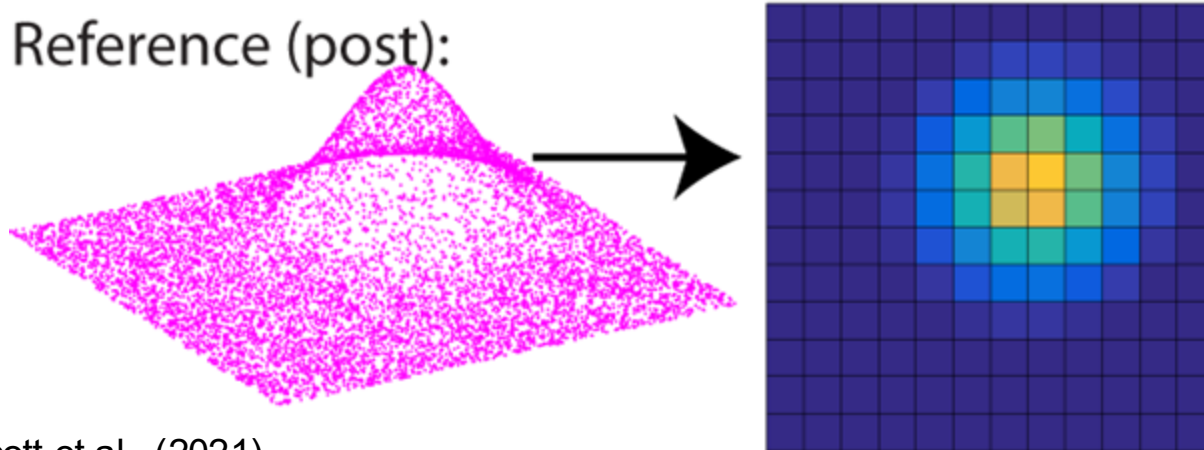
# Vertical Topographic Differencing



Compare (pre):



Reference (post):



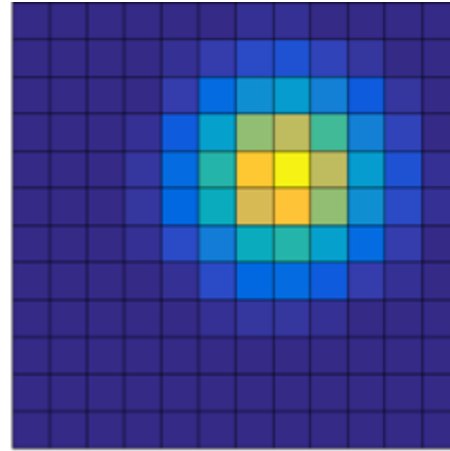
Scott et al., (2021)

Identical grid for pre and post event topography

# Vertical Topographic Differencing



Compare (pre):

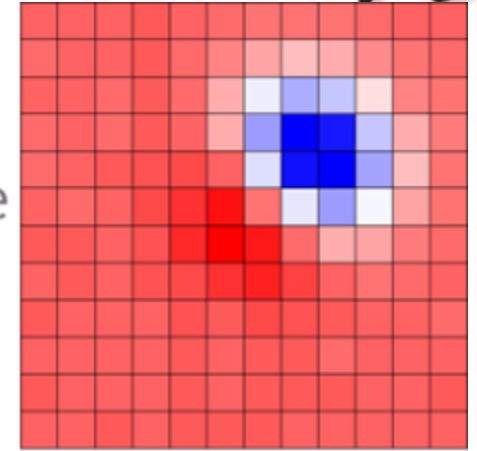


Subtraction:

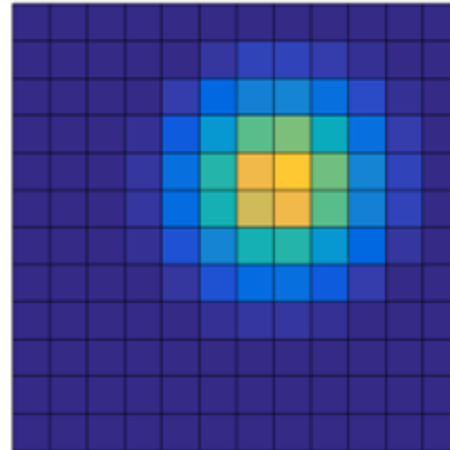
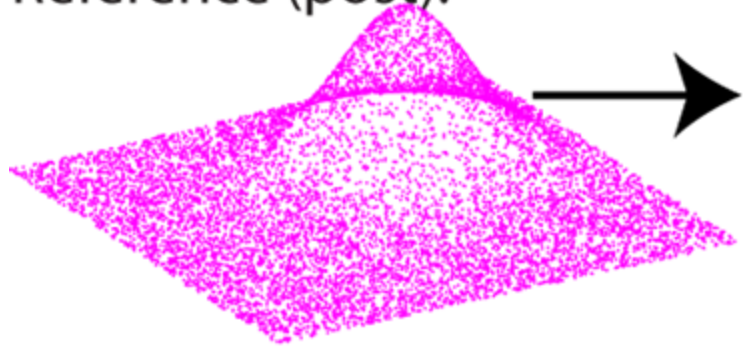
Difference

= Reference-Compare

Red Down Blue Up



Reference (post):

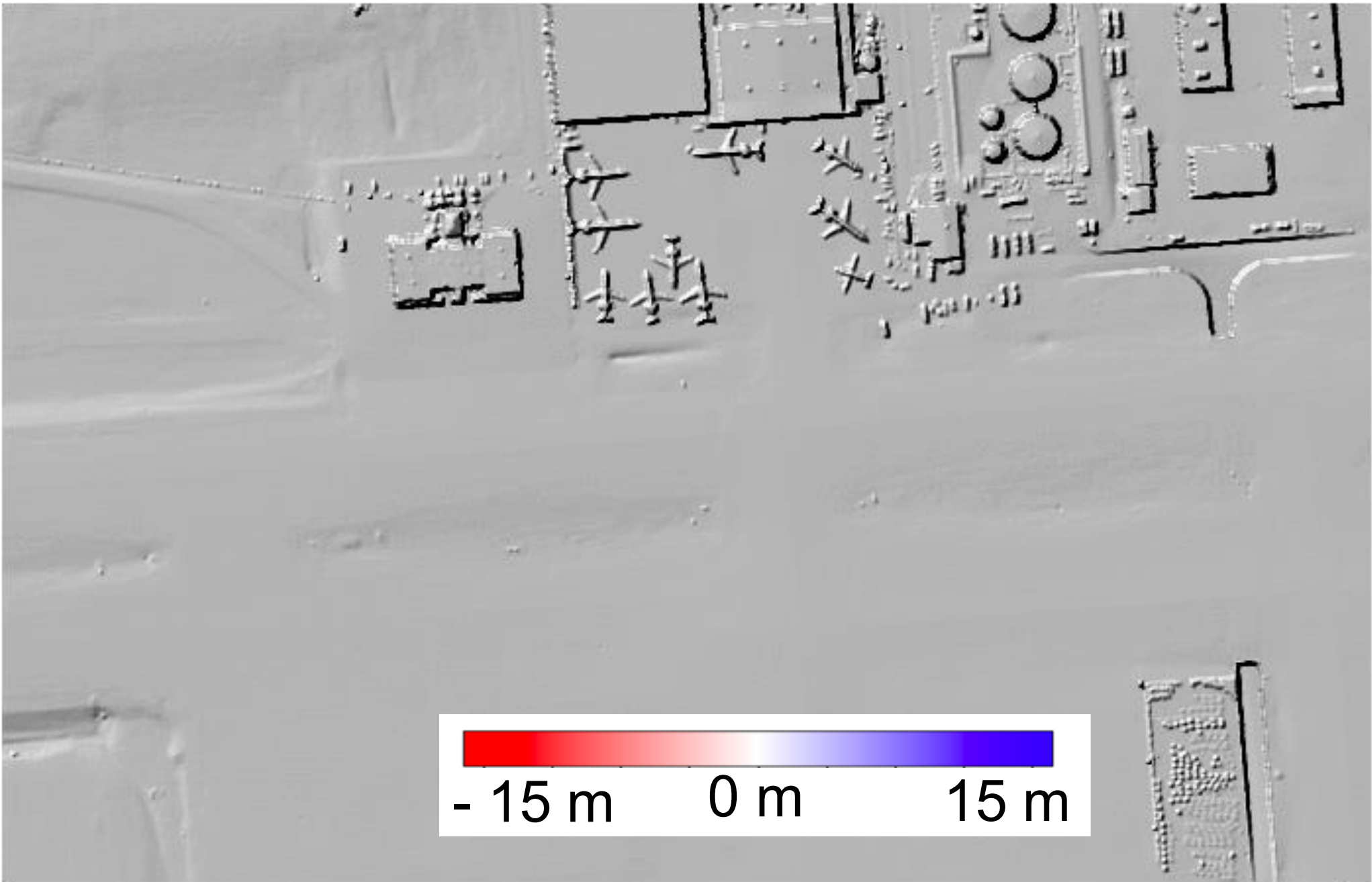


Scott et al., (2021)

## Raster subtraction



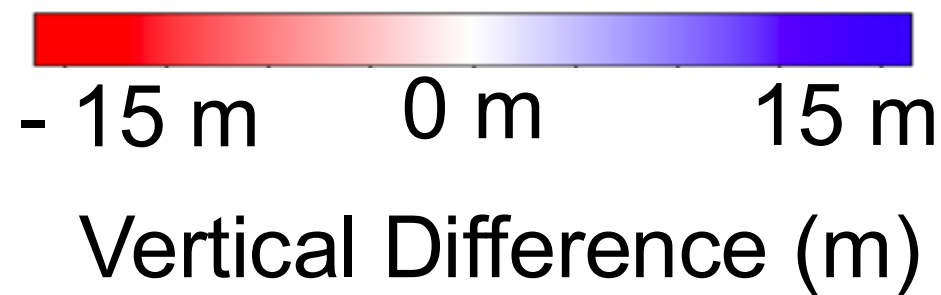
# Salt Lake City Airport





## Yosemite, California

2006-2010





# Salt Lake City, Utah



Vertical Difference (m)

-4

0

4



# On-demand Topographic Differencing



Iowa City, Iowa: 2008-2014



-8                      0                      8  
Vertical Difference (m)

## What?

In a few mouse clicks, users can run vertical and 3D differencing on OT

## Why?

Standardize approach

Democratize access to tools

Solve issues, like CRS projections

## Challenges:

Legacy & Hybrid data

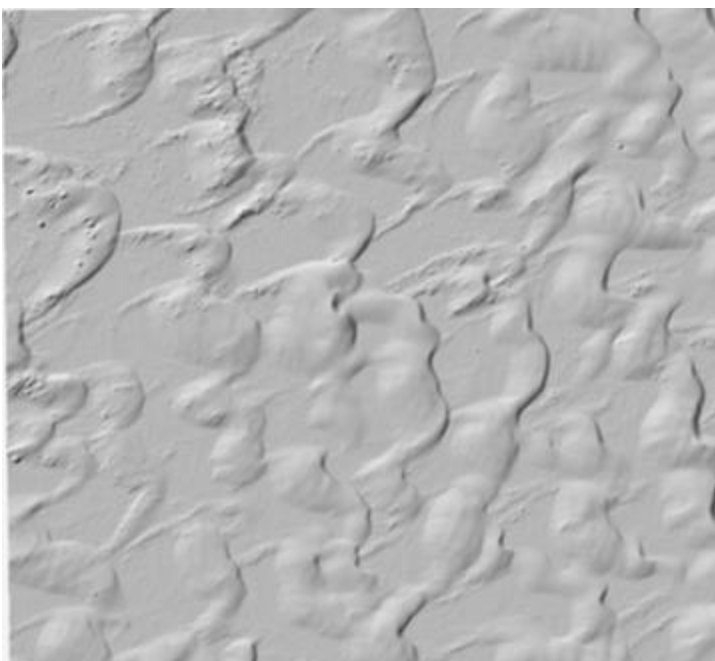
Algorithms: On-demand

Cyber-infrastructure & HPC

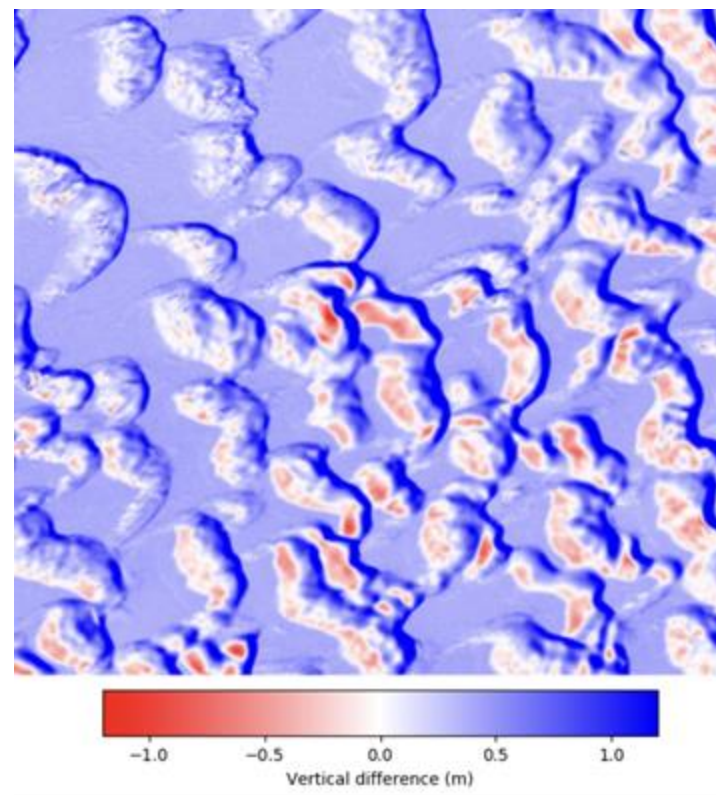
**Scott, C.,** Phan, M., Nandigam, V., Crosby, C., Arrowsmith, R. (2021). Measuring change along the Earth's surface: On-Demand vertical and 3D topographic differencing hosted by OpenTopography. *Geosphere*.  
<https://doi.org/10.1130/GES02259.1>



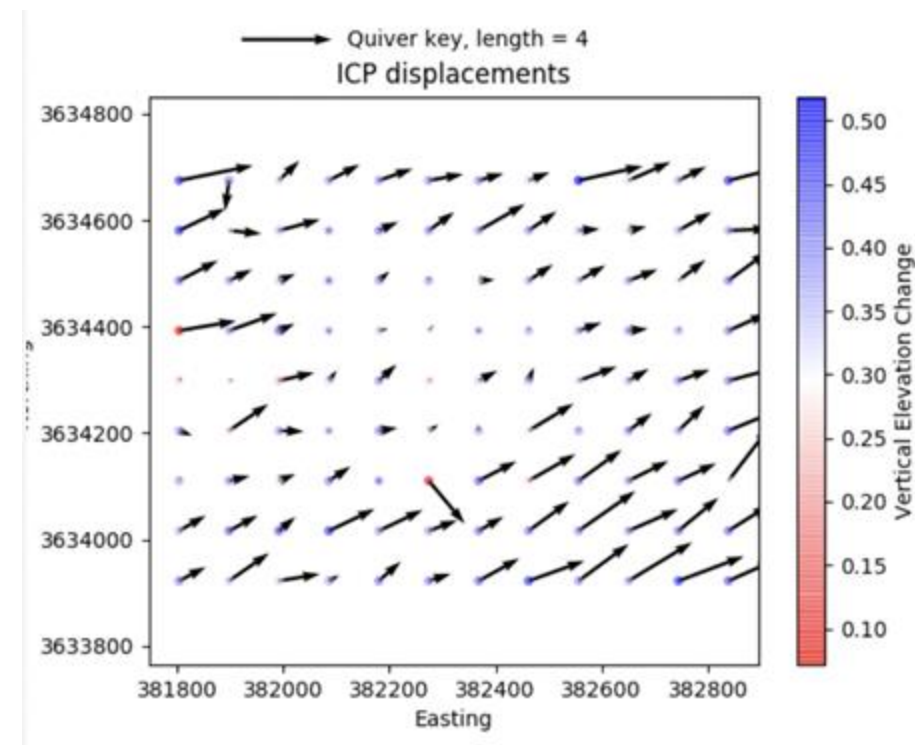
# White Sand National Monument, NM



Hillshade



Vertical differencing

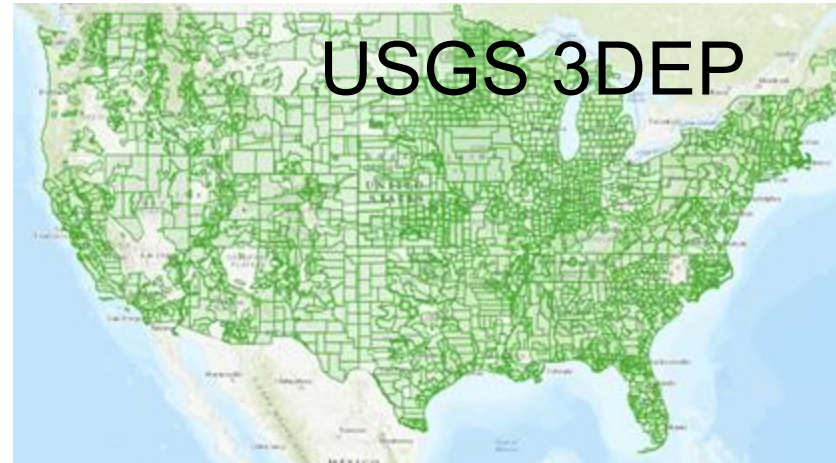


3D differencing

# Differencing in OT



OT



USGS 3DEP



NOAA

New Zealand



Perform differencing on  
(many) overlapping  
datasets

~3000 datasets  
covering over 20% of  
lower 48

Many datasets in New  
Zealand

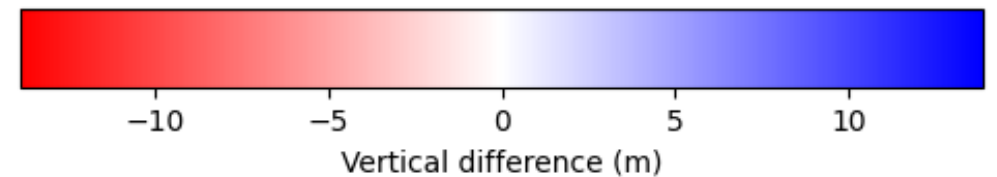
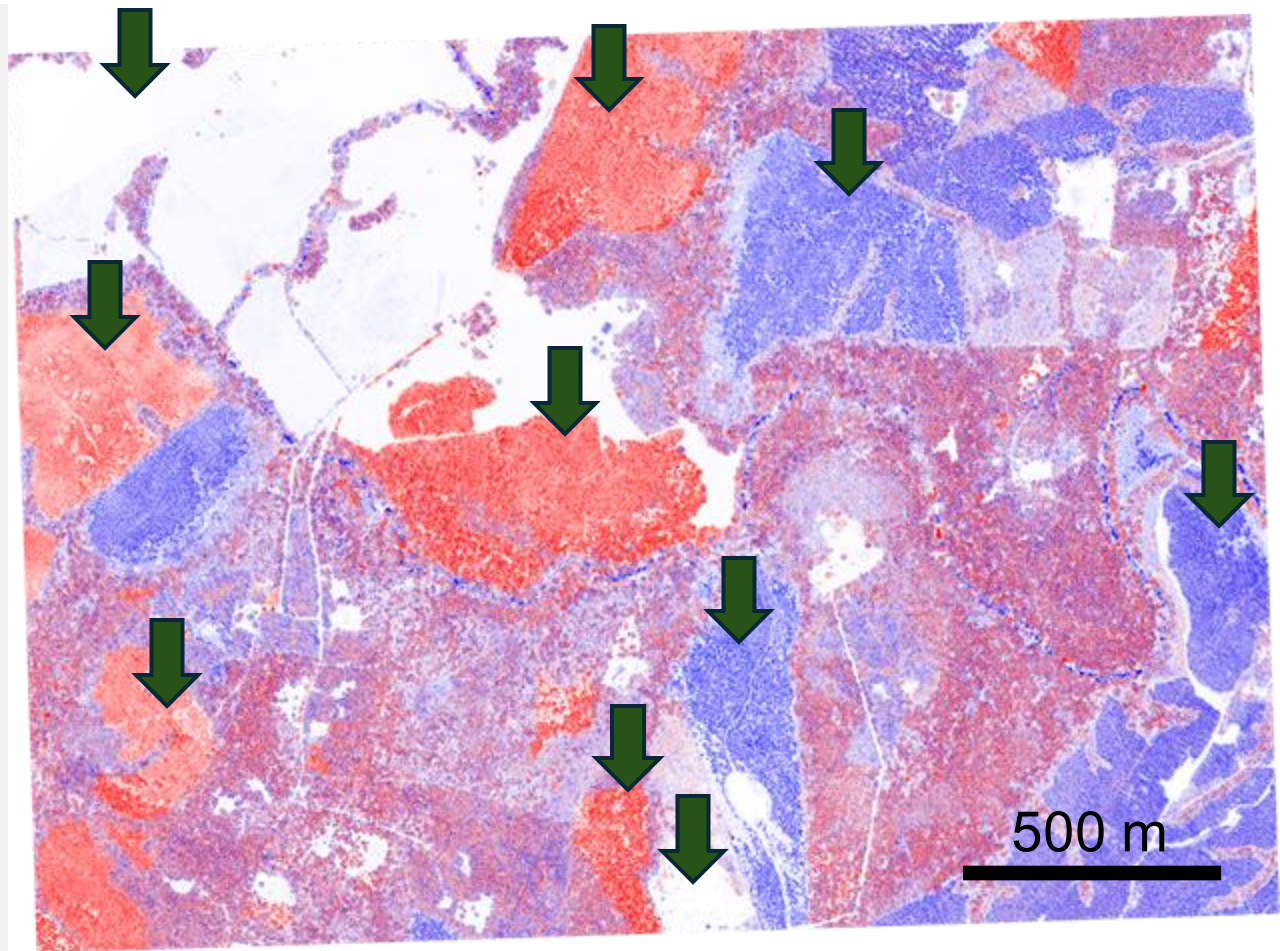
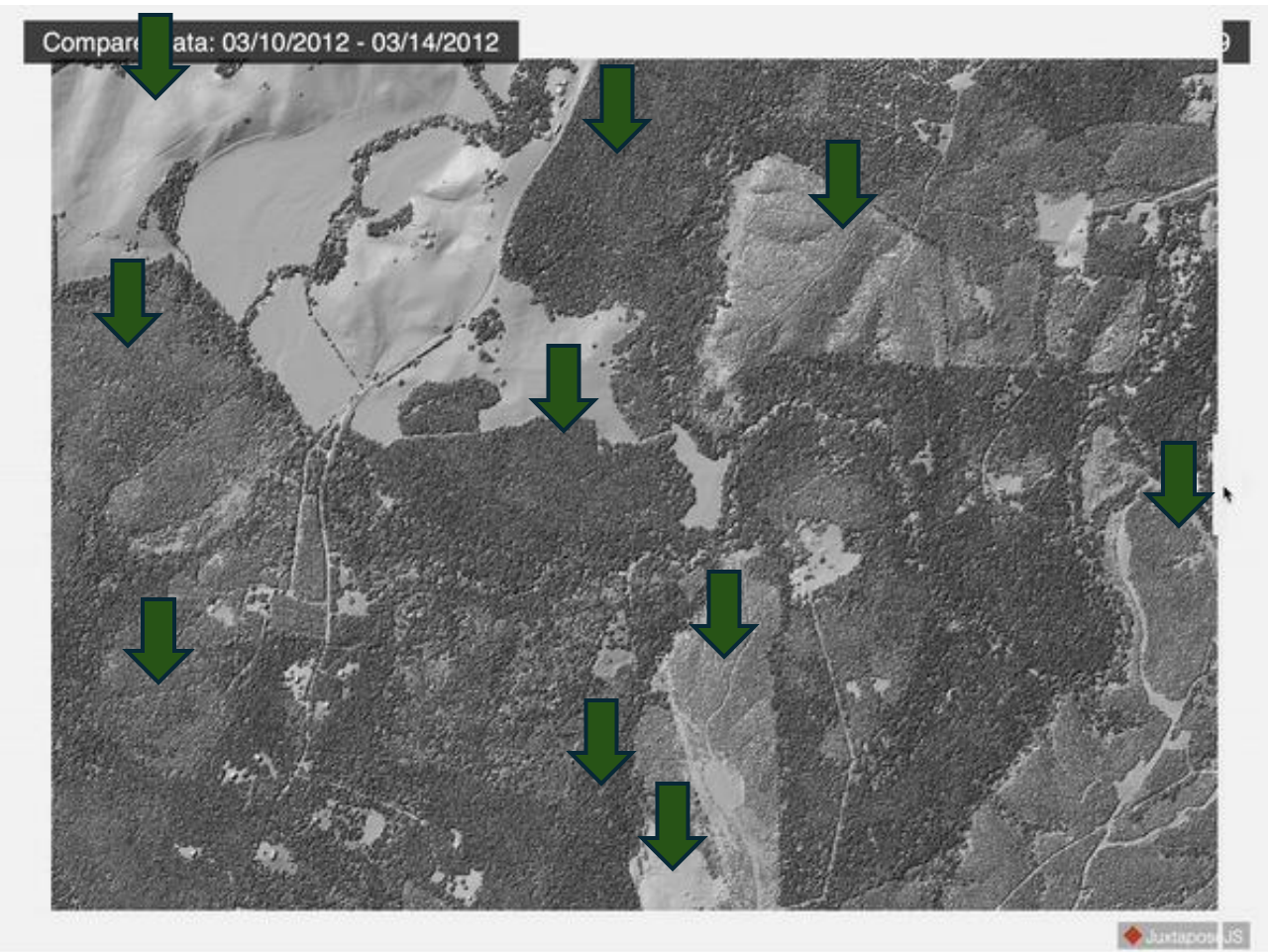
Record many  
processes

Differencing ⚙️



# Uncertainty in Vertical Differencing

## DSM differencing

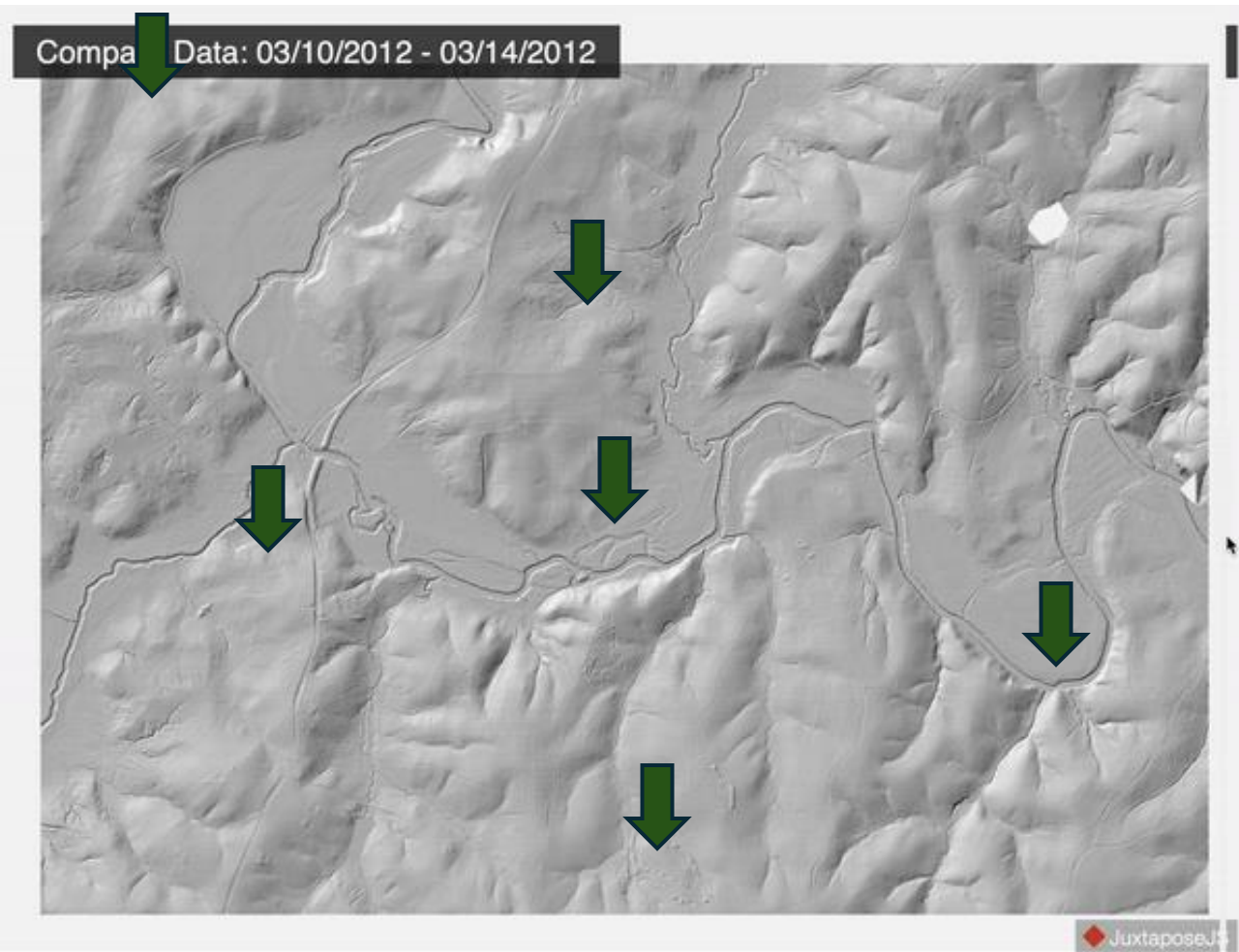


*Roundabout Creek, VA*  
*2012 - 2019*

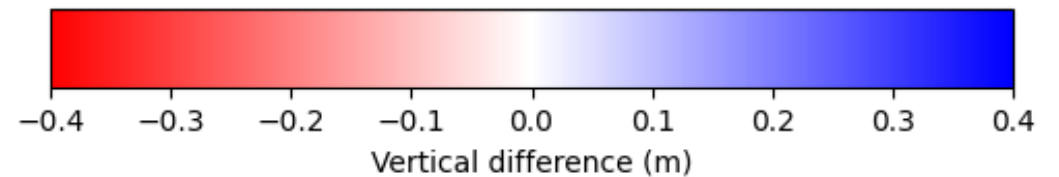
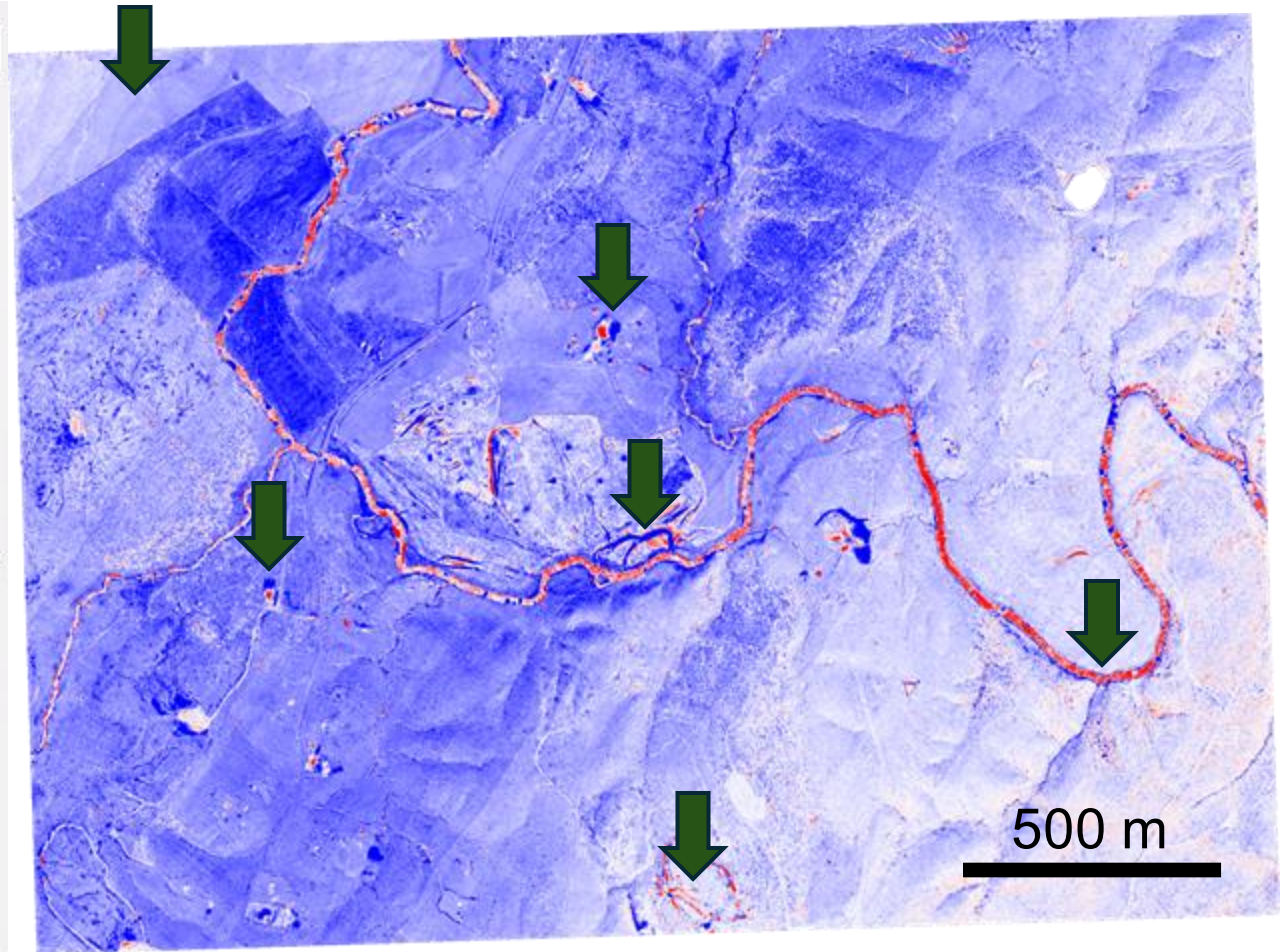


# Uncertainty in Vertical Differencing

## DTM differencing



*Roundabout Creek, VA*  
*2012 - 2019*





# Why care about uncertainty in differencing?



Errors related to dataset acquisition, processing and metadata recording are accentuated in differencing results - critical to understand and quantify the impact of these errors

Essential component of the mapping and monitoring system envisioned by this working group

Easily communicate the presence of different error types of varying orders of magnitude to non-expert users and guide them towards a better understanding of error

# Uncertainty in Vertical Differencing

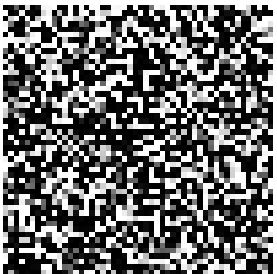


## Properties and spatial patterns of error

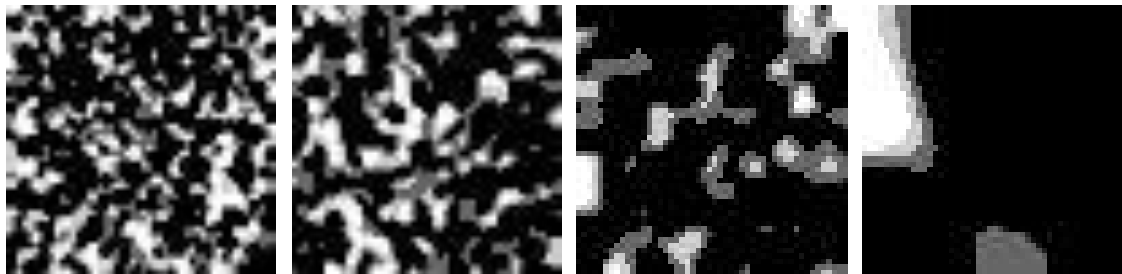
Random

Systematic

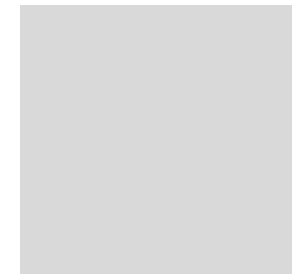
Spatially  
uncorrelated



Spatially  
correlated



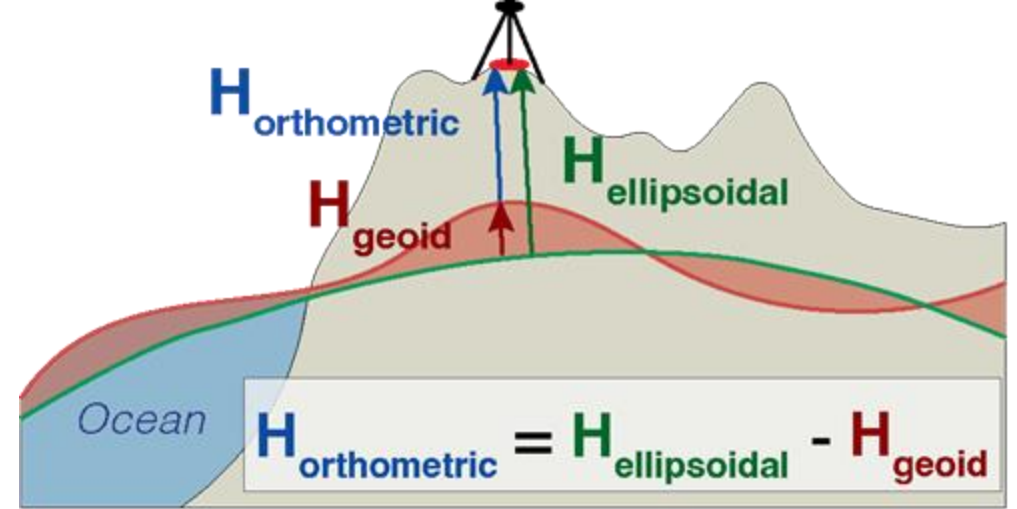
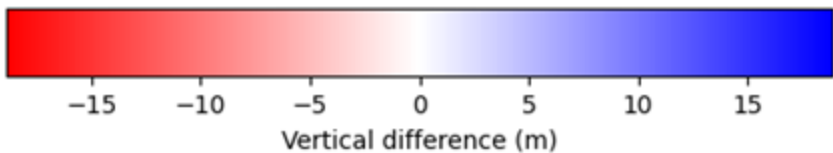
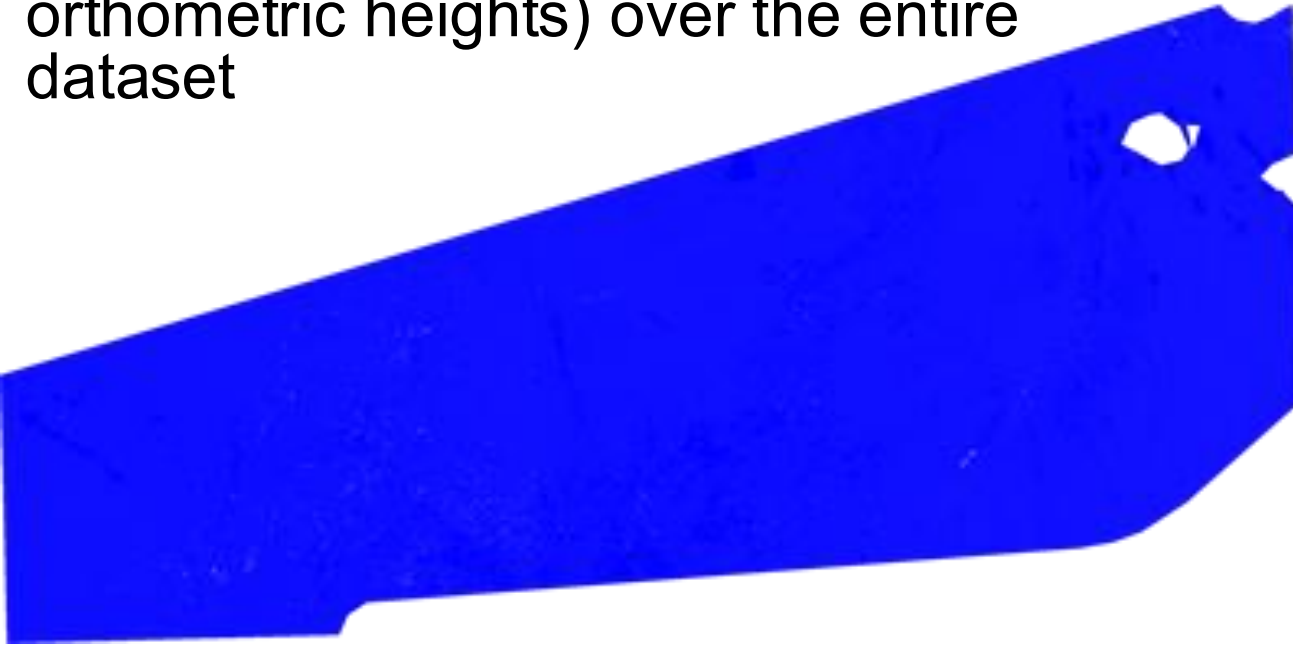
Increasing correlation range length



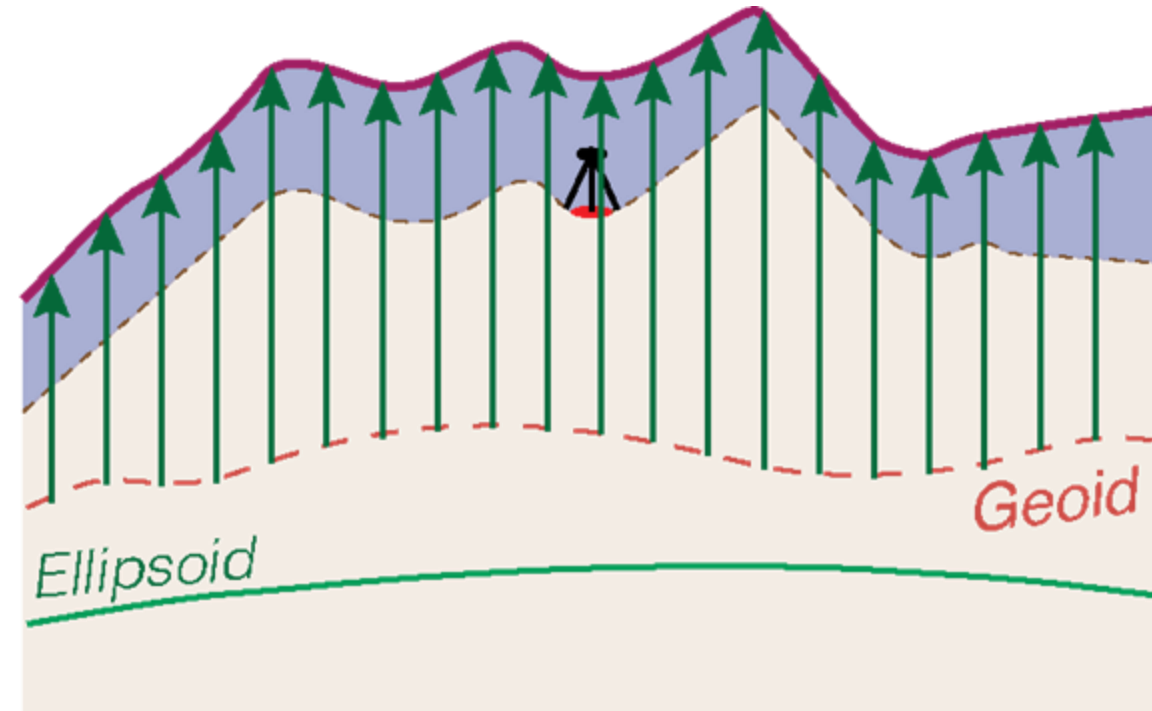


# Systematic long-range error due to metadata errors

Apparent vertical changes from 10-20 cm (incorrect geoid) to a few tens of meters (incorrect reporting of ellipsoidal and orthometric heights) over the entire dataset

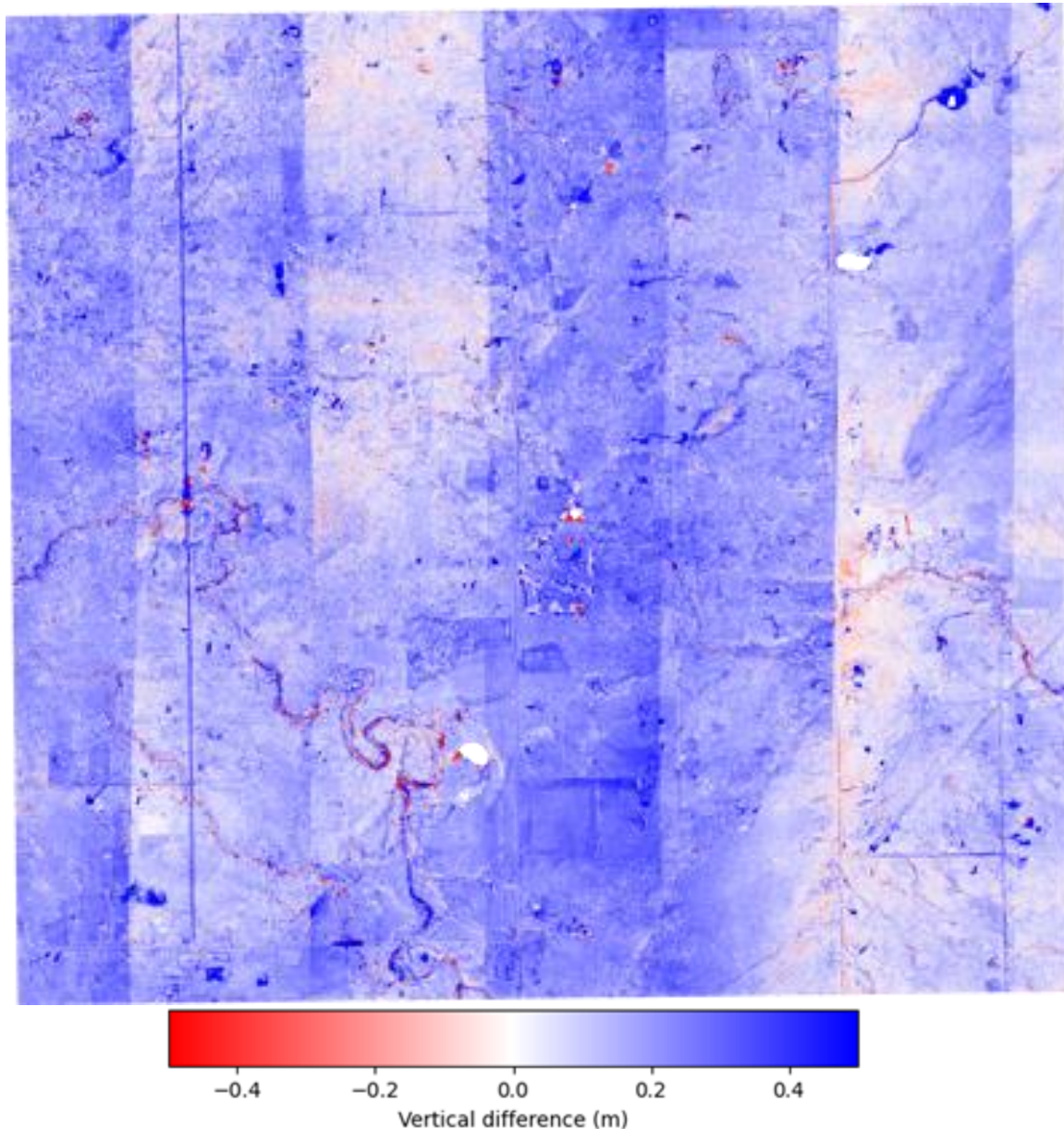


Modified from SERC



Long-range: km+ scale

# Flight line error



Georeferencing errors of the flight lines make linear, swath-to-swath artifacts

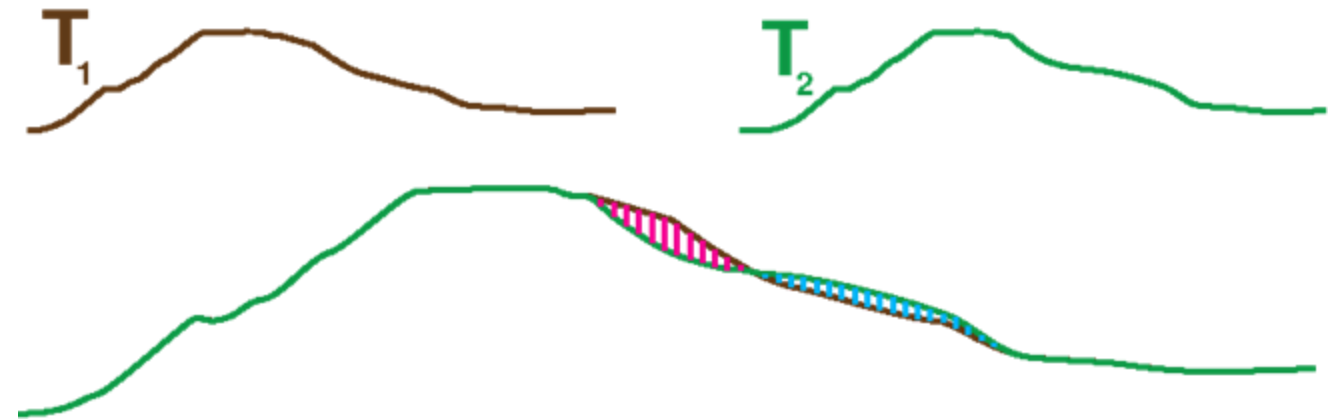
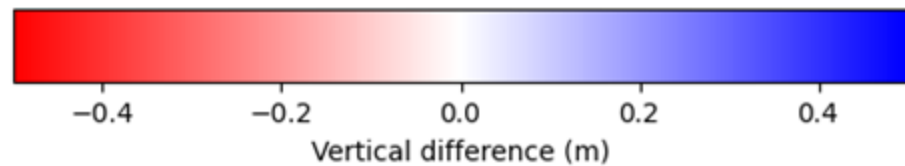
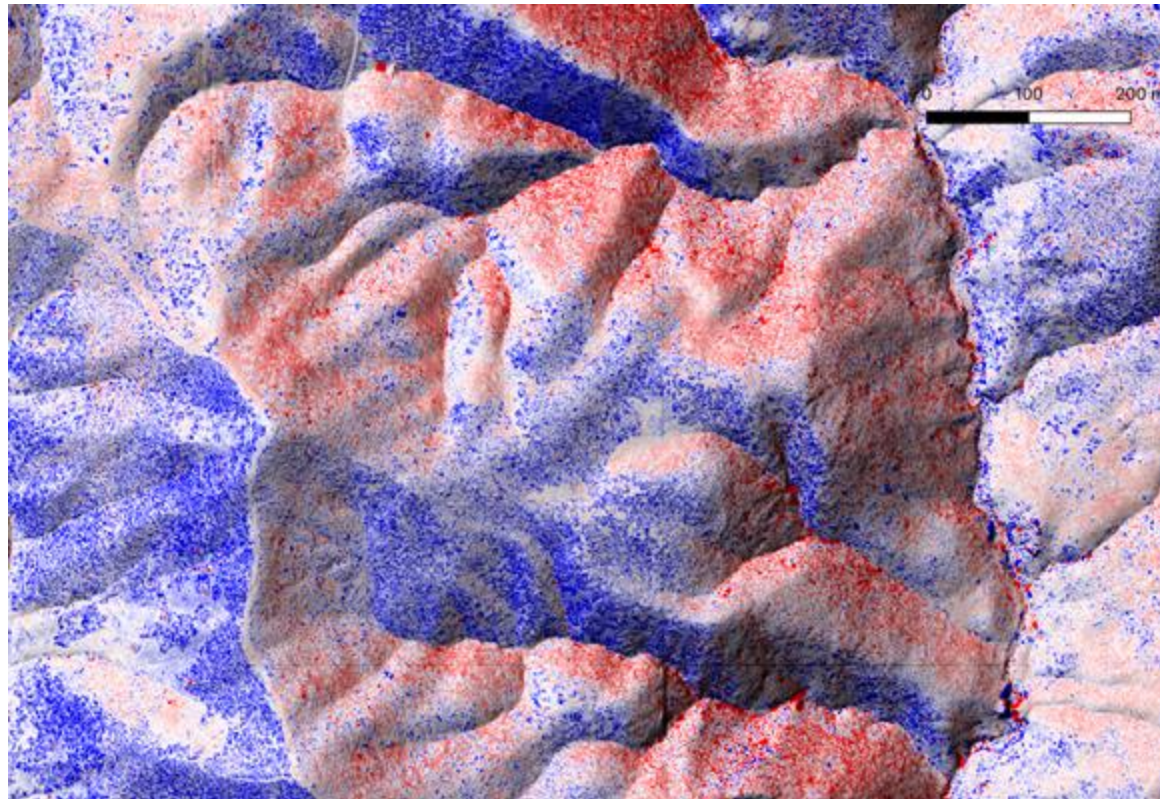
10's of centimeters (or less)

Interfere with linear patterns (e.g., roads, faults, canals) of surface change.

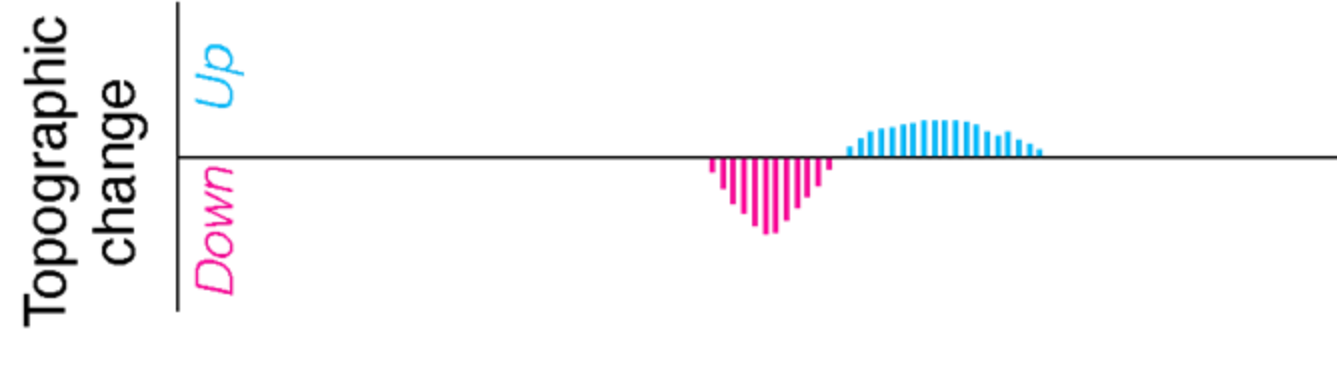
**Long- to mid-range:  
kms - 100s of m**



# Horizontal georeferencing error

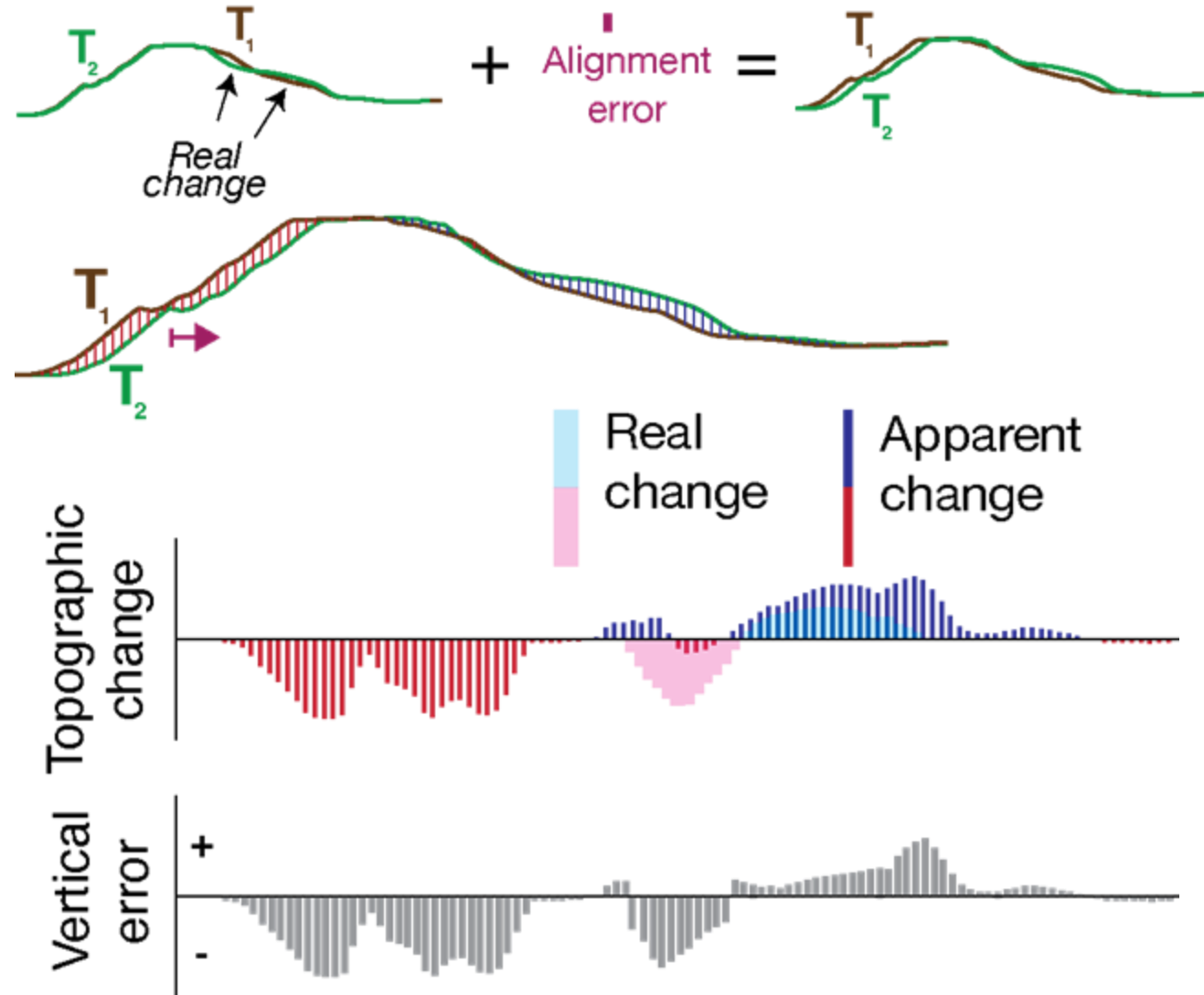
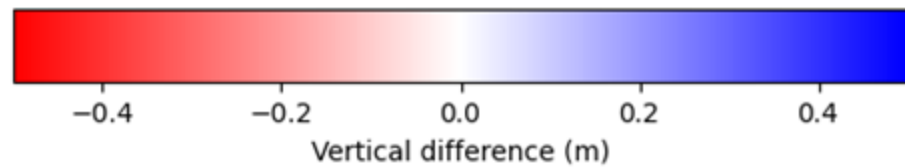
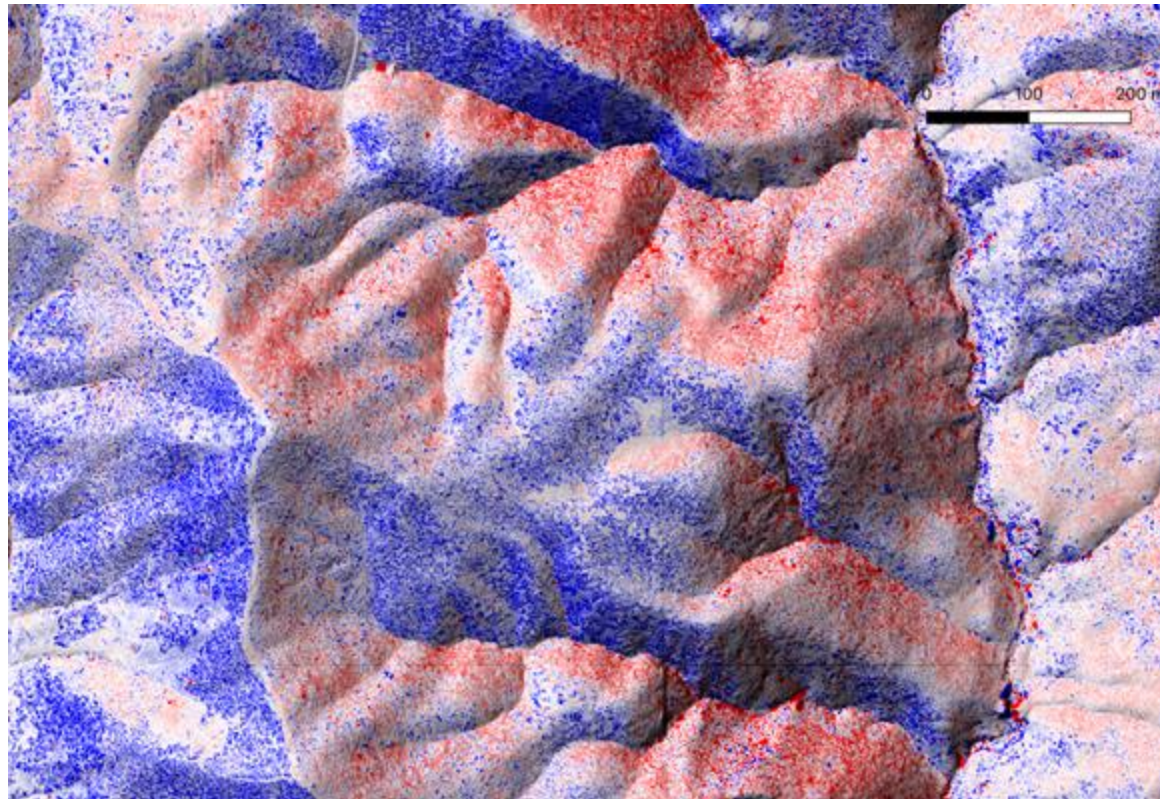


*Real and apparent change are the same*



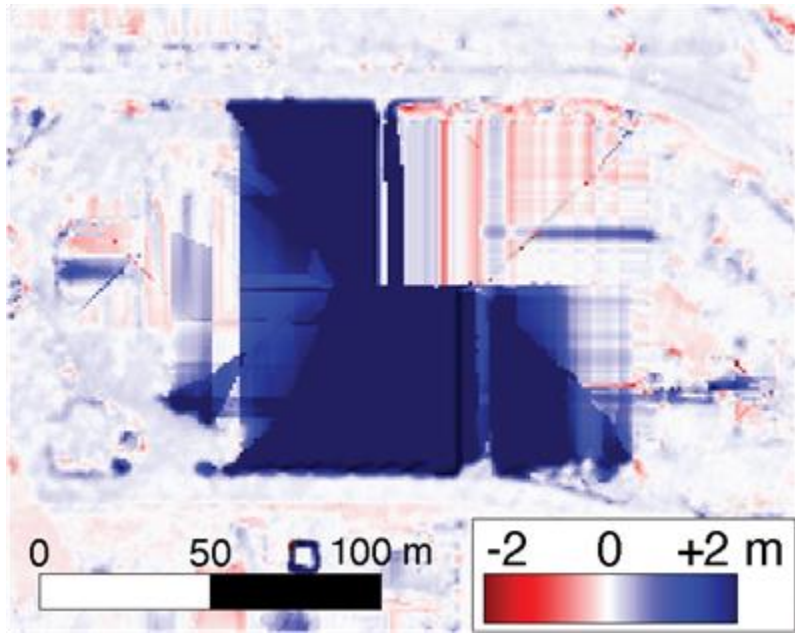
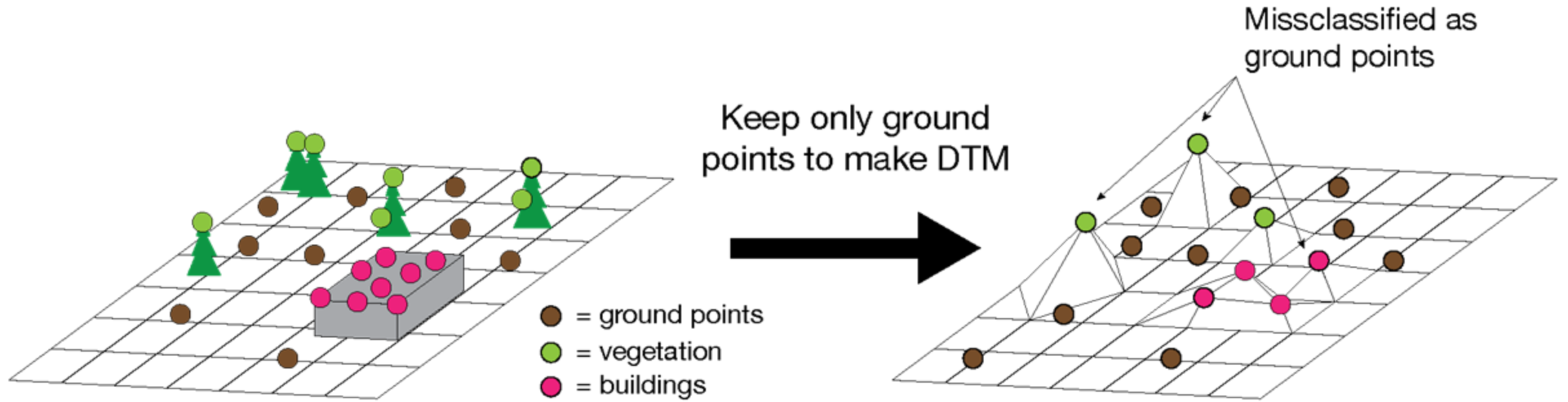
**Mid-range:  
10s to 100s of m**

# Horizontal georeferencing error



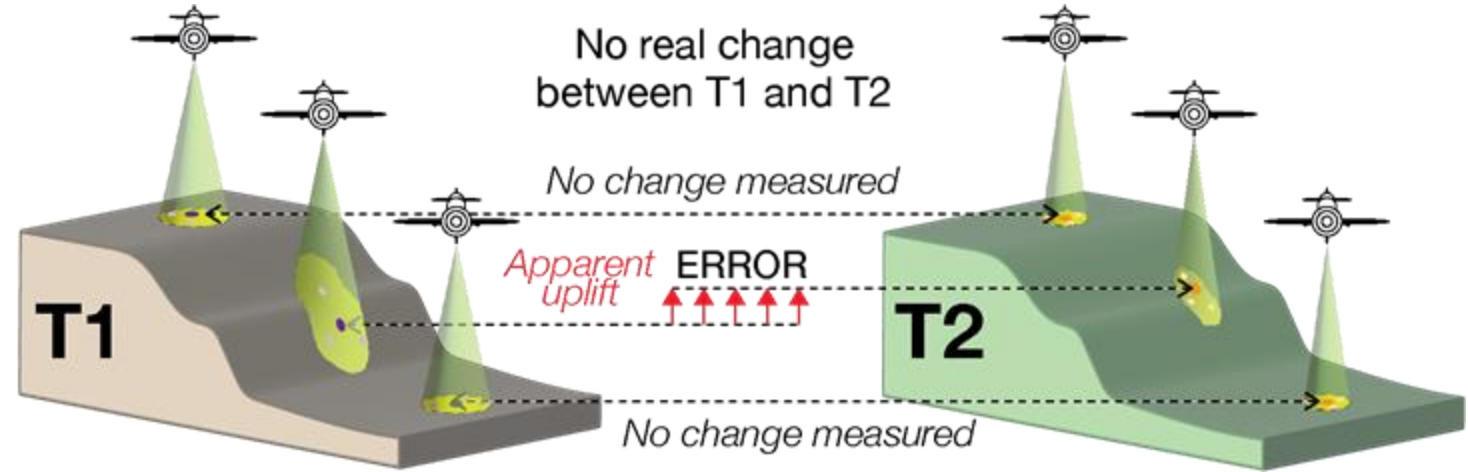
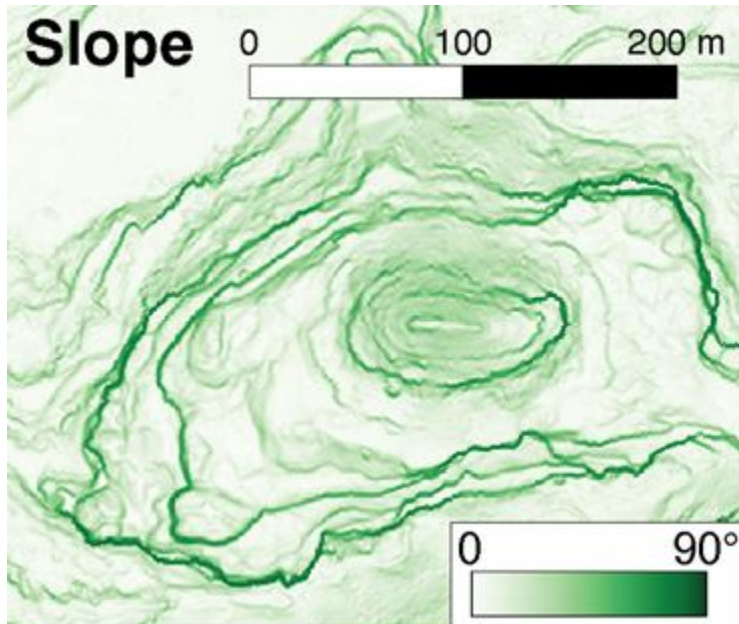
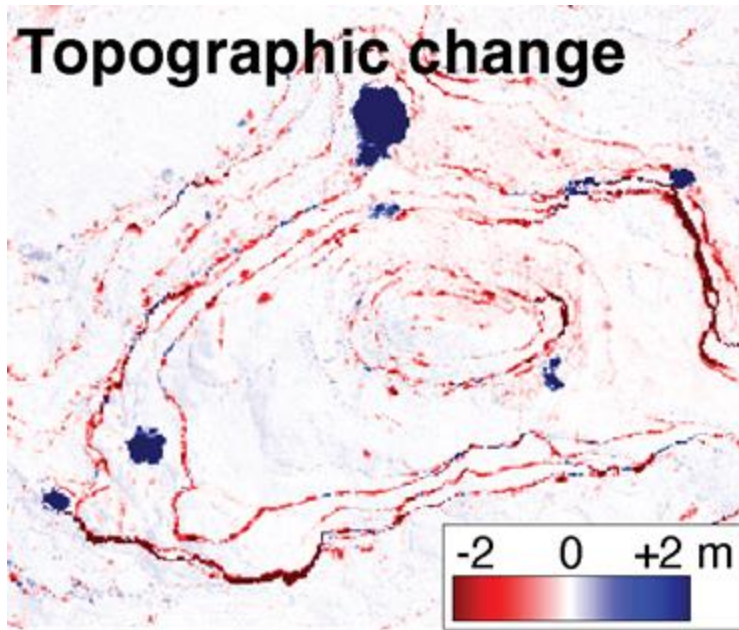


# Misclassification error



**Short-range : meters to 10s of m**

# Geometric distortion



A lidar sensor oblique to the ground surface leads to greater artificial horizontal offsets.

This geometric distortion is particularly acute over steep slopes.

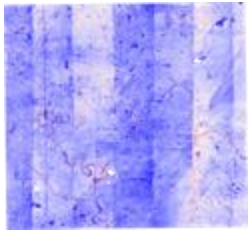
**Short-range : meters to 10s of m**



# Uncertainty in Vertical Differencing



**Very long  
range**



**Long range**



**Mid range**



**Short range**

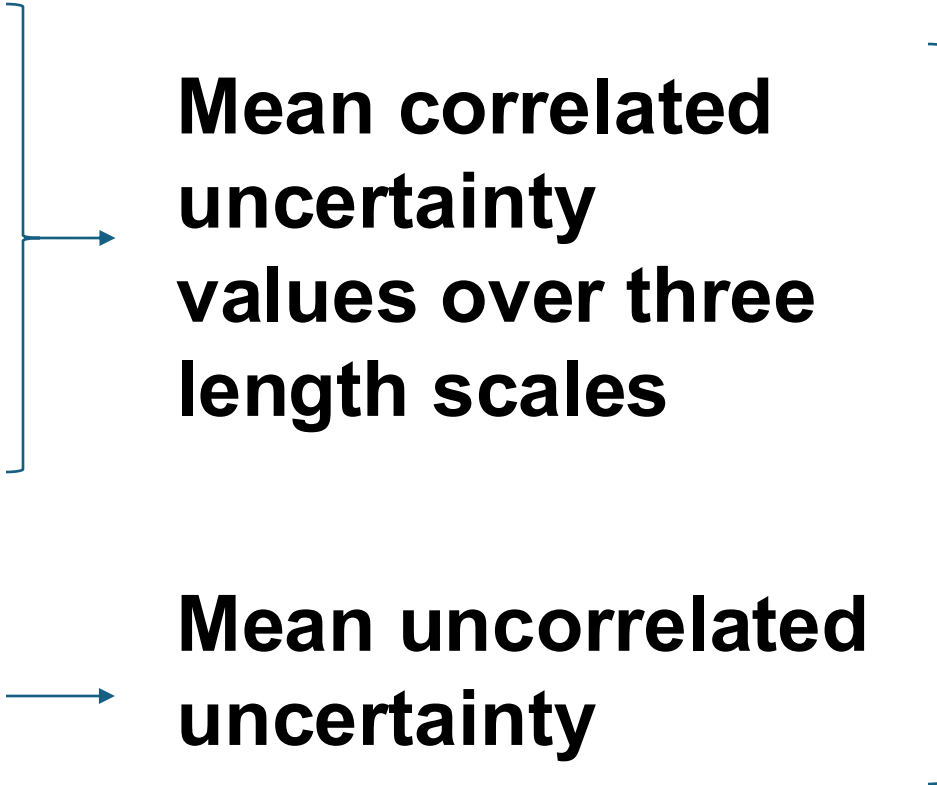


**Very short  
range**



**Vertical bias**

**– 0.4 m**



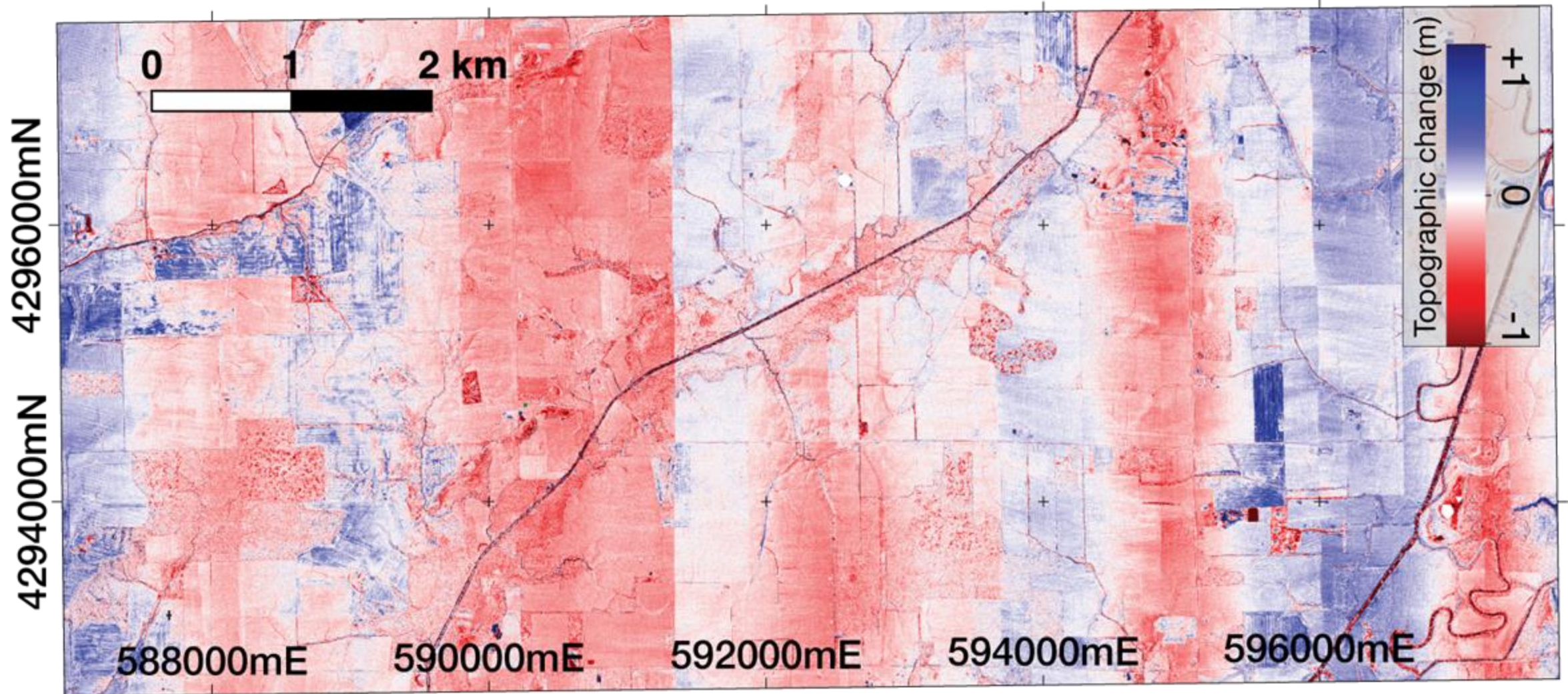
**Mean correlated  
uncertainty  
values over three  
length scales**

**Mean uncorrelated  
uncertainty**

**Total mean  
uncertainty**

**$\pm 0.004$  m**

# Uncertainty in Vertical Differencing





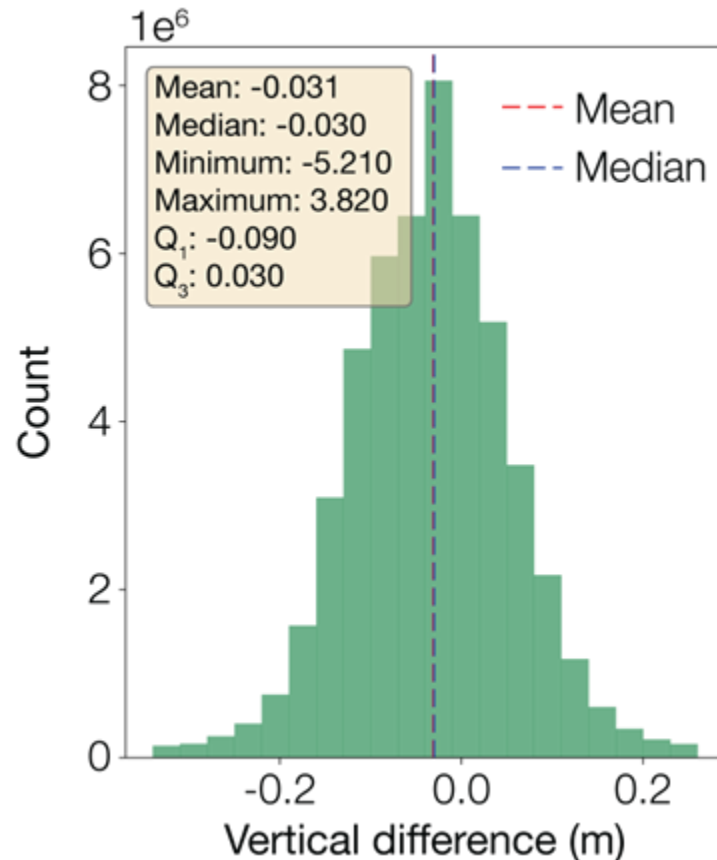
# Uncertainty in Vertical Differencing



**Very long  
range**



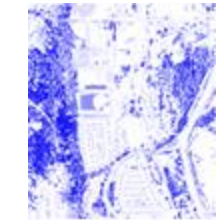
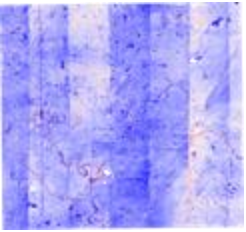
**Vertical bias**  
e.g. - 0.4 m



Area: **52.3 km<sup>2</sup>**

Vertical bias: - 0.030 m

# Uncertainty in Vertical Differencing

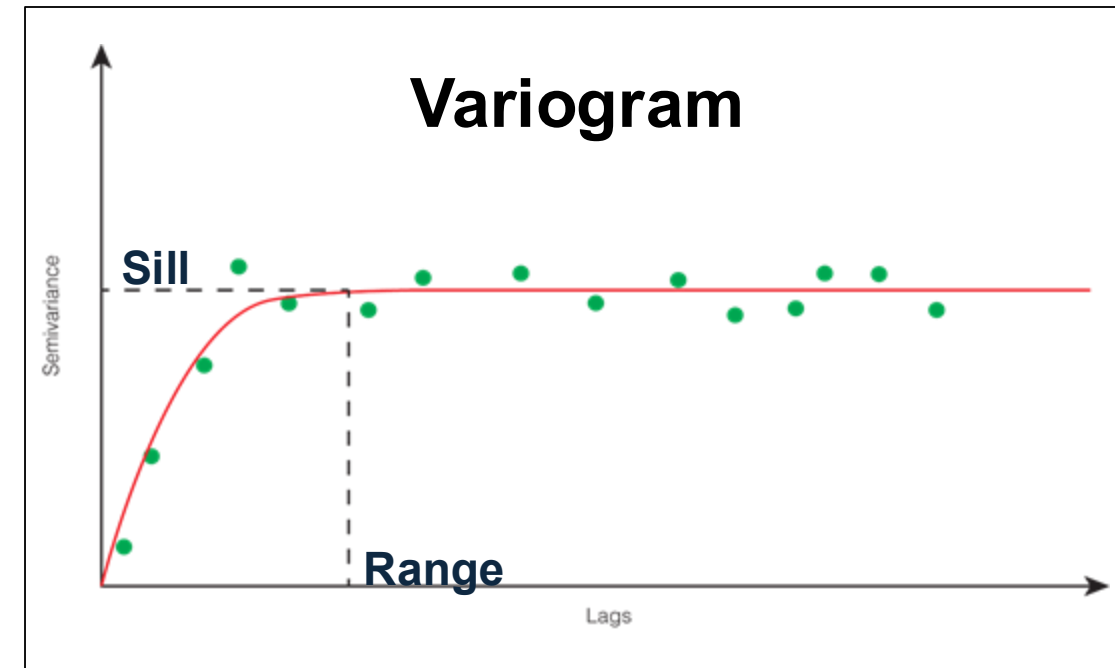


**Long range**

**Mid range**

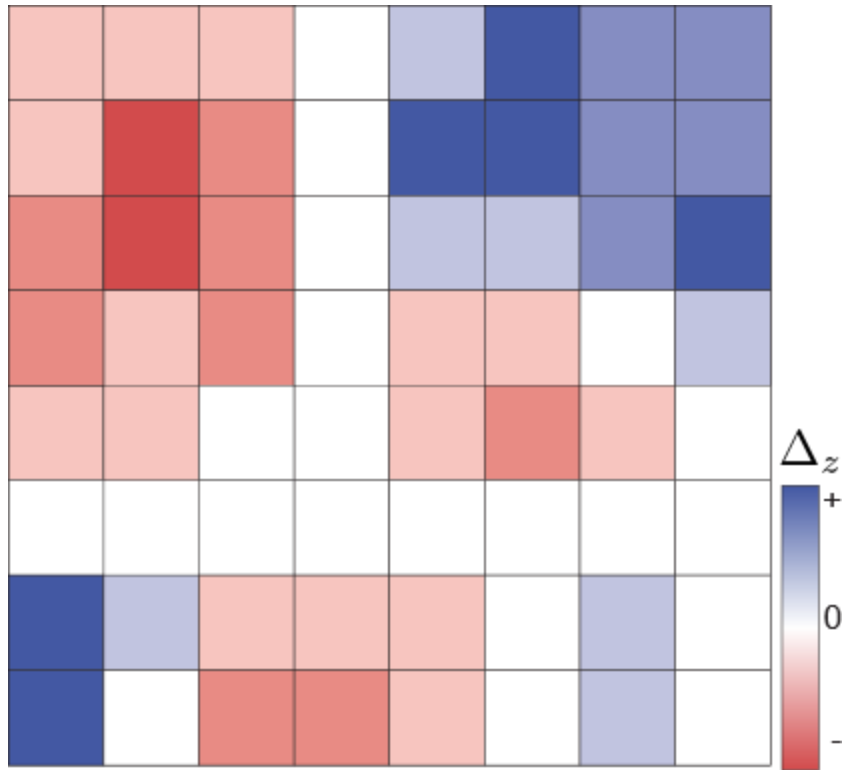
**Short range**

**Mean correlated  
uncertainty  
values over three  
length scales**

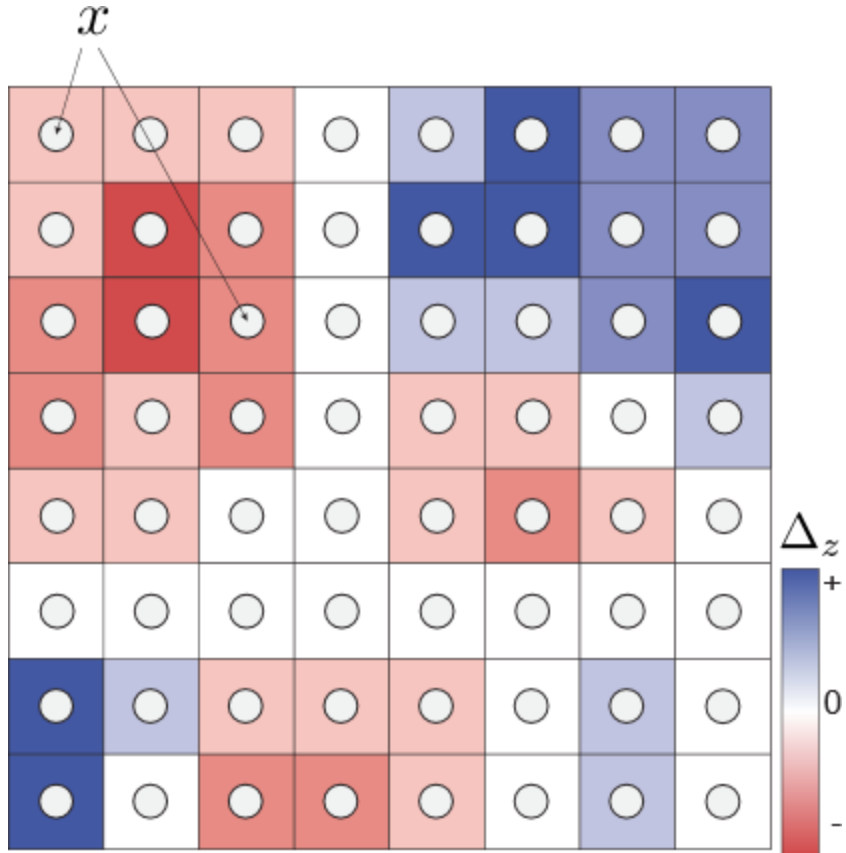




# Uncertainty in Vertical Differencing

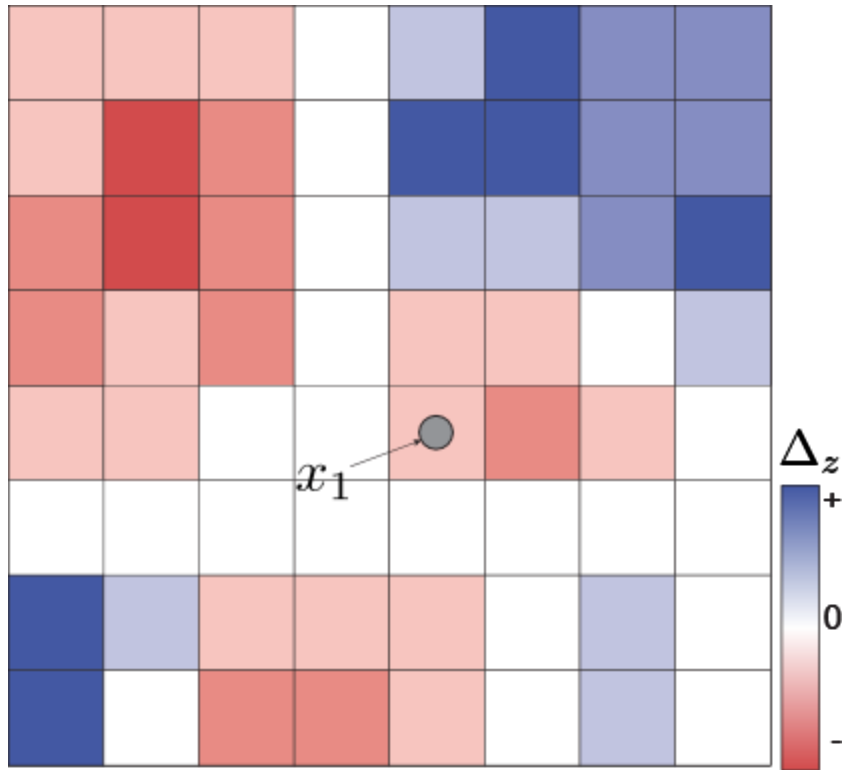


# Uncertainty in Vertical Differencing

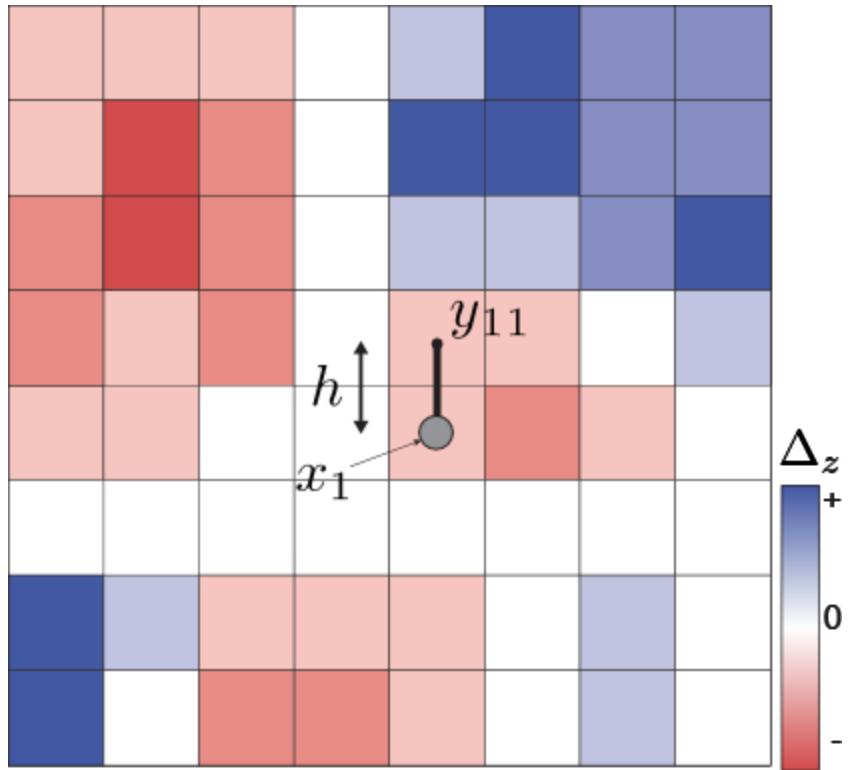




# Uncertainty in Vertical Differencing

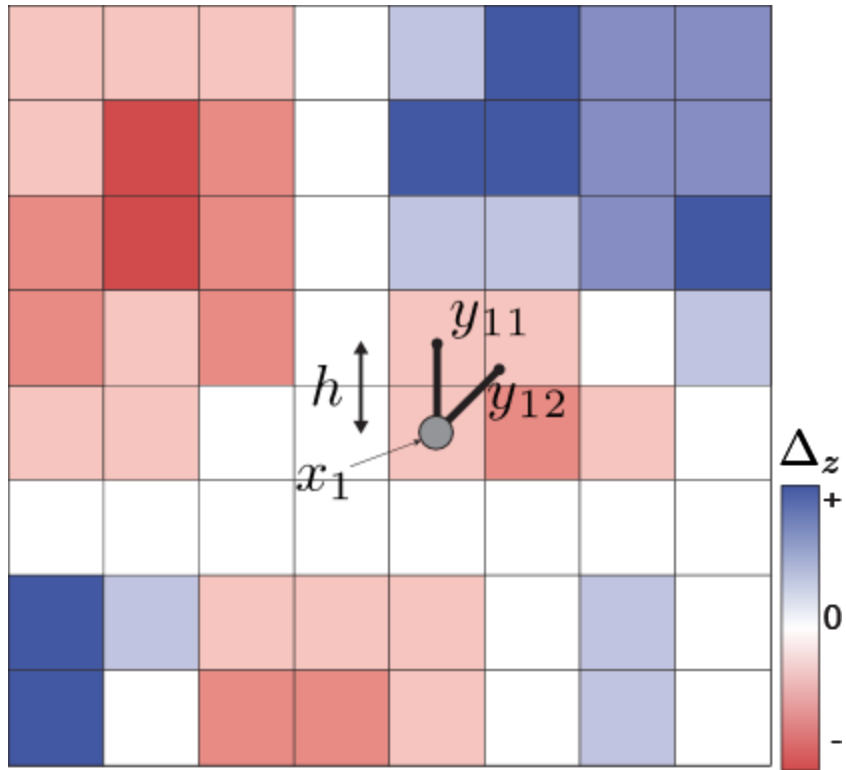


# Uncertainty in Vertical Differencing

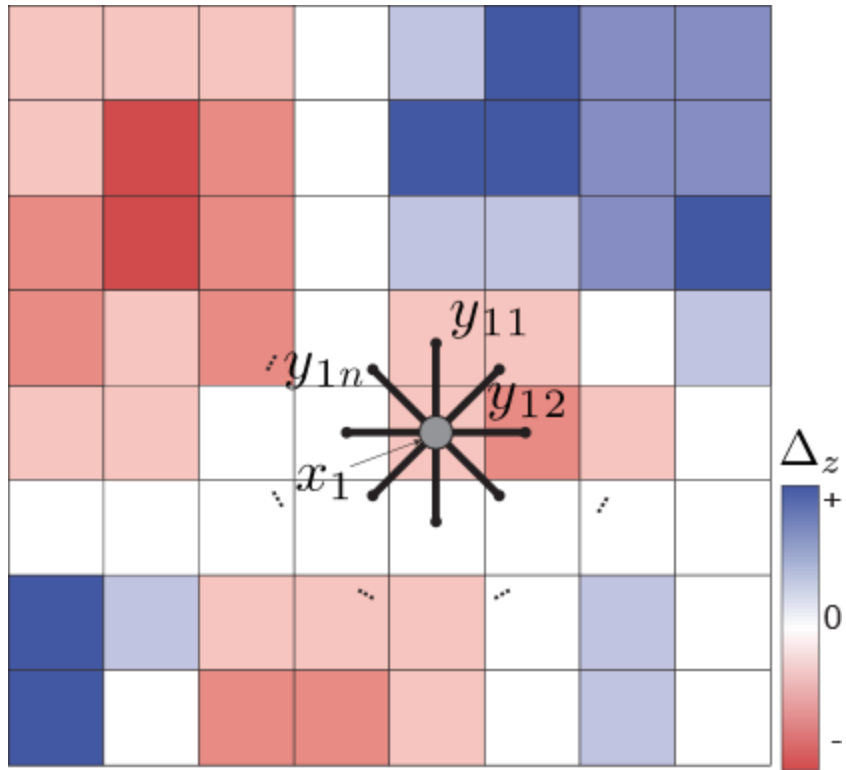




# Uncertainty in Vertical Differencing

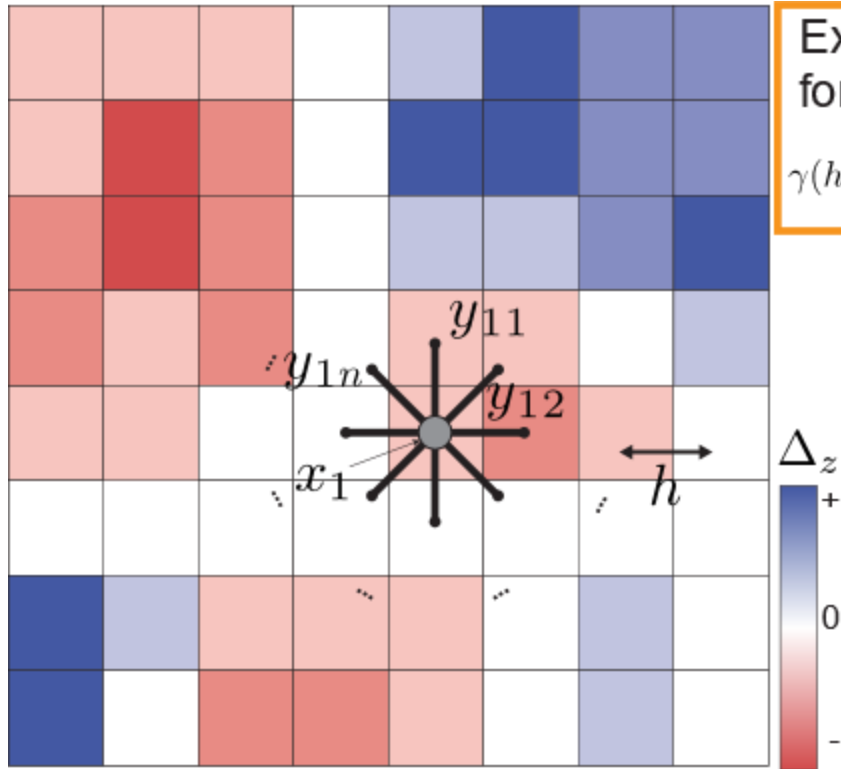


# Uncertainty in Vertical Differencing



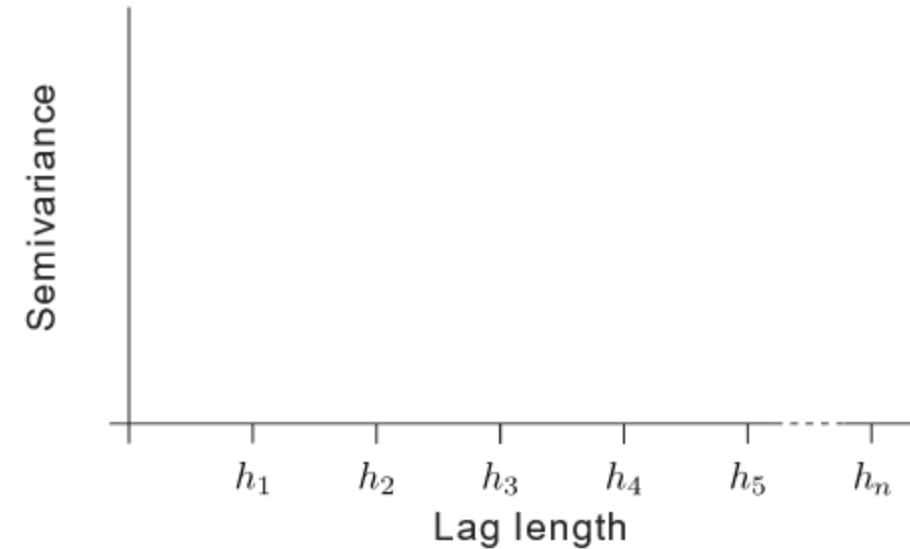


# Uncertainty in Vertical Differencing

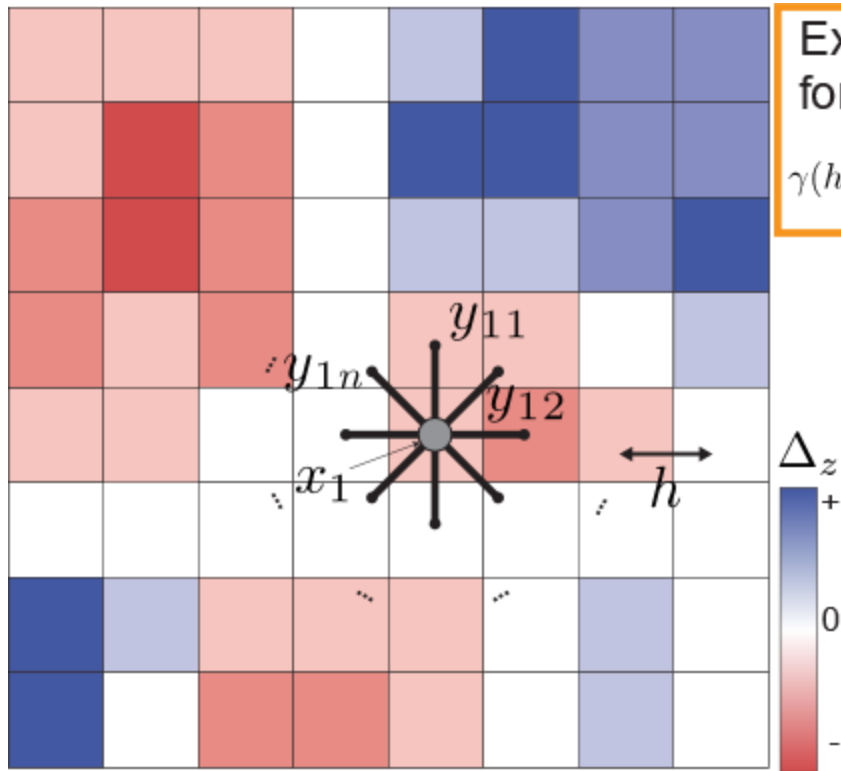


Experimental semivariance calculation for a given lag  $h$ , calculated in  $m$  directions for  $m$  samples :

$$\gamma(h) = \frac{[\Delta_z(x_1) - \Delta_z(y_{h1})]^2 + [\Delta_z(x_1) - \Delta_z(y_{h2})]^2 + \dots + [\Delta_z(x_2) - \Delta_z(y_{h1})]^2 + \dots + [\Delta_z(x_m) - \Delta_z(y_{hn})]^2}{2mn}$$

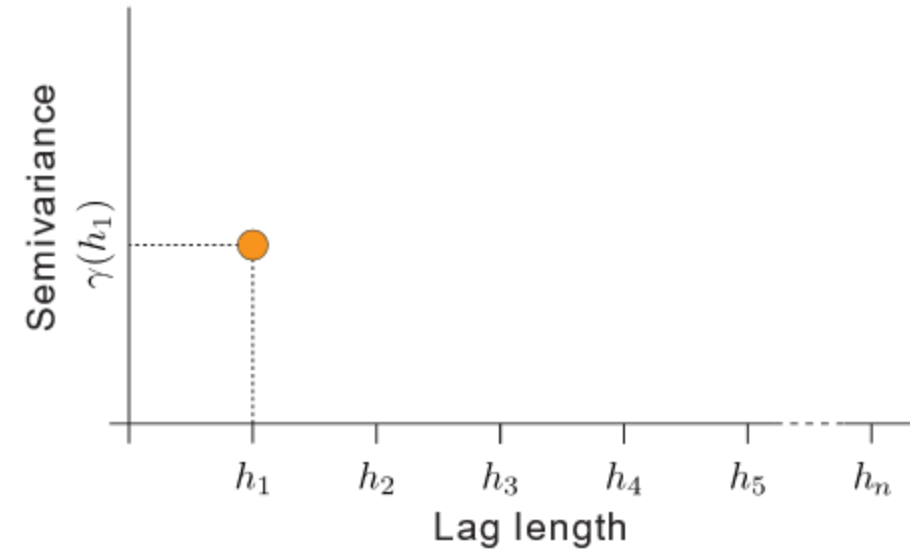


# Uncertainty in Vertical Differencing



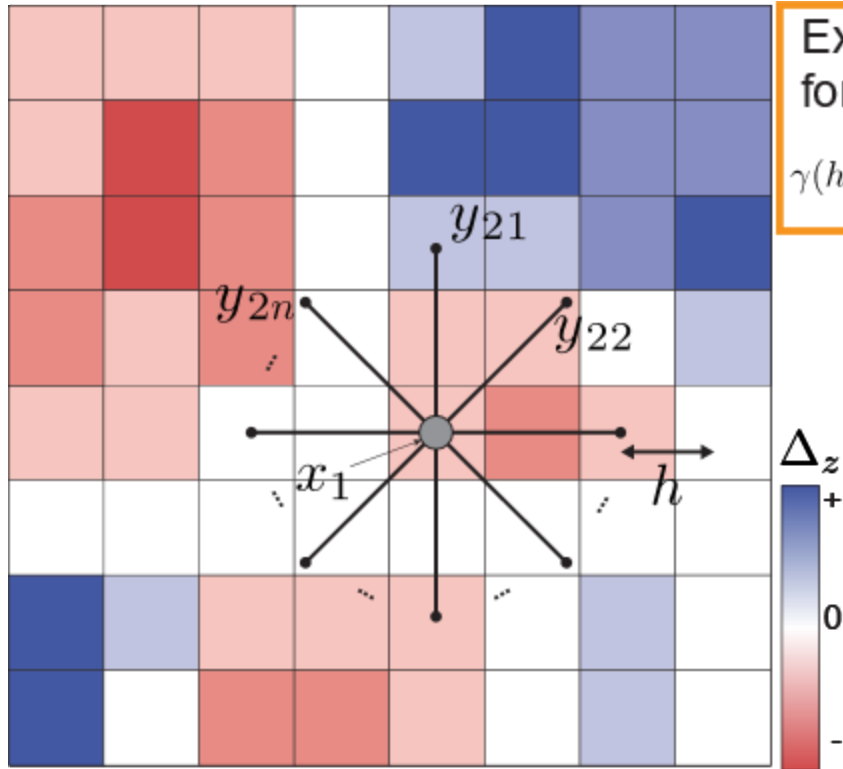
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$$\gamma(h) = \frac{[\Delta_z(x_1) - \Delta_z(y_{h1})]^2 + [\Delta_z(x_1) - \Delta_z(y_{h2})]^2 + \dots + [\Delta_z(x_2) - \Delta_z(y_{h1})]^2 + \dots + [\Delta_z(x_m) - \Delta_z(y_{hn})]^2}{2mn}$$



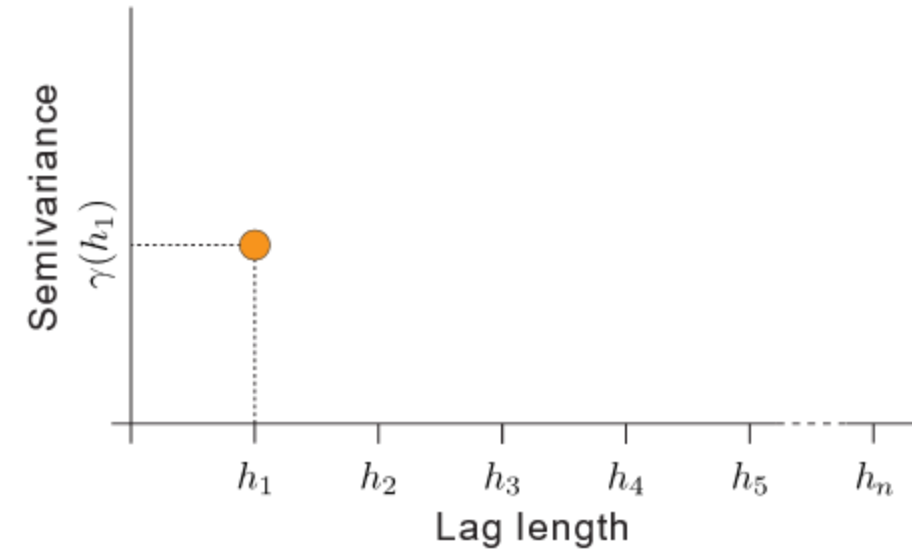


# Uncertainty in Vertical Differencing

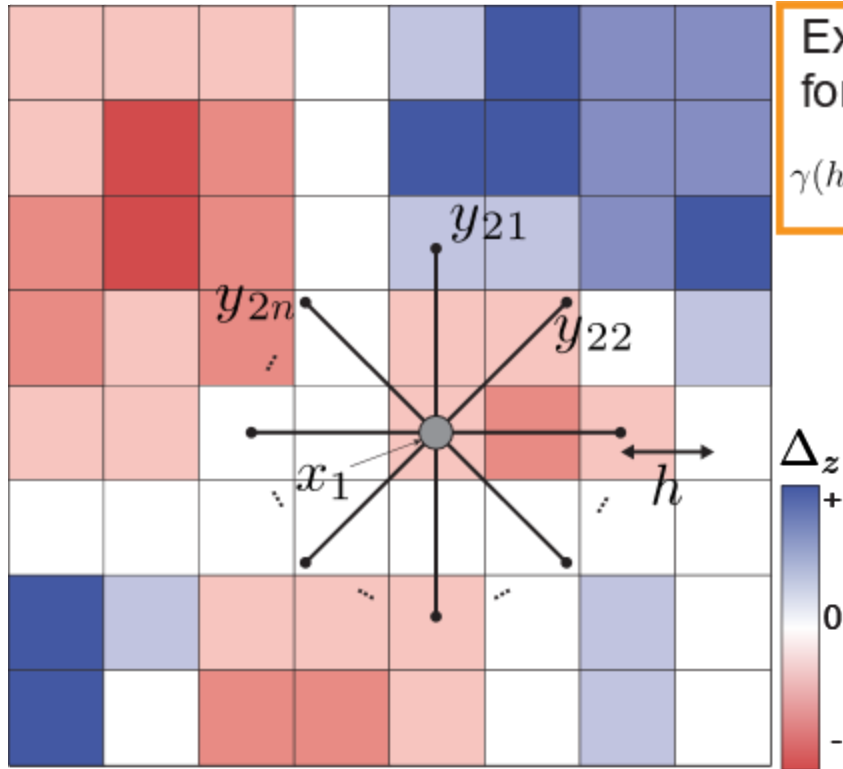


Experimental semivariance calculation for a given lag  $h$ , calculated in  $m$  directions for  $n$  samples :

$$\gamma(h) = \frac{[\Delta_z(x_1) - \Delta_z(y_{h1})]^2 + [\Delta_z(x_1) - \Delta_z(y_{h2})]^2 + \dots + [\Delta_z(x_2) - \Delta_z(y_{h1})]^2 + \dots + [\Delta_z(x_m) - \Delta_z(y_{hn})]^2}{2mn}$$

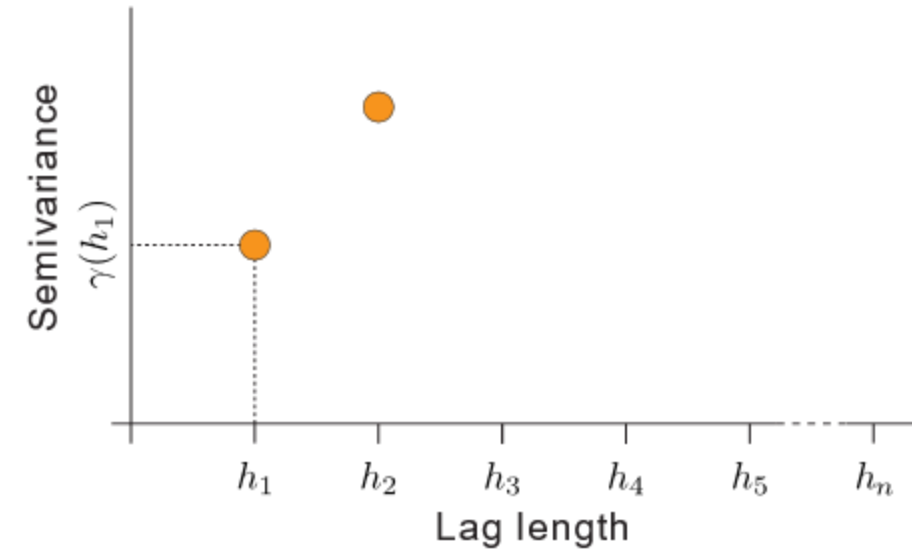


# Uncertainty in Vertical Differencing



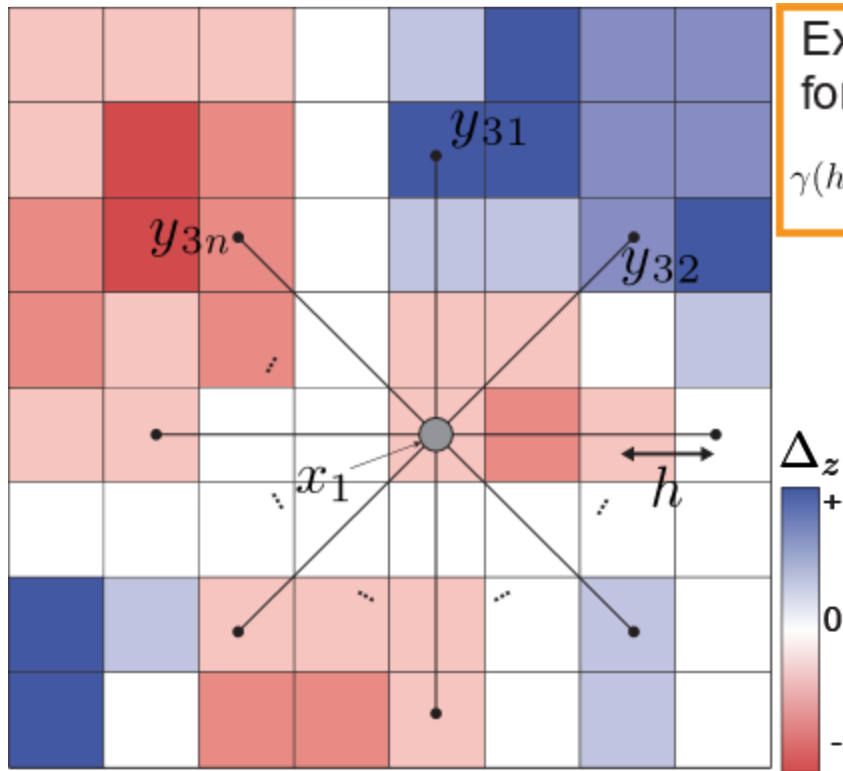
Experimental semivariance calculation for a given lag  $h$ , calculated in  $m$  directions for  $n$  samples :

$$\gamma(h) = \frac{[\Delta_z(x_1) - \Delta_z(y_{h1})]^2 + [\Delta_z(x_1) - \Delta_z(y_{h2})]^2 + \dots + [\Delta_z(x_2) - \Delta_z(y_{h1})]^2 + \dots + [\Delta_z(x_m) - \Delta_z(y_{hn})]^2}{2mn}$$



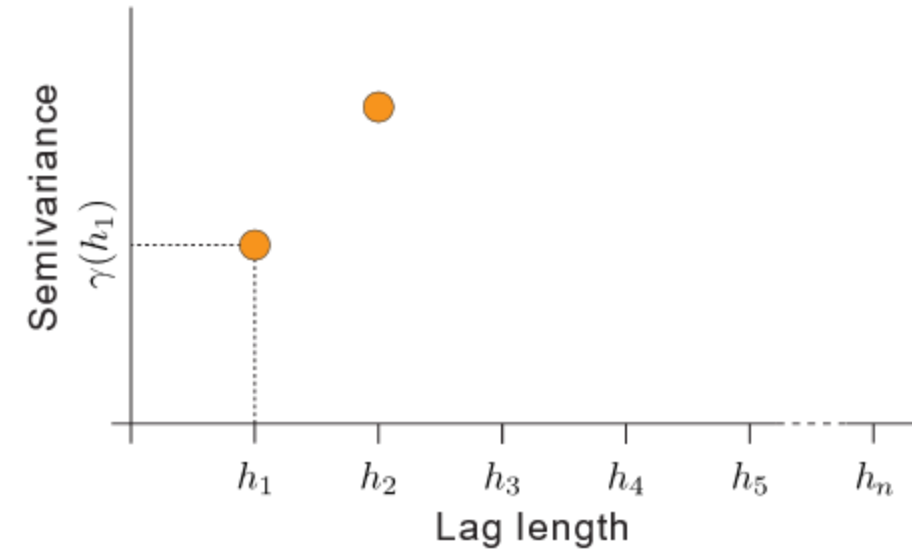


# Uncertainty in Vertical Differencing

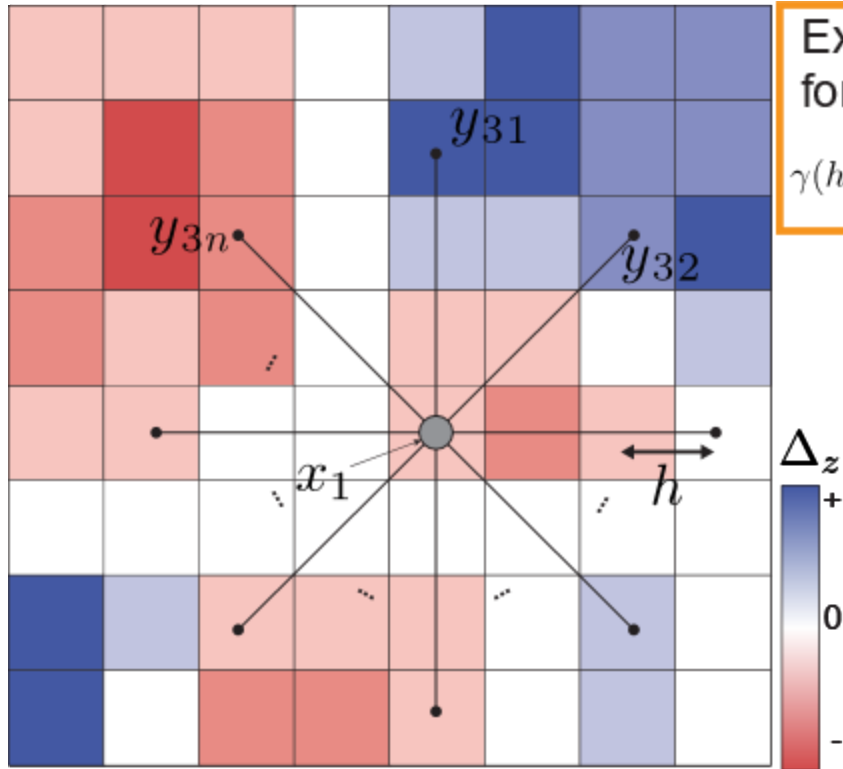


Experimental semivariance calculation for a given lag  $h$ , calculated in  $m$  directions for  $m$  samples :

$$\gamma(h) = \frac{[\Delta_z(x_1) - \Delta_z(y_{h1})]^2 + [\Delta_z(x_1) - \Delta_z(y_{h2})]^2 + \dots + [\Delta_z(x_2) - \Delta_z(y_{h1})]^2 + \dots + [\Delta_z(x_m) - \Delta_z(y_{hn})]^2}{2mn}$$

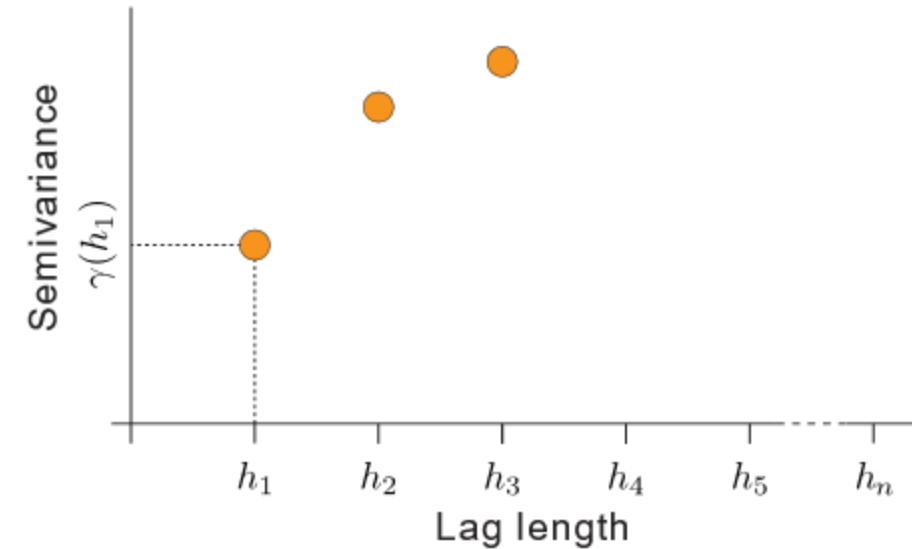


# Uncertainty in Vertical Differencing



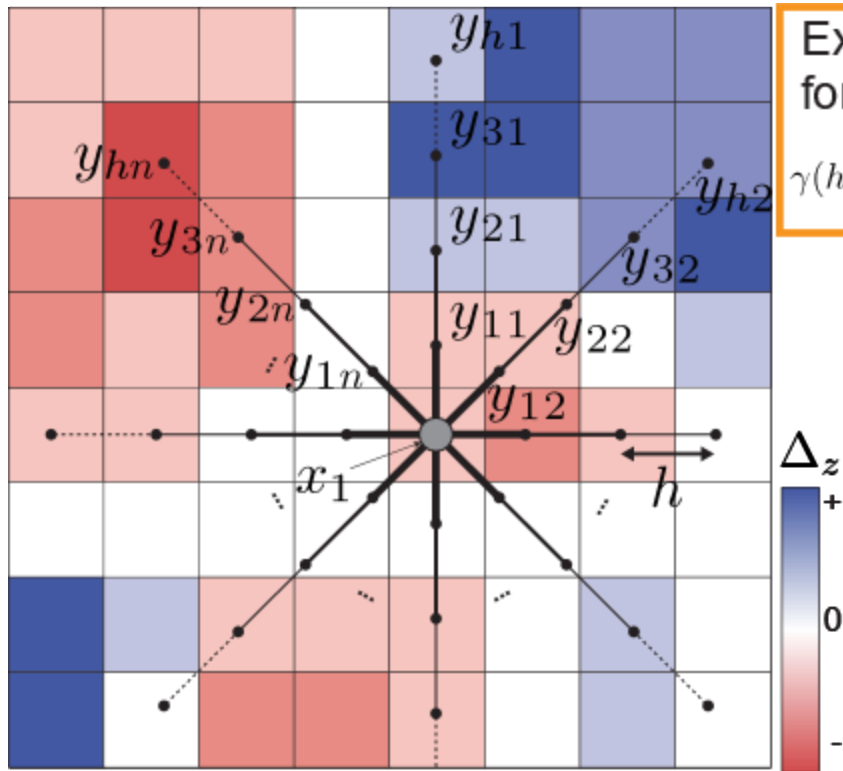
Experimental semivariance calculation for a given lag  $h$ , calculated in  $m$  directions for  $m$  samples :

$$\gamma(h) = \frac{[\Delta_z(x_1) - \Delta_z(y_{h1})]^2 + [\Delta_z(x_1) - \Delta_z(y_{h2})]^2 + \dots + [\Delta_z(x_2) - \Delta_z(y_{h1})]^2 + \dots + [\Delta_z(x_m) - \Delta_z(y_{hn})]^2}{2mn}$$



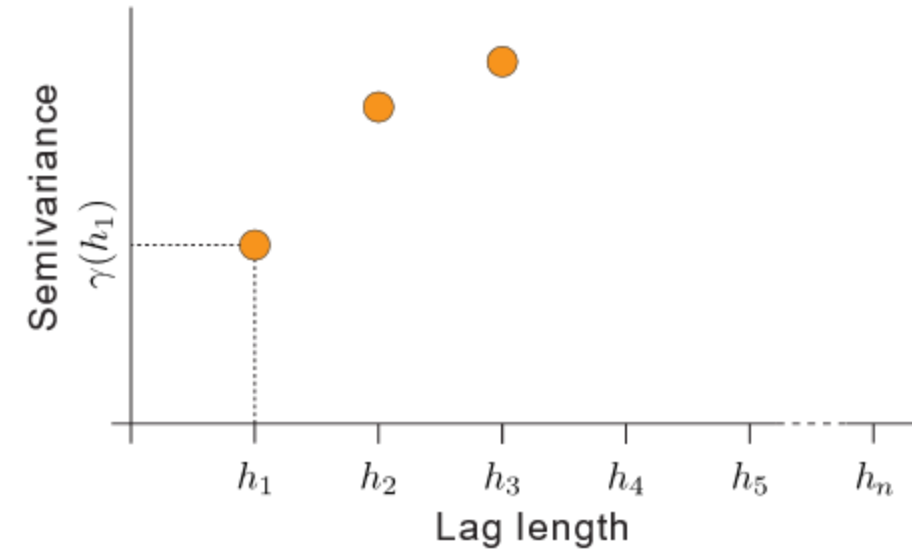


# Uncertainty in Vertical Differencing

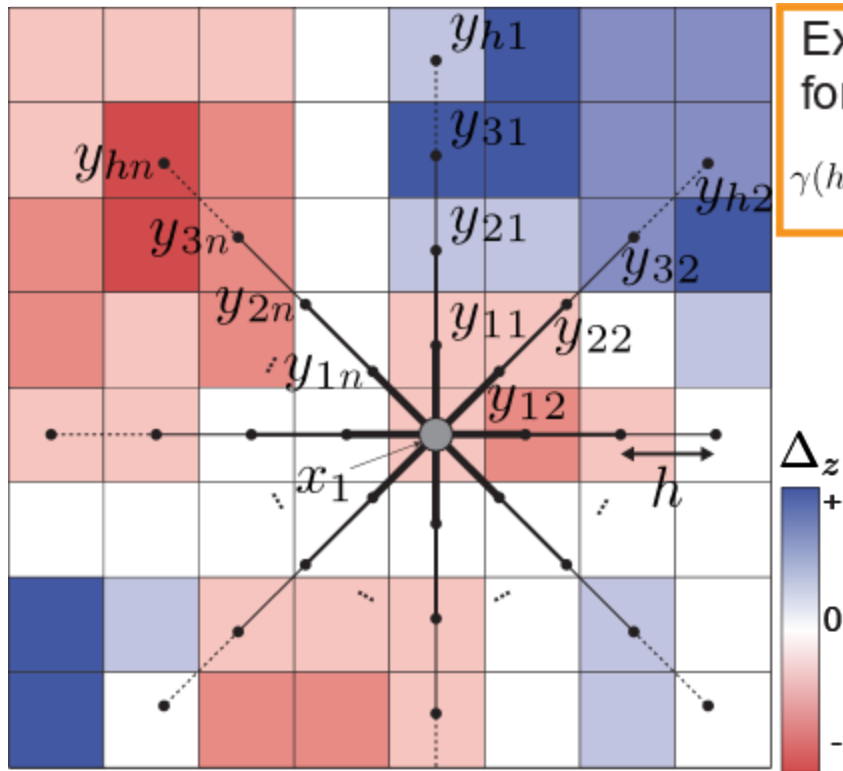


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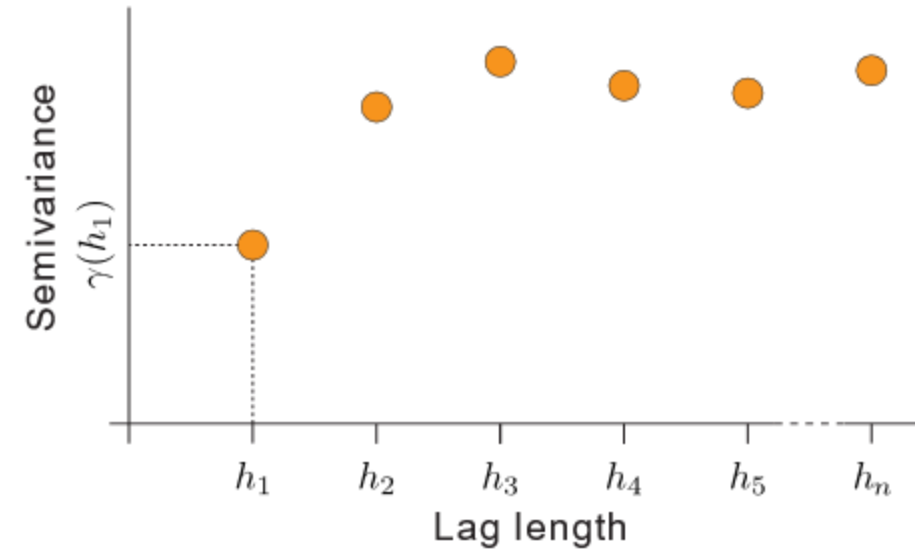


# Uncertainty in Vertical Differencing

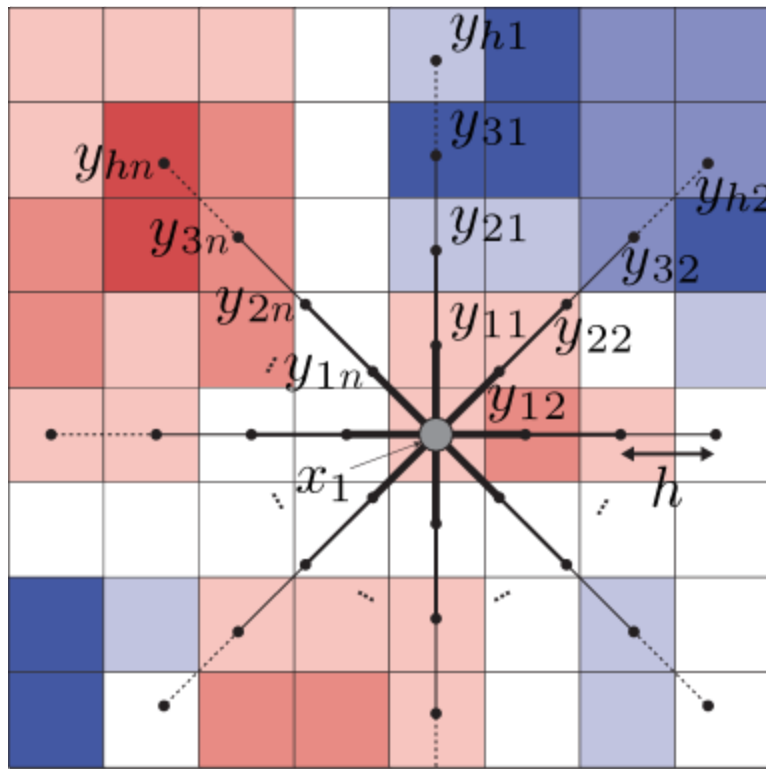


Experimental semivariance calculation for a given lag  $h$ , calculated in  $m$  directions for  $m$  samples :

$$\gamma(h) = \frac{[\Delta_z(x_1) - \Delta_z(y_{h1})]^2 + [\Delta_z(x_1) - \Delta_z(y_{h2})]^2 + \dots + [\Delta_z(x_2) - \Delta_z(y_{h1})]^2 + \dots + [\Delta_z(x_m) - \Delta_z(y_{hn})]^2}{2mn}$$



# Uncertainty in Vertical Differencing



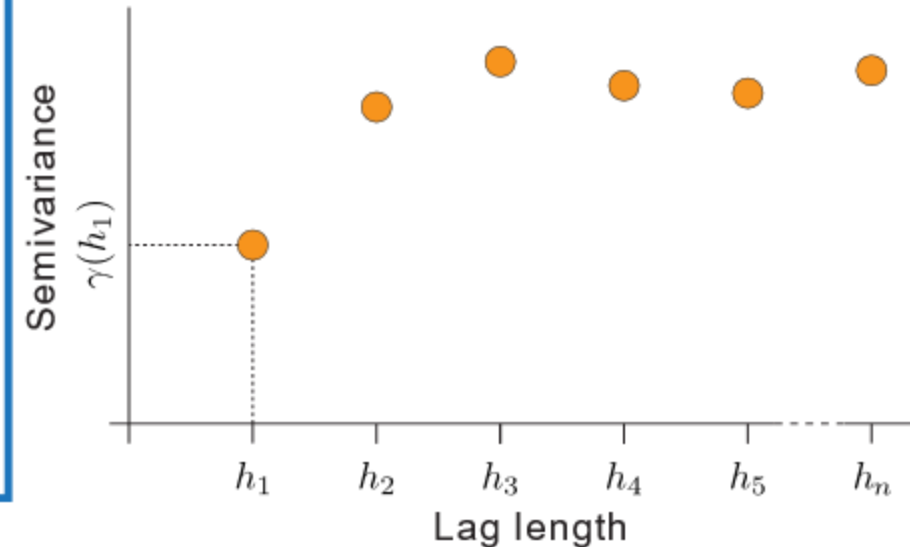
Experimental semivariance calculation for a given lag  $h$ , calculated in  $m$  directions for  $m$  samples :

$$\gamma(h) = \frac{[\Delta_z(x_1) - \Delta_z(y_{h1})]^2 + [\Delta_z(x_1) - \Delta_z(y_{h2})]^2 + \dots + [\Delta_z(x_2) - \Delta_z(y_{h1})]^2 + \dots + [\Delta_z(x_m) - \Delta_z(y_{hn})]^2}{2mn}$$

Semivariance modeled with spherical model of range  $a$  and sill  $c$  :

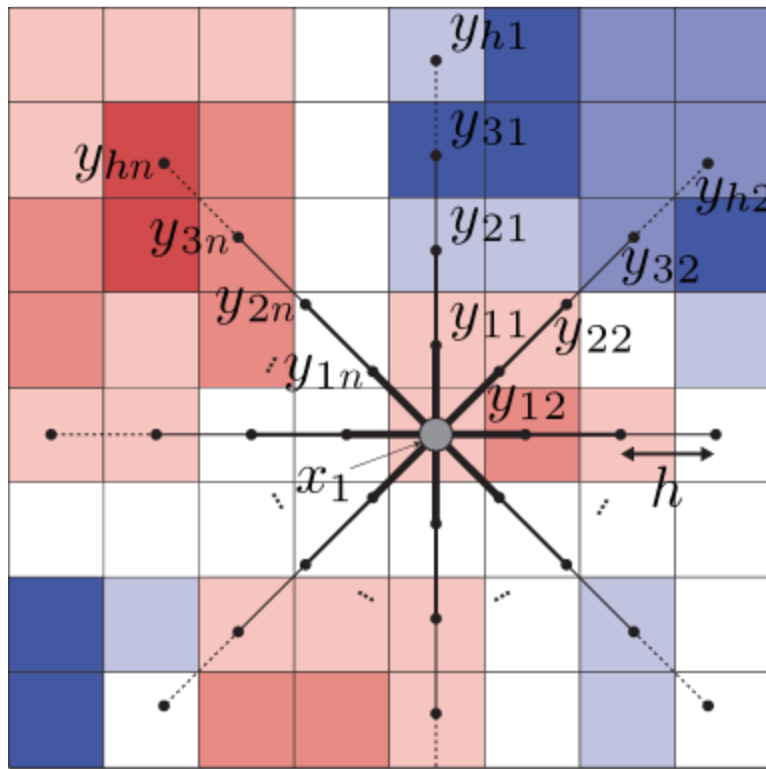
$$\gamma(h) = \begin{cases} 0, & h = 0 \\ c_0 + (c - c_0) \left[ \frac{3h}{2a} - \frac{1}{2} \left( \frac{h}{a} \right)^3 \right], & 0 < h \leq a \\ c, & h > a \end{cases}$$

$c_0$  represents the nugget effect, equal to 0 in this example.





# Uncertainty in Vertical Differencing



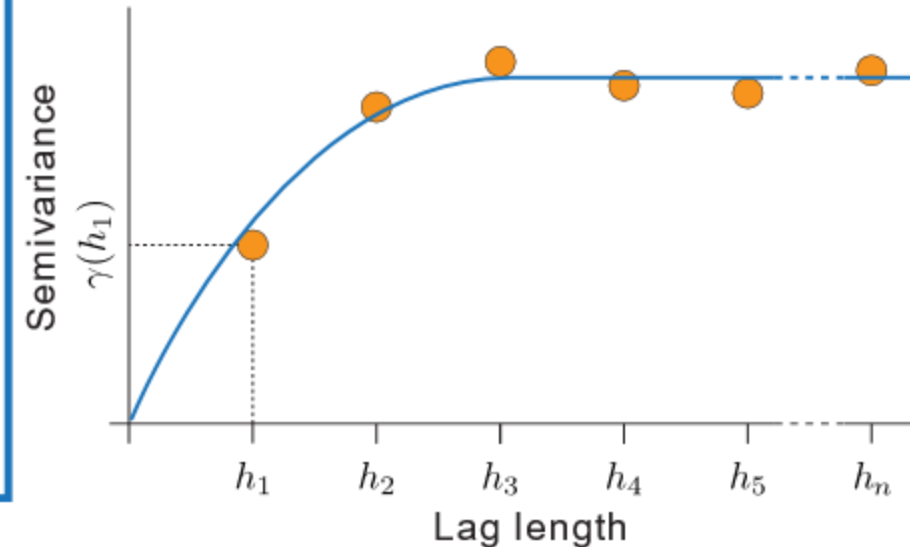
Experimental semivariance calculation for a given lag  $h$ , calculated in  $m$  directions for  $m$  samples :

$$\gamma(h) = \frac{[\Delta_z(x_1) - \Delta_z(y_{h1})]^2 + [\Delta_z(x_1) - \Delta_z(y_{h2})]^2 + \dots + [\Delta_z(x_2) - \Delta_z(y_{h1})]^2 + \dots + [\Delta_z(x_m) - \Delta_z(y_{hn})]^2}{2mn}$$

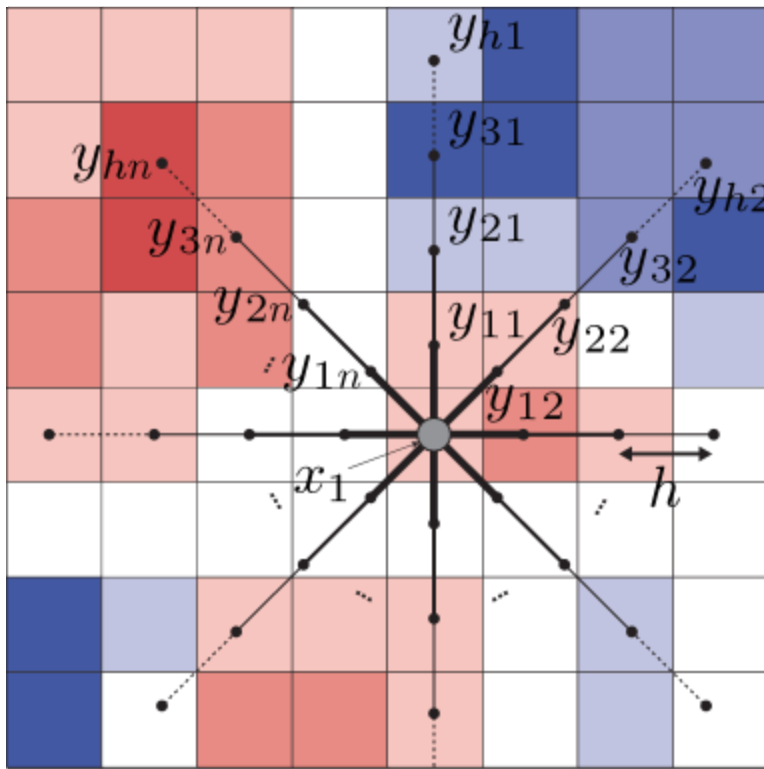
Semivariance modeled with spherical model of range  $a$  and sill  $c$  :

$$\gamma(h) = \begin{cases} 0, & h = 0 \\ c_0 + (c - c_0) \left[ \frac{3h}{2a} - \frac{1}{2} \left( \frac{h}{a} \right)^3 \right], & 0 < h \leq a \\ c, & h > a \end{cases}$$

$c_0$  represents the nugget effect, equal to 0 in this example.



# Uncertainty in Vertical Differencing



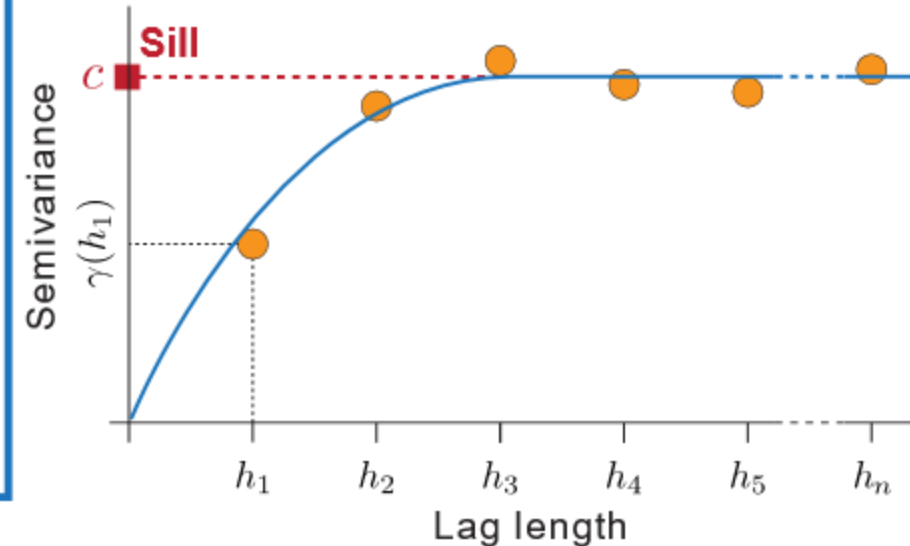
Experimental semivariance calculation for a given lag  $h$ , calculated in  $m$  directions for  $m$  samples :

$$\gamma(h) = \frac{[\Delta_z(x_1) - \Delta_z(y_{h1})]^2 + [\Delta_z(x_1) - \Delta_z(y_{h2})]^2 + \dots + [\Delta_z(x_2) - \Delta_z(y_{h1})]^2 + \dots + [\Delta_z(x_m) - \Delta_z(y_{hn})]^2}{2mn}$$

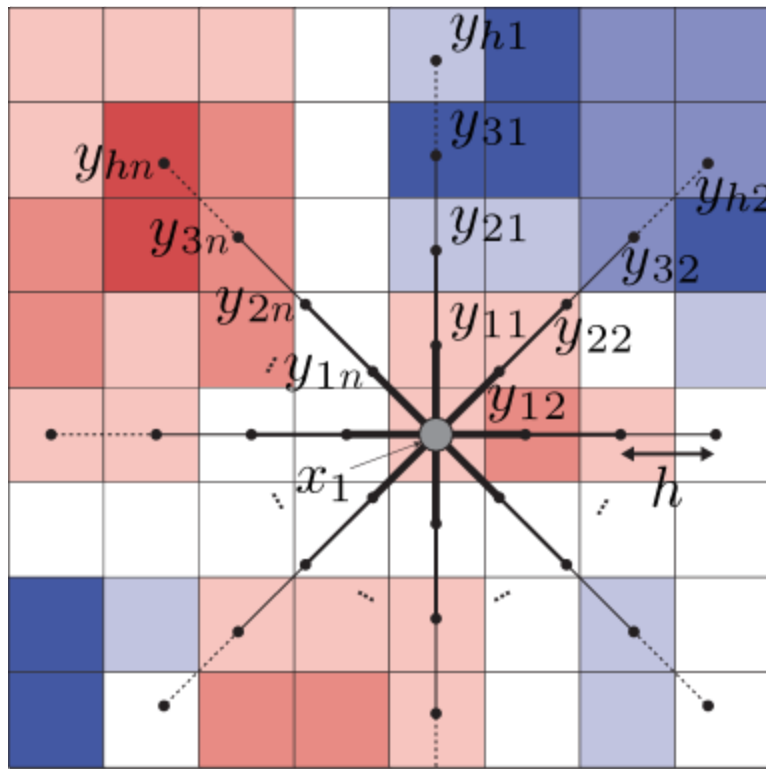
Semivariance modeled with spherical model of range  $a$  and sill  $c$  :

$$\gamma(h) = \begin{cases} 0, & h = 0 \\ c_0 + (c - c_0) \left[ \frac{3h}{2a} - \frac{1}{2} \left( \frac{h}{a} \right)^3 \right], & 0 < h \leq a \\ c, & h > a \end{cases}$$

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# Uncertainty in Vertical Differencing



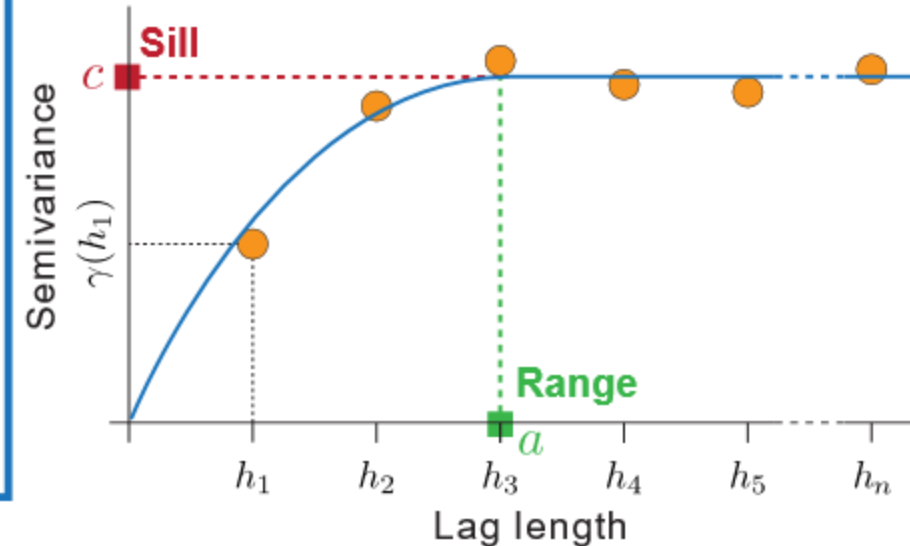
Experimental semivariance calculation for a given lag  $h$ , calculated in  $m$  directions for  $m$  samples :

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Semivariance modeled with spherical model of range  $a$  and sill  $c$  :

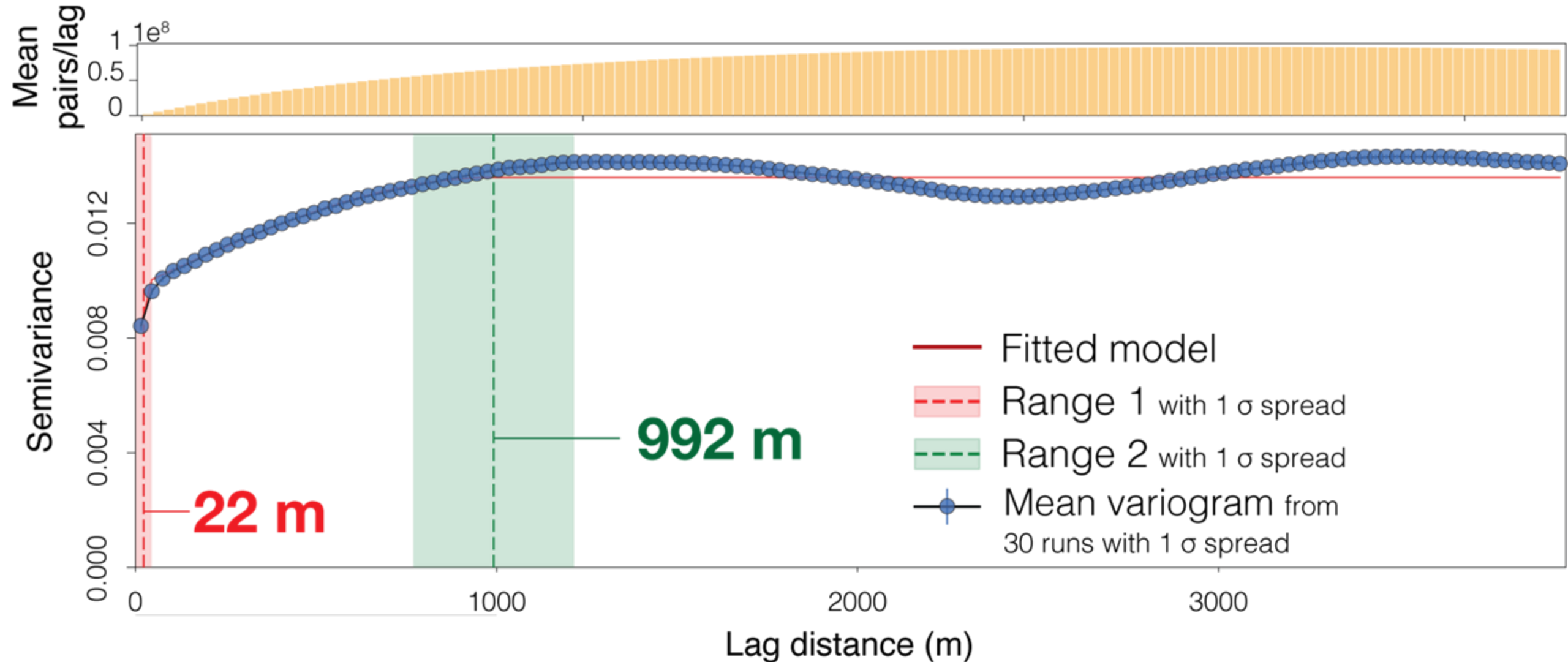
$$\gamma(h) = \begin{cases} 0, & h = 0 \\ c_0 + (c - c_0) \left[ \frac{3h}{2a} - \frac{1}{2} \left( \frac{h}{a} \right)^3 \right], & 0 < h \leq a \\ c, & h > a \end{cases}$$

$c_0$  represents the nugget effect, equal to 0 in this example.

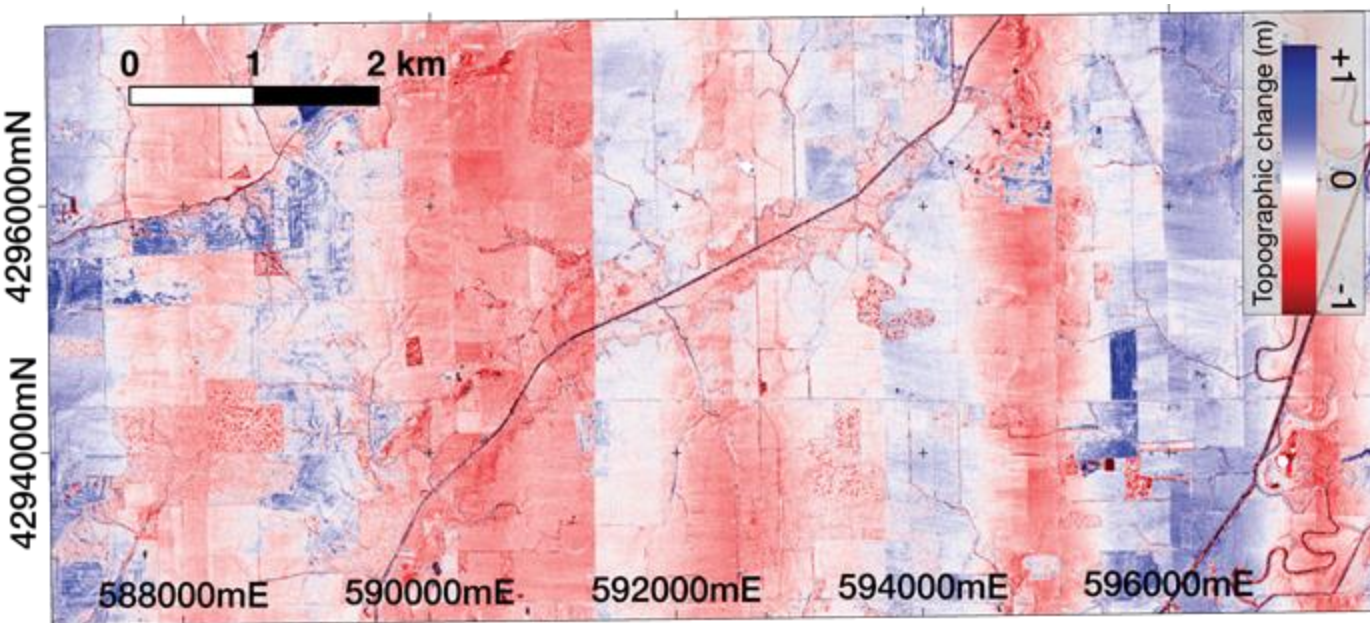




# Uncertainty in Vertical Differencing



# Uncertainty in Vertical Differencing



Area: 52.3 km<sup>2</sup>

Vertical bias: - 0.030 m

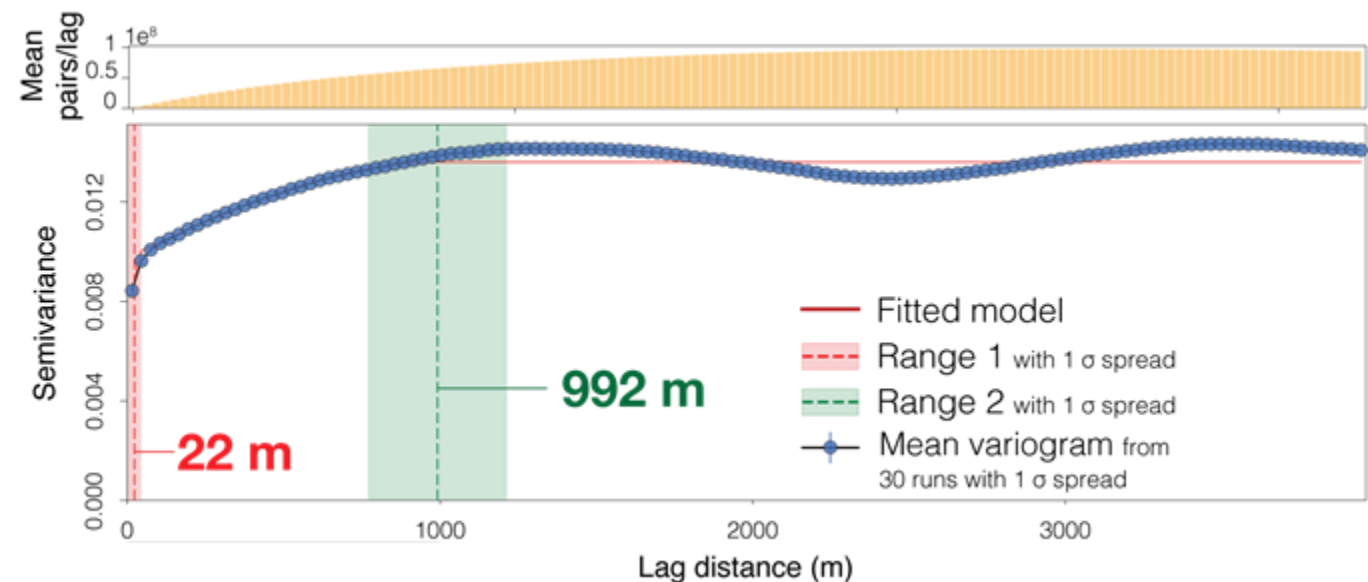
Propagated uncertainty:  
Random, uncorrelated:  
< 0.001 m

Random, correlated:

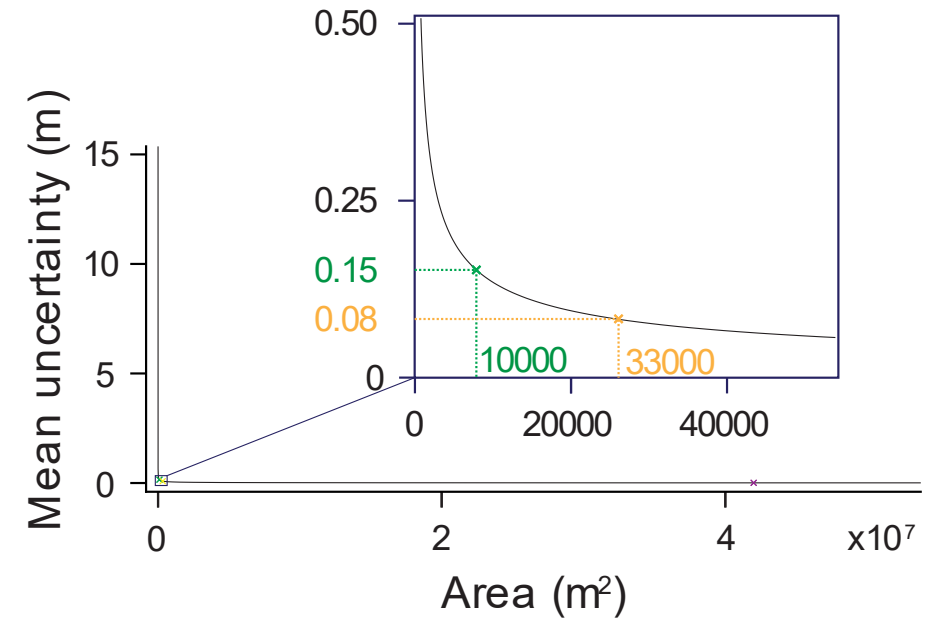
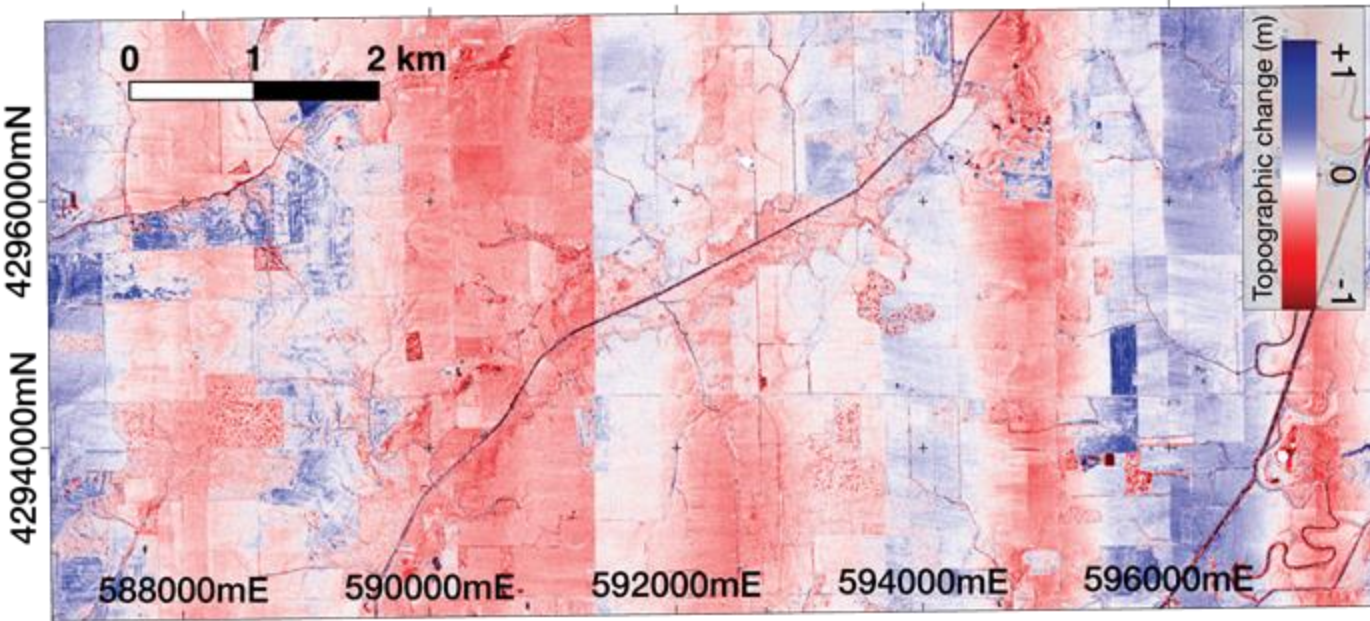
Range 1:  $\pm 0.001$  m

Range 2:  $\pm 0.009$  m

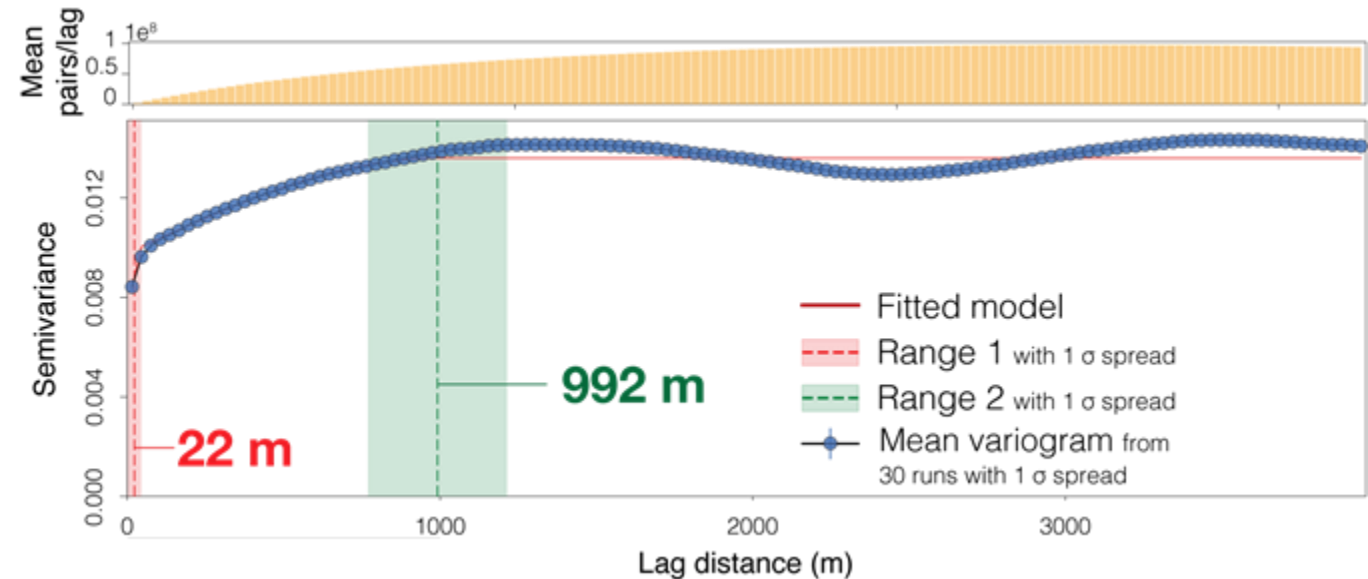
Total:  $\pm 0.009$  m



# Uncertainty in Vertical Differencing



Area: 52.3 km<sup>2</sup>  
 Vertical bias: - 0.030 m  
 Propagated uncertainty:  
 Random, uncorrelated:  
 < 0.001 m  
 Random, correlated:  
 Range 1:  $\pm 0.001$  m  
 Range 2:  $\pm 0.009$  m  
 Total:  $\pm 0.009$  m

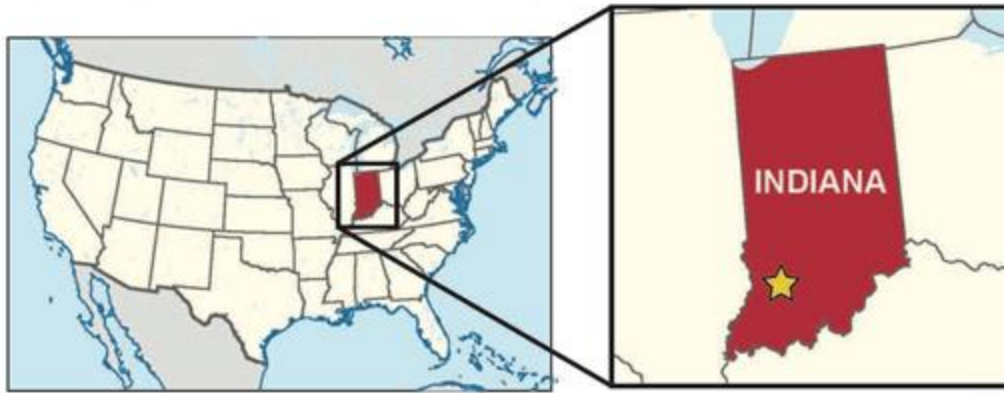




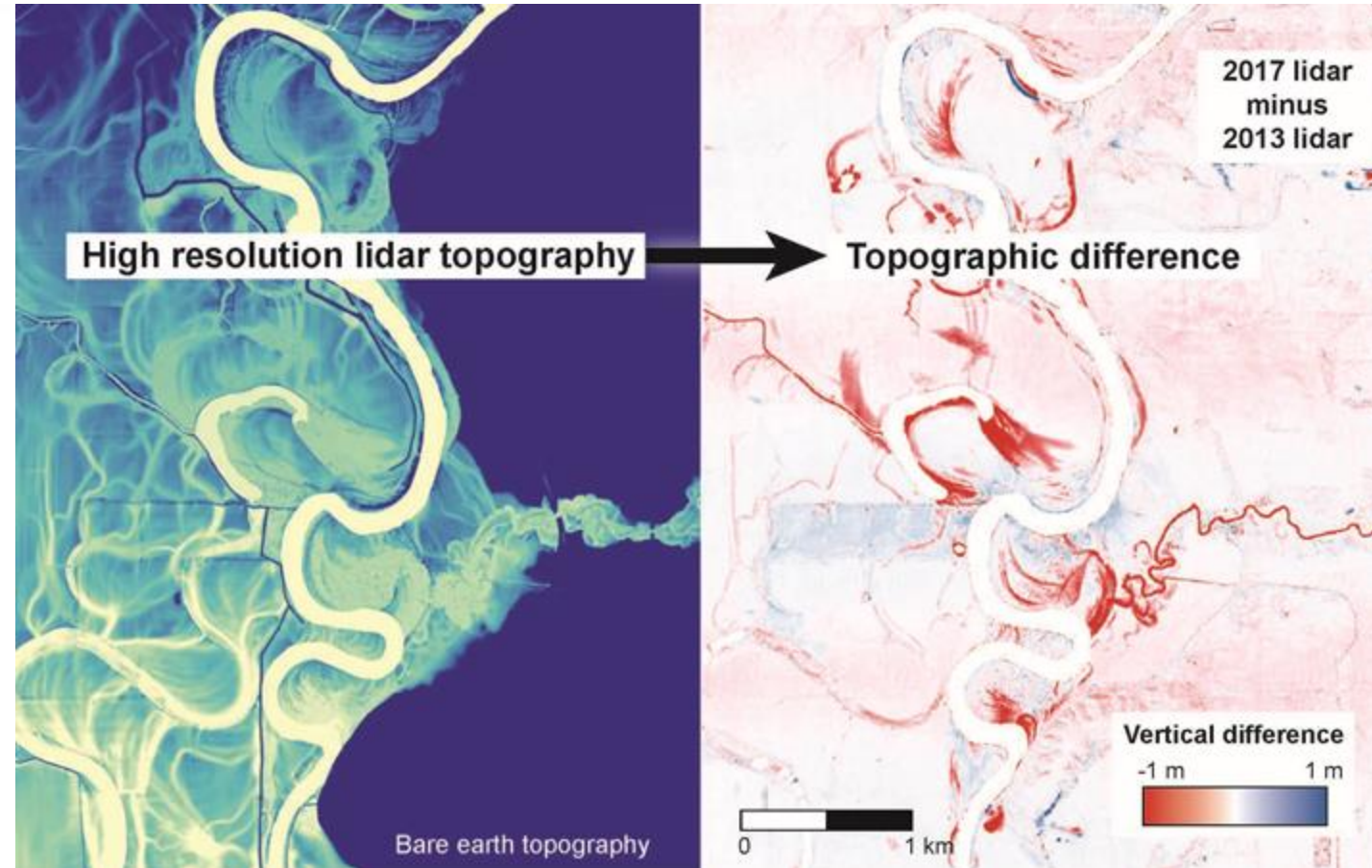
# Demo



# Statewide Topographic Differencing of Indiana



**Scott, C. P., Beckley, M., Phan, M., Zawacki, E., Crosby, C., Nandigam, V., & Arrowsmith, R. (2022). Statewide USGS 3DEP Lidar Topographic Differencing Applied to Indiana, USA. *Remote Sensing*, 14(4).**  
<https://doi.org/10.3390/rs14040847>



# Statewide Topographic Differencing of Indiana



## Motivation:

Large-scale topography processing  
What does a decade of change look  
like across a state?

## Why Indiana:

Two statewide datasets  
Anticipated interesting change  
Data-hosting partnership between  
OT and Indiana



Indiana Dunes National Park



# Statewide Topographic Differencing Challenges



**Big data:** Indiana is  $10^2$ - $10^3$  larger than the area of large past differencing studies

## Computation:

- Need high performance computing (HPC) resources
- Memory needs, especially for point cloud to raster/grid
- Final products are ~4 TB

**Noise:** Sources? Correct at the state-scale?

**Visualize the results?**

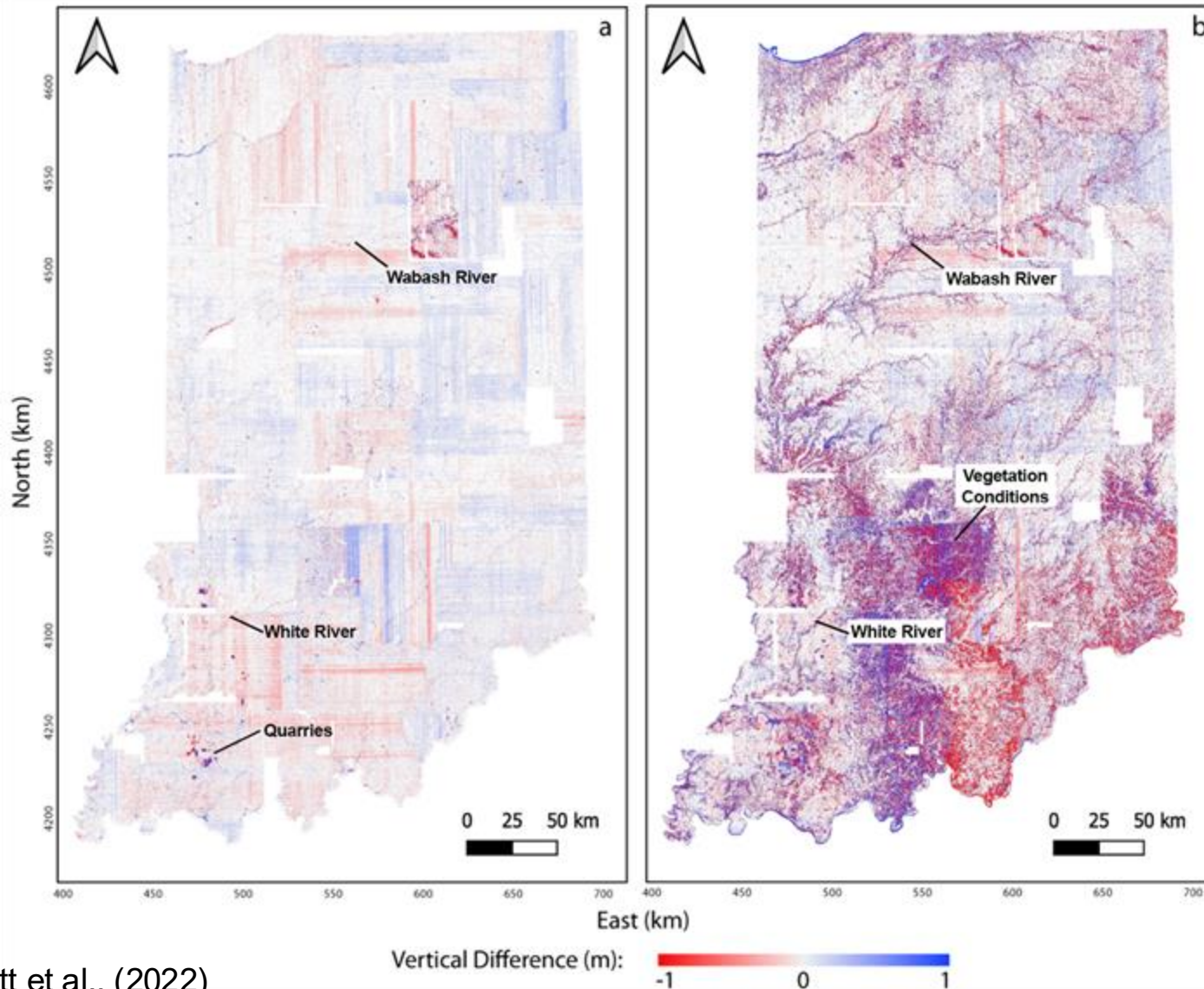


# Indiana Topographic Differencing



Digital Terrain Model

Digital Surface Model



Fluvial and riparian

Vegetation (correlations with season of data acquisition)

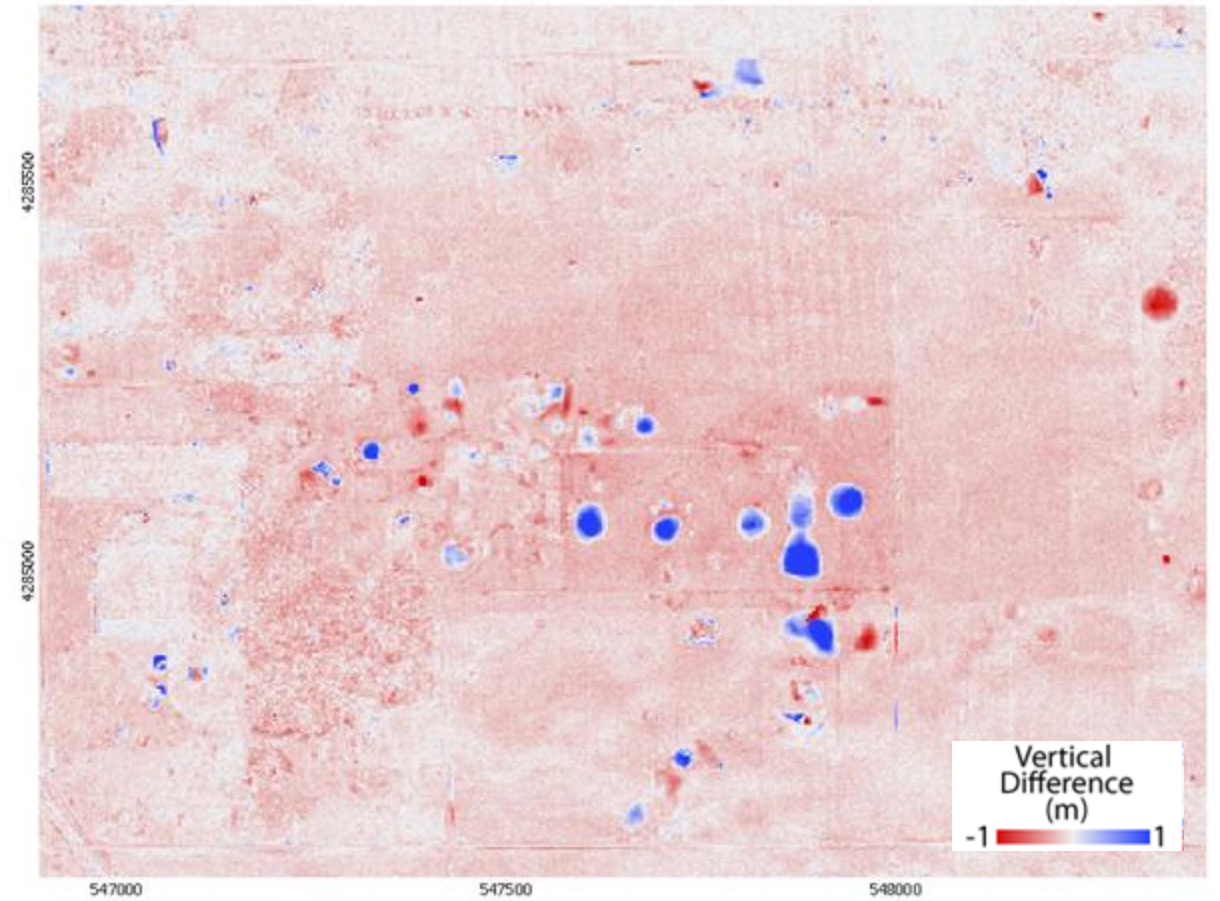
Quarries and mining

Flight alignment errors

**Browsable map:**  
[portal.opentopography.org/indiana](http://portal.opentopography.org/indiana)

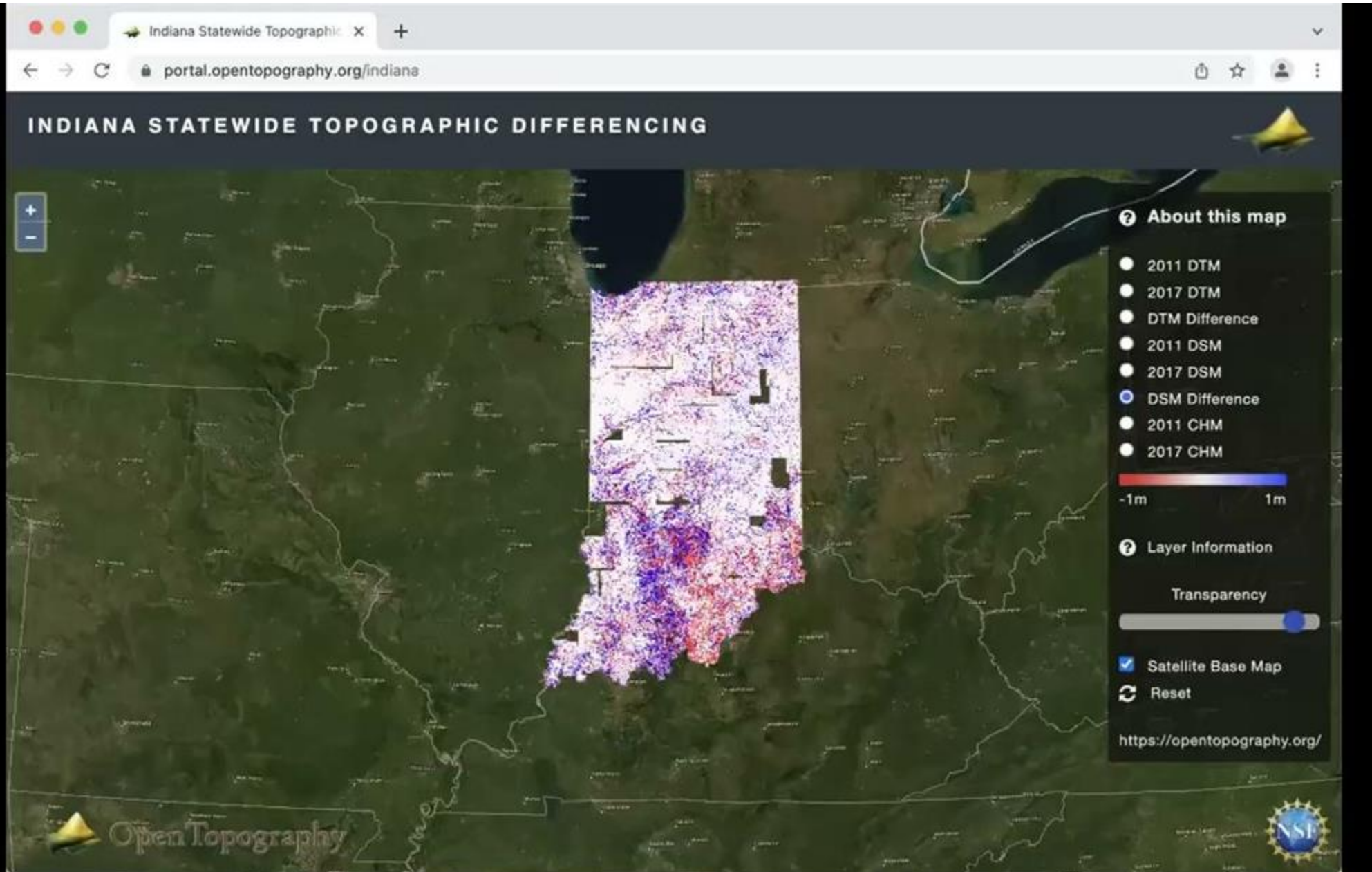


# Sinkholes



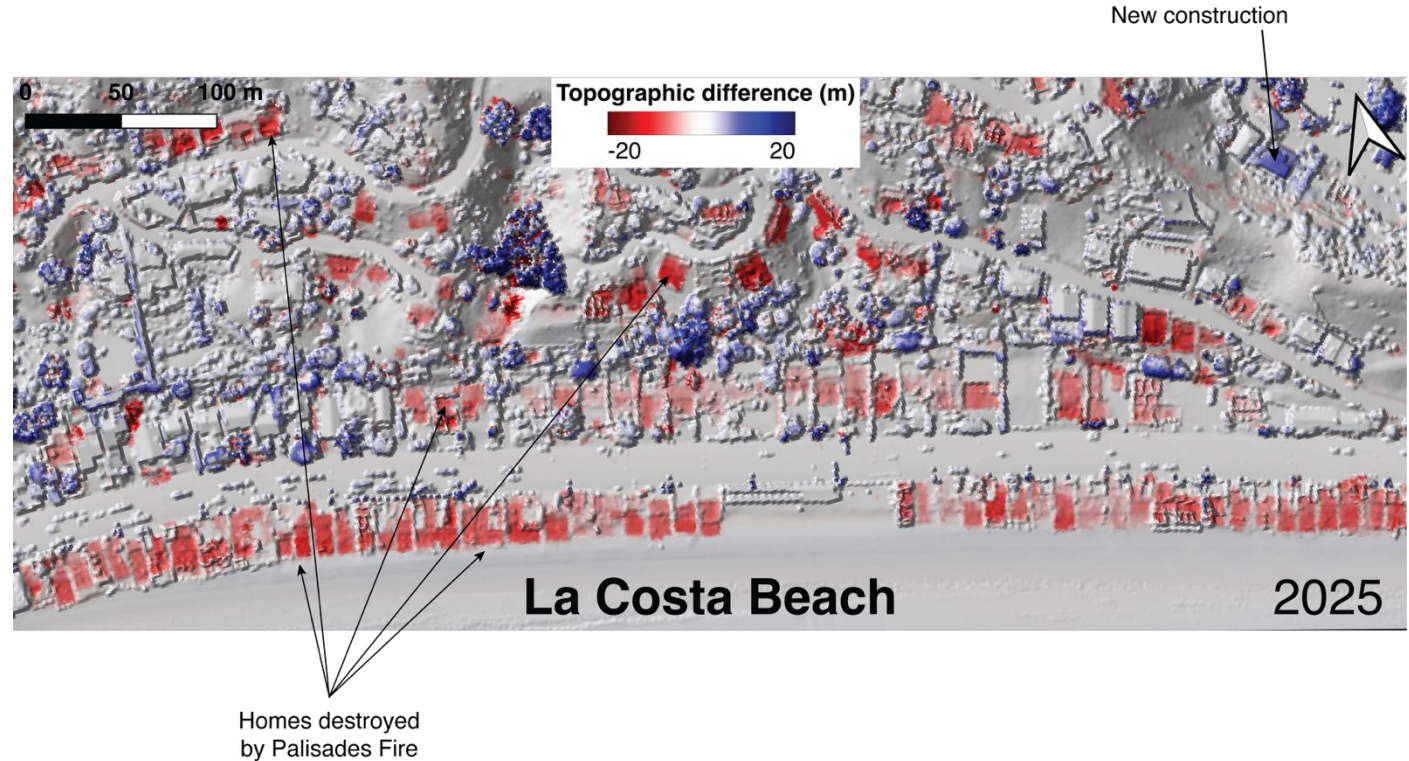


Visualize: <https://portal.opentopography.org/indiana>





# Differencing shows the impacts of the 2025 LA Fires



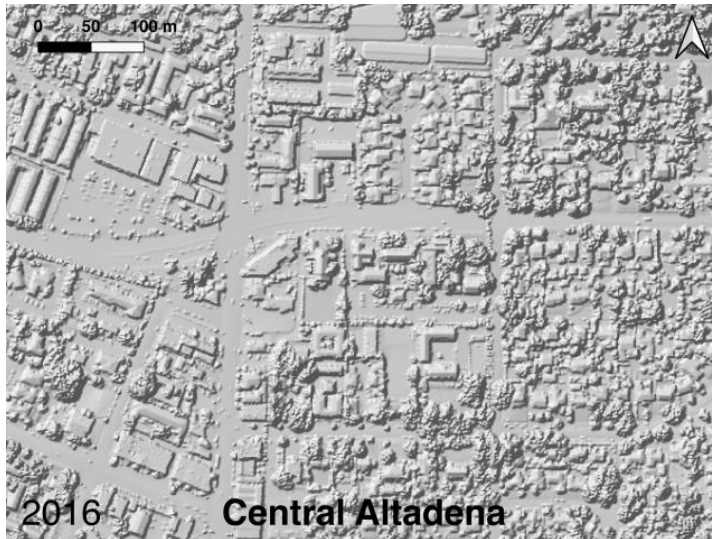
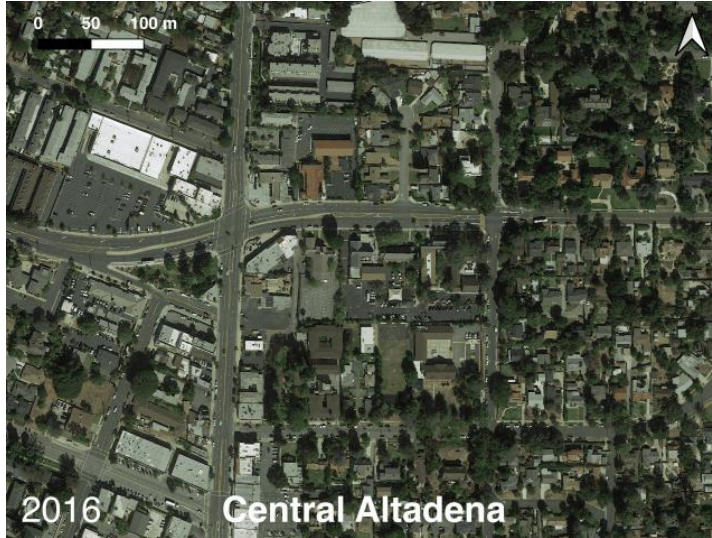
## Palisades Fire

**Blog post:** <https://opentopography.org/blog/using-lidar-understand-impacts-2025-palisades-and-eaton-fires-los-angeles-ca>

**Data portal:** <https://portal.opentopography.org/lafires>

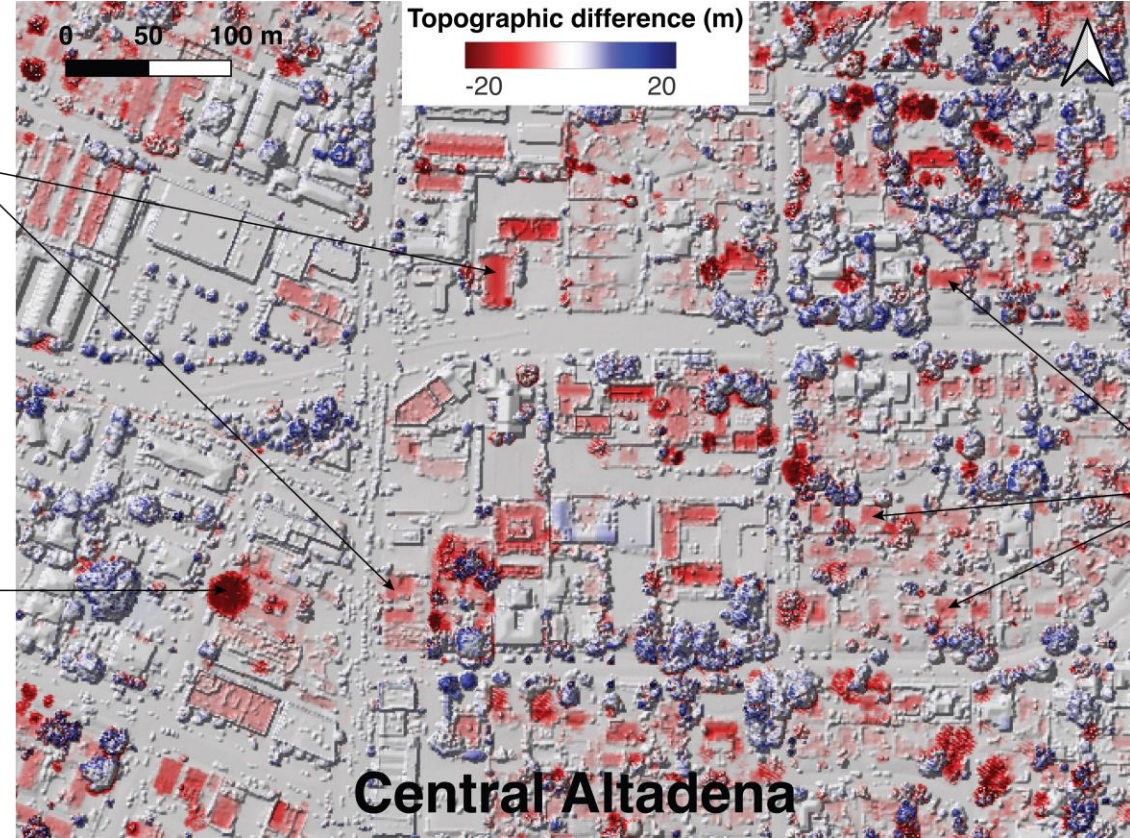


# Differencing shows the impacts of the 2025 LA Fires



Church and commercial buildings destroyed by Eaton Fire

Large tree removed



Homes destroyed by Eaton Fire

## Eaton Fire

<https://opentopography.org/blog/using-lidar-understand-impacts-2025-palisades-and-eaton-fires-los-angeles-ca>



# Resources: Self-paced Learning



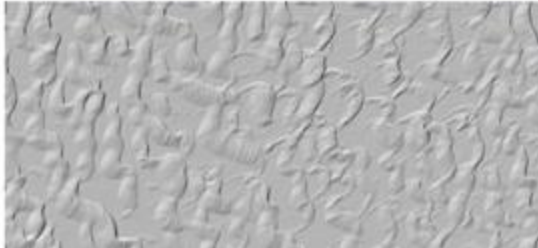
HOME DATA RESOURCES LEARN ABOUT

## Topographic Differencing

As part of OpenTopography's digital training resources, this page lists the material that we have developed about topographic differencing. The resources include several video tutorials, blog posts with examples of differencing results processed on OpenTopography, material presented at workshops, links to GitHub code repositories, and a differencing exercise designed for undergraduate courses.

Topographic differencing reveals surface change from a variety of tectonic, geomorphic, and anthropogenic processes including earthquakes, volcanic eruptions, river erosion, landslides, sand dune migration, and urban development. Differencing techniques have grown in popularity over the past decade as the number of multi-temporal topographic datasets has increased.

Vertical differencing is the subtraction of gridded elevation data (a.k.a. raster or digital elevation models [DEMs]) that span an event of interest. Early application of this method focused on rivers, although the technique has since been applied to a broader case set. 3D differencing is calculated with a windowed implementation of the Iterative Closest Point (ICP) algorithm. This approach works best when the landscape shifts laterally, for example in surface rupturing earthquakes.



<https://opentopography.org/learn/differencing>

Blog posts with differencing examples and error discussion

Video tutorials: Differencing on OT, 3D differencing on Matlab

Conference presentations

Github links to differencing code

Undergraduate differencing exercise

# Resources: Peer-reviewed Open Access Publications



Software Contribution

**GEOSPHERE**

GEOSPHERE, v. 12, no. 4  
<https://doi.org/10.1130/GES02259.1>  
13 figures, 2 tables  
CORRESPONDENCE: cpscott1@asu.edu

CITATION: Scott, C., Phan, M., Nandigam, V., Crosby, C., and Arrowsmith, J. R., 2022, Measuring change at Earth's surface: On-demand vertical and three-dimensional topographic differencing implemented in OpenTopography. *Geosphere*, v. 12, no. 4, p. 1518–1532. <https://doi.org/10.1130/GES02259.1>.

Science Editor: Andrea Hampel  
Associate Editor: Brian J. Ventres

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## Measuring change at Earth's surface: On-demand vertical and three-dimensional topographic differencing implemented in OpenTopography

Chelsea Scott<sup>1</sup>, Minh Phan<sup>2</sup>, Viswanath Nandigam<sup>2</sup>, Christopher Crosby<sup>1</sup>, and J Ramon Arrowsmith<sup>2</sup>

<sup>1</sup>School of Earth and Space Exploration, Arizona State University, Tempe, Arizona 85287, USA  
<sup>2</sup>San Diego Supercomputer Center, University of California San Diego, La Jolla, California 92093, USA  
<sup>3</sup>UNAVCO, Boulder, Colorado 80501, USA

**ABSTRACT**

Topographic differencing measures landscape change by comparing multitemporal high-resolution topography data sets. Here, we focused on two types of topographic differencing: (1) Vertical differencing is the subtraction of digital elevation models (DEMs) that span an event of interest. (2) Three-dimensional (3-D) differencing measures surface change by registering point clouds with a rigid deformation. We recently released topographic differencing in OpenTopography where users perform on-demand vertical and 3-D differencing via an online interface. OpenTopography is a U.S. National Science Foundation-funded facility that provides access to topographic data and processing tools. While topographic differencing has been applied in numerous research studies, the lack of standardization, particularly of 3-D differencing, requires the customization of processing for individual data sets and hinders the community's ability to efficiently perform differencing on the growing archive of topography data. Our paper focuses on streamlined techniques with which to efficiently difference data sets with varying spatial resolution and sensor type (i.e., optical vs. light detection and ranging [lidar]) and over variable landscapes. To optimize on-demand differencing, we considered algorithm choice and displacement resolution. The optimal resolution is controlled by point density, landscape characteristics (e.g., leaf-on vs. leaf-off), and data set quality. We provide processing options derived from metadata that allow users to produce optimal high-quality results, while experienced users can fine tune the parameters to suit their needs. We anticipate that the differencing tool will expand access to this state-of-the-art technology, will be a valuable educational tool, and will serve as a template for differencing the growing number of multitemporal topography data sets.

**INTRODUCTION**

Topographic differencing measures landscape change from urban growth, flooding (Wheaton et al., 2009; Izumida et al., 2017), coastal processes (Brock et al., 2001; Bull et al., 2010), earthquakes and creeping faults (Oslen et al., 2012; Nissen et al., 2012, 2014; Clark et al., 2017; Scott et al., 2018a; Wedmore et al., 2019; Barnhart et al., 2019; Scott et al., 2020), volcanic eruptions (Albino et al., 2015), and landslides (Lucier et al., 2014), among other events. Interest in this technique is growing as more regions are surveyed with multitemporal topography data. Vertical differencing is the subtraction of raster-based digital elevation models (DEMs) and can be performed on original raster topography or grids generated from point cloud data, as shown in Figure 1. Three-dimensional (3-D) differencing resolves the best rigid deformation during an event of interest and is performed with a windowed implementation of the iterative closest point (ICP) algorithm (Besl and McKay, 1992; Chen and Medioni, 1992), as illustrated in Figure 2. The 3-D differencing method, in particular, often requires an expert to dedicate substantial effort to customize processing, and there is little standard methodology or documentation available. As multitemporal topography coverage increases, more data types with variable characteristics are differenced, and results are used to respond to natural disasters and study phenomena altering Earth's surface. In this paper, we describe our implementation of on-demand vertical and 3-D differencing on topography data available via OpenTopography ([opentopography.org](http://opentopography.org)). A major challenge in 3-D differencing is to select the appropriate differencing algorithm and the resolution of derived displacements, which depend on data resolution, noise, and landscape characteristics. We compared several differencing algorithms and incorporated metadata (e.g., point density) into the default processing settings. Our workflow quickly produces quality differencing results and offers default options that can be further tailored for individual data sets by more advanced users. Deployment of these tools in OpenTopography expands access to state-of-the-art technology for scientists, geospatial professionals, and students. Additionally, our tools can become a reference that contributes to the standardization of topographic differencing, which is lacking in the geosciences.

OpenTopography is a U.S. National Science Foundation-funded facility that enables discovery and access of high-resolution topography data sets and provides on-demand processing tools. OpenTopography is built on a scalable-system-oriented architecture that supports a range of downstream processing tools that derive common science products from hosted raw data (Krishnan et al., 2011). As of October 2020, the 341 point cloud data sets hosted by OpenTopography cover more than



remote sensing



Article

## Statewide USGS 3DEP Lidar Topographic Differencing Applied to Indiana, USA

Chelsea Phipps Scott<sup>1,\*</sup>, Matthew Beckley<sup>2</sup>, Minh Phan<sup>3</sup>, Emily Zawacki<sup>1</sup>, Christopher Crosby<sup>2</sup>, Viswanath Nandigam<sup>3</sup> and Ramon Arrowsmith<sup>1</sup>

- <sup>1</sup> School of Earth and Space Exploration, Arizona State University, Tempe, AZ 85287, USA; emilyzawacki@asu.edu (E.Z.); ramon.arrowsmith@asu.edu (R.A.)
  - <sup>2</sup> UNAVCO, Boulder, CO 80301, USA; beckley@unavco.org (M.B.); crosby@unavco.org (C.C.)
  - <sup>3</sup> San Diego Supercomputer Center, University of California San Diego, La Jolla, CA 92093, USA; mnphan@ucsd.edu (M.P.); vnandigam@ucsd.edu (V.N.)
- \* Correspondence: cpscott1@asu.edu

**Abstract:** Differencing multi-temporal topographic data (radar, lidar, or photogrammetrically derived point clouds or digital elevation models—DEMs) measures landscape change, with broad applications for scientific research, hazard management, industry, and urban planning. The United States Geological Survey's 3D Elevation Program (3DEP) is an ambitious effort to collect light detection and ranging (lidar) topography over the United States' lower 48 and Interferometric Synthetic Aperture Radar (InSAR) in Alaska by 2023. The datasets collected through this program present an important opportunity to characterize topography and topographic change at regional and national scales. We present Indiana statewide topographic differencing results produced from the 2011–2013 and 2016–2020 lidar collections. We discuss the insights, challenges, and lessons learned from conducting large-scale differencing. Challenges include: (1) designing and implementing an automated differencing workflow over 94,000 km<sup>2</sup> of high-resolution topography data, (2) ensuring sufficient computing resources, and (3) managing the analysis and visualization of the multiple terabytes of data. We highlight observations including infrastructure development, vegetation growth, and landscape change driven by agricultural practices, fluvial processes, and natural resource extraction. With 3DEP and the U.S. Interagency Elevation Inventory data, at least 37% of the Contiguous 48 U.S. states are already covered by repeat, openly available, high-resolution topography datasets, making topographic differencing possible.

**Keywords:** lidar; topographic change; USGS 3DEP; Indiana; vertical differencing



Citation: Scott, C.P.; Beckley, M.; Phan, M.; Zawacki, E.; Crosby, C.; Nandigam, V.; Arrowsmith, R. Statewide USGS 3DEP Lidar Topographic Differencing Applied to Indiana, USA. *Remote Sens.* 2022, 14, 847. <https://doi.org/10.3390/rs14040847>

Academic Editor: Luke Wallace





White River, IN



# OpenTopography



## Thank you!

[www.opentopography.org](http://www.opentopography.org)

*Contact:* [info@opentopography.org](mailto:info@opentopography.org)

*Socials:* [@OpenTopography](https://www.instagram.com/opentopography)

**SDSC**



**EarthScope**  
Consortium

